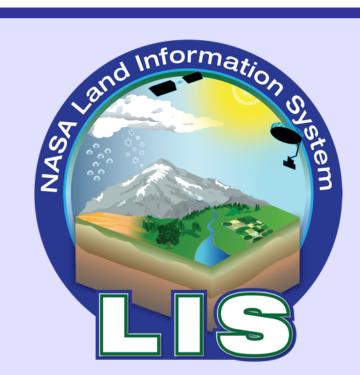


Assessment of Soil Moisture Initialization Approaches for NU-WRF Forecasts



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Background

 Land-atmosphere (L-A) prediction is governed by a series of processes and feedbacks, which we call Local L-A Coupling ('LoCo'), as follows:

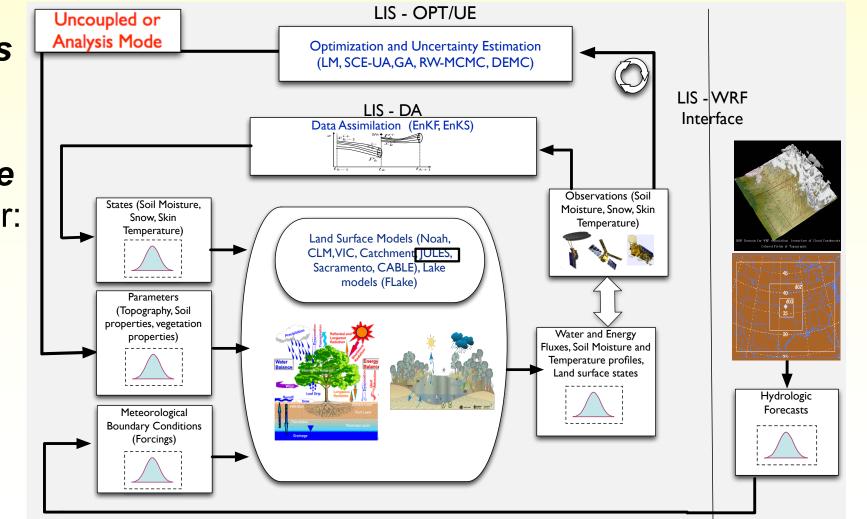
 $\Delta SM \rightarrow \Delta EF \rightarrow \Delta PBL \rightarrow \Delta ENT \rightarrow \Delta T_{2m}, Q_{2m} \triangleright \Delta Precip/Clouds$

- Impacts of soil moisture initial conditions are therefore felt downstream during WRF forecasts.
- Little attention has been paid to the variability in soil moisture initialization approaches, including what is now possible from satellites such as SMAP.
- Objective: Perform a practical assessment of the impact of soil moisture initial conditions on initialization of short-term weather forecasts.
- Case Study: July 11th and Aug 28th, 2015
- Domain: 1100x750 @ 1km over U.S. SGP
- **Observations:** SMAP Soil Moisture
- Models: LIS-Noah (v3.3) LSM + NU-WRF

NASA's Land Information System (LIS)

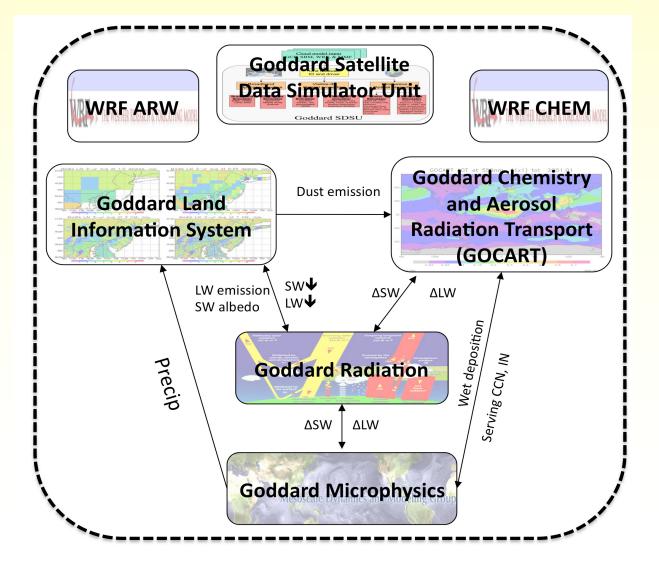
 Provides a suite of LSMs under a consistent, high-performance computing and software **framework** that allows for:

- Land DA, Calibration
- Flexible Forcing, Parameters, Physics, Ensembles
- Coupling to WRF



NASA Unified WRF (NU-WRF)

- Provides an observation-driven, integrated modeling system that represents aerosol, cloud, precipitation and land processes at satellite-resolved scales (1-4 km)
- Integrate unique NASA observation and modeling assets under one roof:
- Satellite Data
- Model Physics
- Expertise/Software



LIS Runs and Experimental Design

A suite of LIS simulations was performed to isolate impacts of:

Atmospheric Forcing

-NLDAS-2: best available, observed precipitation, 0.125-deg

-GDAS: coarse, global, 0.3-deg Green Vegetation Fraction

-Climatological: Monthly, satellite-based @ 3km -Real-time: Daily, VIIRS-based @ 3km

Part Space Part Space Par

-Model space: on the 1km grid of the LSM (*traditional approach) -Observation space: on the 36km grid of the SMAP L3-Passive data

Initialization Source	Forcing	DA-Space	GVF	
LIS (Control)	NLDAS-2	No DA	VIIRS	
LIS (GDAS)	GDAS	No DA	VIIRS	Suite of
LIS (GVF)	NLDAS-2	No DA	Climatology	
NLDAS	NLDAS-2	No DA	Climatology	Initial
WRF	NARR	No DA	Climatology	
SMAP	-	-	ı	Conditions
LIS-DA	NLDAS-2	Model (1 km)	VIIRS	
LIS-DA	NLDAS-2	Observation (36 km)	VIIRS	

LIS includes a multi-algorithm assimilation subsystem (LIS-DA) ranging from techniques such as:

- Direct Insertion (DI) Ensemble Kalman Filter (EnKF)
- LIS-DA can perform **product** or **radiance** (LIS-RTM) based assimilation for land surface states:
 - Soil Moisture
 - Surface Temperature
 - Snow (SWE, snow cover)
- - Groundwater

Spinup & Data Assimilation Runs

DA Algorithm:

- LIS Ensemble KF (size X)
- Perturbations to forcing and prognostic

Observations:

- SMAP L3 Passive Soil Moisture (EASE
- grid) • 9 km spatial, 2-3 day temporal revisit

Simulations:

- Full spinup: 1 May 2011 1 April 2017
- DA performed: 1 April 2015- 1 April 2017

Results

Variability in Soil Moisture Initial Conditions

• The soil moisture fields on July 11th and Aug 28th as generated from the various model and observation sources (Figs. 1, 2) vary as a result of the following:

LIS-Noah Specifications

- Precipitation: GDAS has generally less precipitation than NLDAS-2 producing drier soil moisture.
- Precipitation: NLDAS-2 has local maxima that GDAS misses entirely (implications for DA).
- GVF: Climatology and VIIRS are similar leading to only subtle soil moisture differences.

Data Assimilation (in progress..)

 LIS-DA runs assimilating will be sensitive to the DA being performed at model (1km) vs. SMAP (9 or 36km) resolution.

• NLDAS-2

 NLDAS-Noah (v2.8) tends to be wetter than the Noah (v3.x) simulations above.

• NARR

situ data (Fig. 3).

 NARR w/Noah LSM (v2.7.1) is coarser spatially but similar to NLDAS-2 in terms of soil moisture magnitude and pattern.

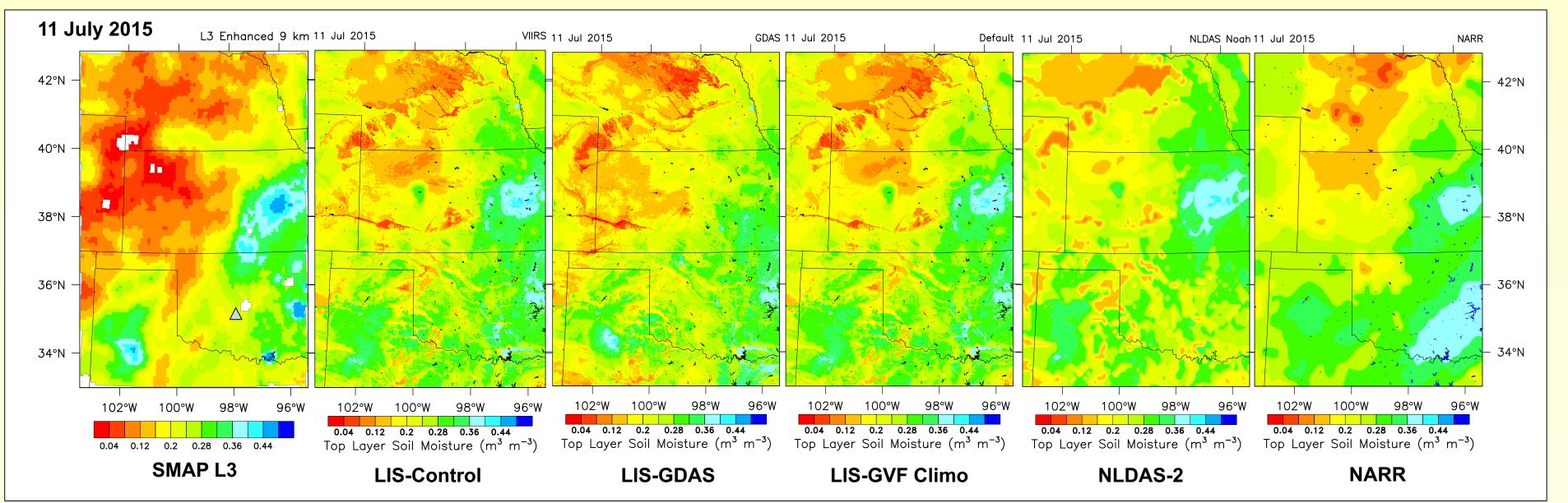
SMAP Performance

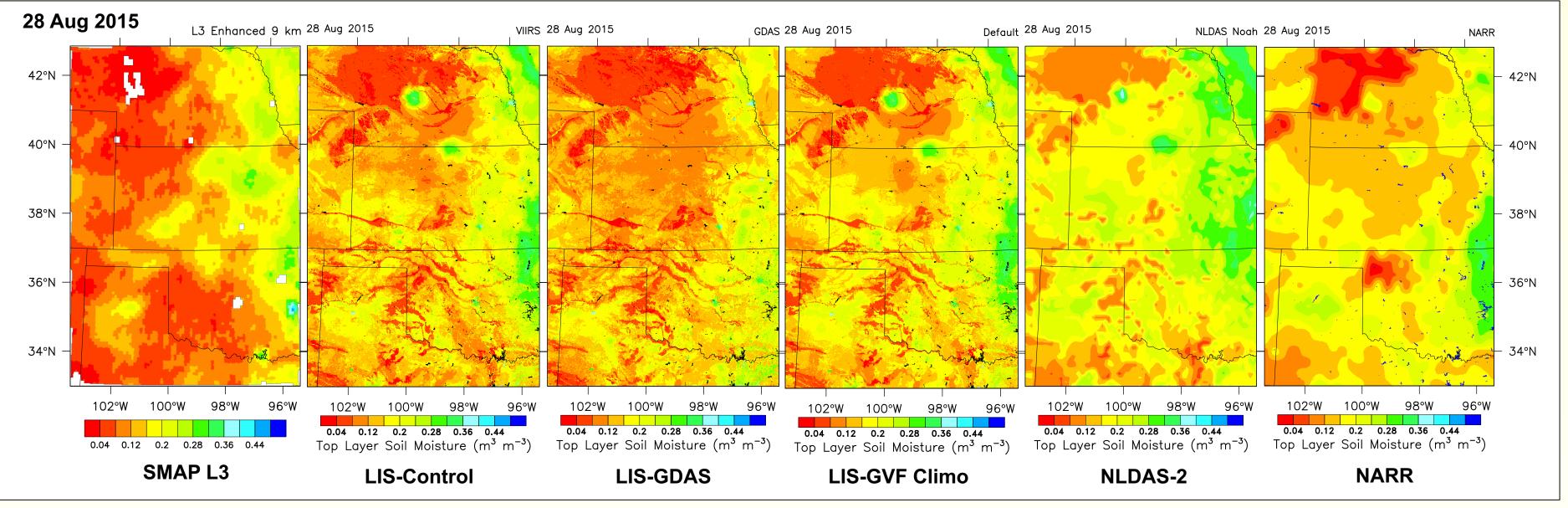
- Overall, SMAP performs quite well and looks like 'real' soil moisture both in time and space.
- Return time over a given location over the SGP is on the order of every ~2 days using the morning (6am) overpass (more frequent if evening is included).
- SMAP captures the overall heterogeneity and gradients (E-W) of soil moisture in the region well when compared with the other model-based products (Figs. 1, 2).
- SMAP tends to be drier especially over the western (dry/bare soil) regions than the model-based conditions (Figs. 1-3).
- and magnitude (Figs. 1,2,4). Drydowns occur more rapidly in SMAP data than in model/in-

Wetting (precip) events are captured very well, both in time

- Dry bias in SMAP particularly during dry regimes is likely a result
- of actual SMAP retrieval depth being less than 5cm (i.e. 1-3cm), as well as vegetation and emissivity impacts.

Soil Moisture Initialization Intercomparison





Figures 1 & 2. Near-surface soil moisture on July 11 and August 28, 2015 at 12Z (morning) from a) the SMAP L3, 9km soil moisture product, and the array of LIS 5-year spinups using the Noah v3.6 LSM including the b) Control Run (NLDAS-2 forcing and VIIRS GVF), c) GDAS forcing, d) GVF Climatology, along with that from the e) operational NLDAS-2 product using the Noah v.2.7.1 LSM and f) NARR Reanalysis using the Noah v.2.7.1 LSM.

Spatial Distribution of Soil Moisture

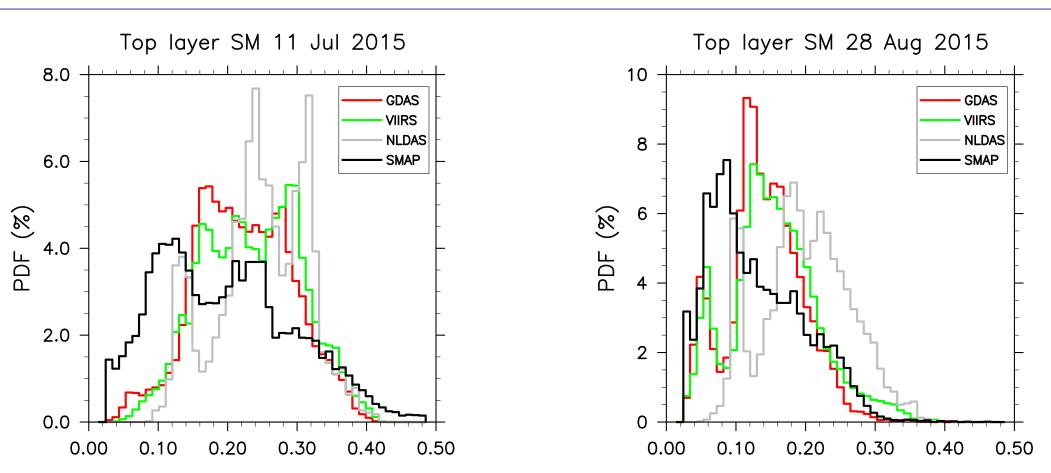


Figure 3. Spatial PDFs of the near-surface soil moisture plotted in Figs. 1 & 2 for the SMAP, LIS-Control, LIS-GDAS, and NLDAS-2 simulations on 11 July and 28 August 2015.

- The spatial distribution of near-surface soil moisture on 11 July tends to be bimodal due to a consistent antecedent precipitation gradient (NW-SE) over the region.
- The magnitude of the peaks depends on the precipitation forcing (GDAS – drier vs. NLDAS –

SMAP is consistently drier than the models

below 0.25 m3/m3, but comparable above 0.30.

- → The spatial distribution on 28 August tends to be more normal with much drier peaks (~0.10) due to more uniform drying over the region by late-August.
- The operational NLDAS product is significantly wetter than the other model or observation products.

Evaluation at Little Washita

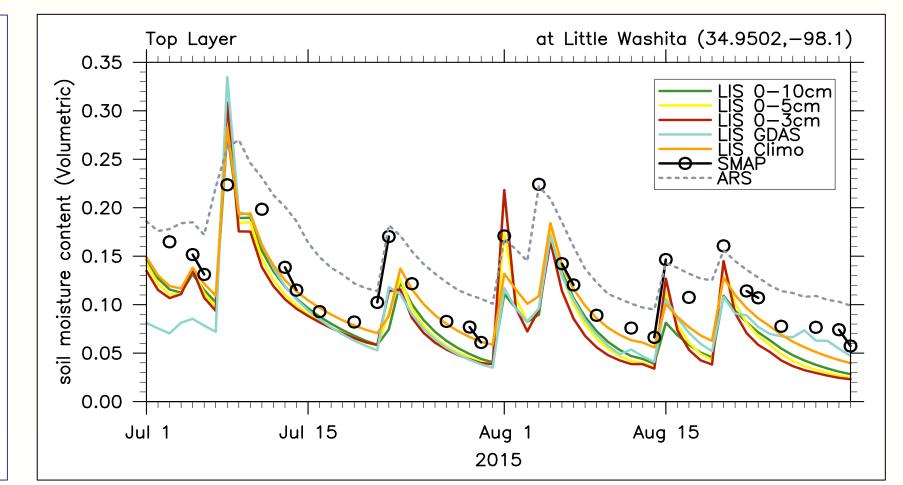


Figure 4. Time series of near-surface soil moisture at the Little Washita, OK site taken from SMAF and in-situ (ARS) observations and LIS-Control (0-10cm) and LIS simulations with the top soil layer modified to be thinner (5cm and 3cm).

Precipitation events and drydown periods are captured well in each of

- the model and observation products. LIS is consistently drier than the in-situ (ARS; c. Mike Cosh) data regardless of the top layer thickness employed in the Noah LSM.
- > SMAP performs quite well in terms of wetting events (peaks) and drydown shape, with observations every ~2 days.
- LIS and SMAP soil moisture and dynamics are similar, with LIS drying

down more rapidly during dry periods in mid-late August.

Conclusions

- There is significant spread in soil moisture conditions, even for the same modeling system, based on forcing, parameter inputs, LSM version, and spatial resolution.
- SMAP now offers the ability to provide realistic near-surface soil moisture conditions at 9km resolution, and is comparable to model and in-situ products.
- The overall climatologies of soil moisture from varying model, satellite, and in-situ products still need to be reconciled, and should be a function wet vs. dry regime and wetting vs. drydown event.
- This suite of initialization approaches will be extended to include:
- a) LIS runs with SMAP data assimilation
- b) LIS runs using SMAP to calibrate the Noah LSM
- The full suite will then used to kick off 24h NU-WRF forecasts to evaluate their downstream and L-A coupling impacts.

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