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Mesoscale
&
Microscale Meteorology @ NCAR



WRF-Var Background Error Generation

WRF Tutorial

July 28th 2005

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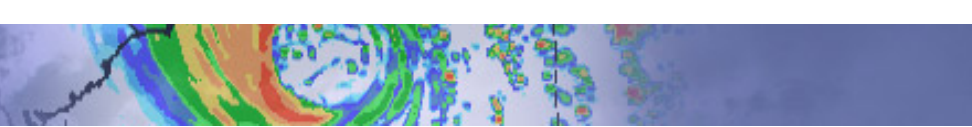


Outline of Talk

1. Use of Background Errors in WRF-Var.
2. WRF-Var Background Error Covariance Generation (gen_be).
3. Error Tuning.
4. Future Work.



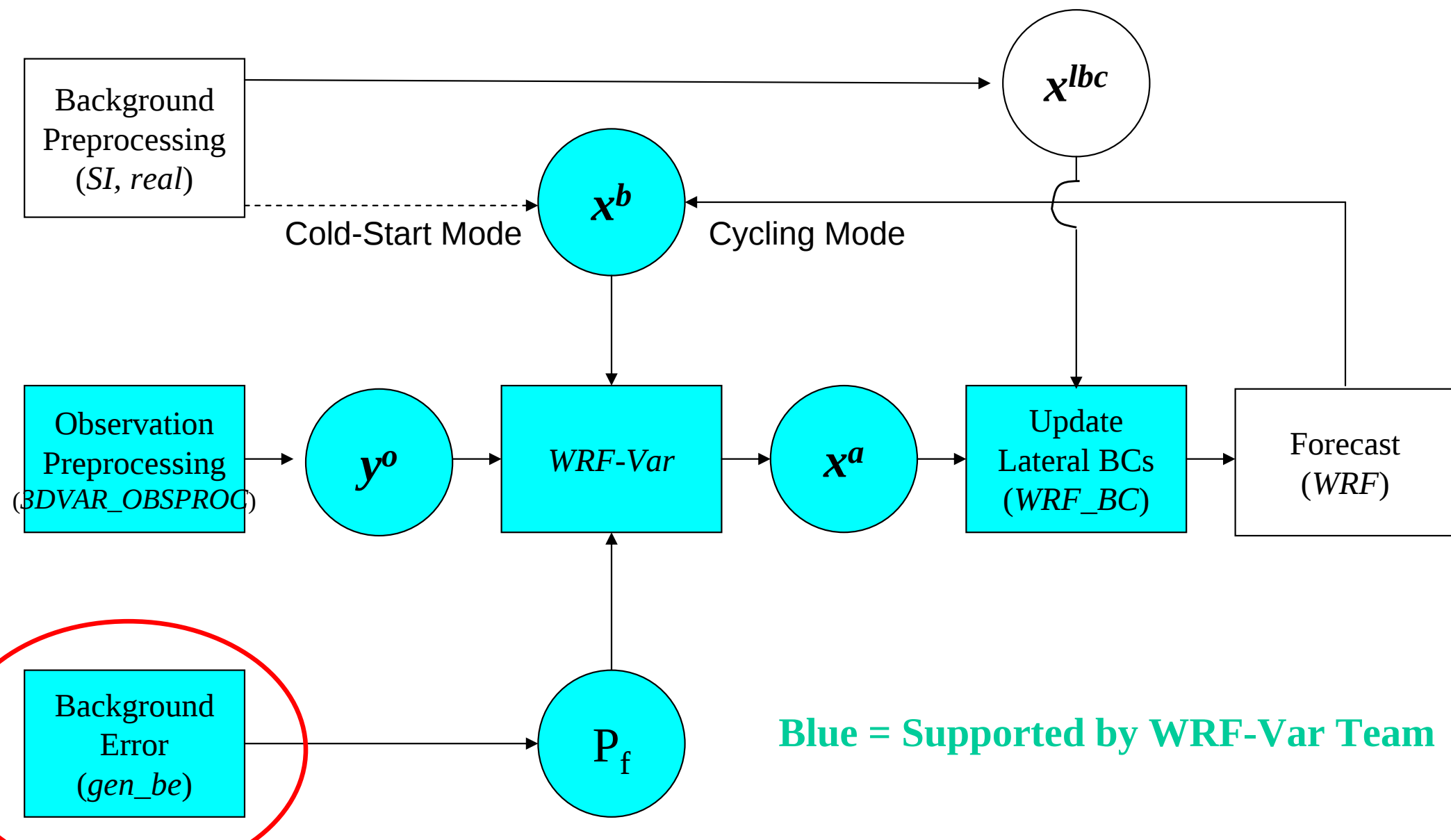
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1. Use of Background Errors in WRF-Var



WRF-Var in the WRF Modeling System





Background Error (BE) Estimation in WRF-Var

The number 1 question from WRF-Var users is

“What background error covariances are best for my application?”.

Procedure:

1. Use default statistics files supplied with code (MM5, GFS-based).
2. Create you own, once you have run your system for ~a few weeks.
3. Implement, tune, and iterate.

A new utility *gen_be* has been developed at NCAR to calculate BEs.



Incremental WRF-Var and Preconditioning

- Define **analysis increments**: $\mathbf{x}^a = \mathbf{x}^b + \mathbf{I} \mathbf{x}'$
- Solve **incremental** cost function:

$$J(\mathbf{x}) = \frac{1}{2} \mathbf{x}'^T \mathbf{P}_b^{-1} \mathbf{x}' + \frac{1}{2} \sum_n [\mathbf{d} - \mathbf{y}']_n^2 / \sigma_{on}^2$$

where $\mathbf{y}' = \mathbf{H}\mathbf{x}'$, $\mathbf{d} = \mathbf{y} - \mathbf{H}(\mathbf{x}^b)$

- Define **preconditioned control variable** $\mathbf{v}$ space transform $\mathbf{x}' = \mathbf{U}\mathbf{v}$ where $\mathbf{U}$ transform **CAREFULLY** chosen to satisfy $\mathbf{P}_b = \mathbf{U}\mathbf{U}^T$.
- Choose (at least assume) control variable components with uncorrelated errors:

$$J(\mathbf{x}) = \frac{1}{2} \sum_i v_i^2 + \frac{1}{2} \sum_n [\mathbf{d} - \mathbf{y}']_n^2 / \sigma_{on}^2$$



Background Error Estimation for WRF-Var

- Assume background error covariance estimated by model perturbations $\mathbf{x}'$:

$$\mathbf{P}_f = \overline{(\mathbf{x}^b - \mathbf{x}^t)(\mathbf{x}^b - \mathbf{x}^t)^T} \approx \overline{\mathbf{x}' \mathbf{x}'^T}$$

Two ways of defining $\mathbf{x}'$ in utility *gen_be*:

- The NMC-method (Parrish and Derber 1992):

$$\mathbf{P}_f = \overline{\mathbf{x}' \mathbf{x}'^T} \approx \overline{A(\mathbf{x}^{t2} - \mathbf{x}^{t1})(\mathbf{x}^{t2} - \mathbf{x}^{t1})^T}$$

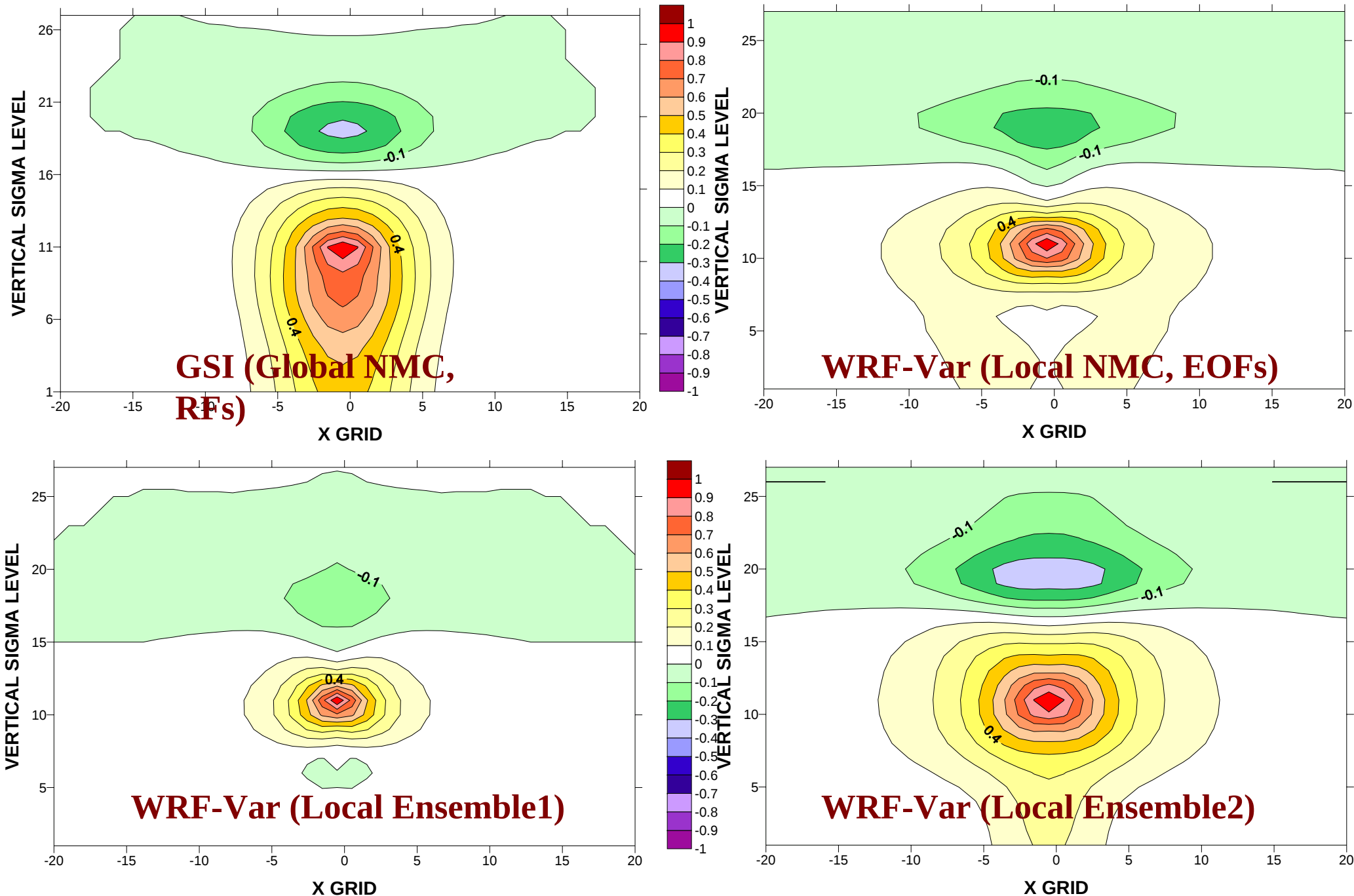
where e.g. $t2=24\text{hr}$, $t1=12\text{hr}$ forecasts...

- ...or ensemble perturbations (Fisher 2003):

$$\mathbf{P}_f = \overline{\mathbf{x}' \mathbf{x}'^T} \approx C \overline{(\mathbf{x}^k - \langle \mathbf{x} \rangle)(\mathbf{x}^k - \langle \mathbf{x} \rangle)^T}$$

- Tuning via innovation vector statistics and/or variational methods.

Analysis Sensitivity to Background Error Model

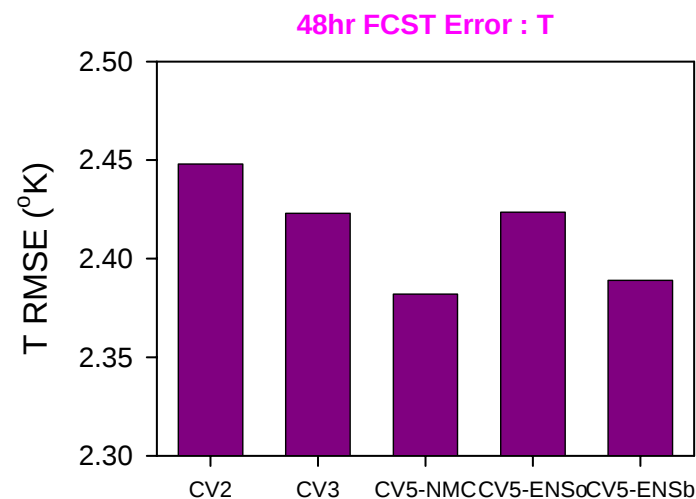
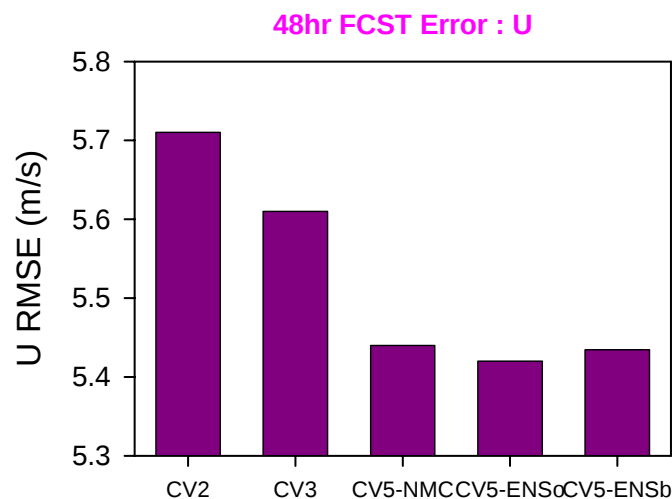
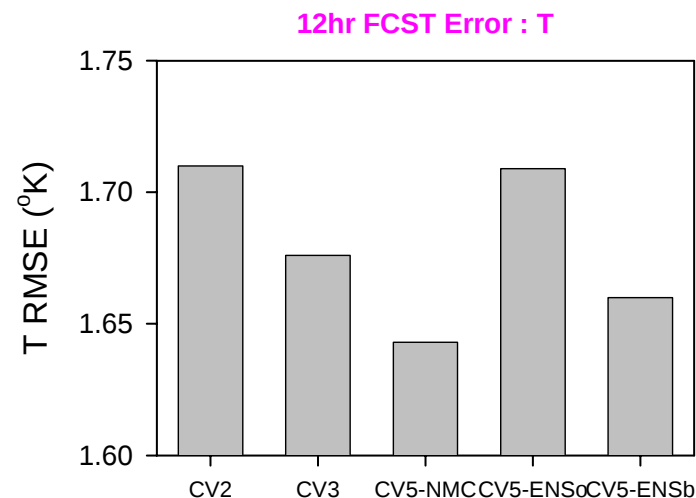
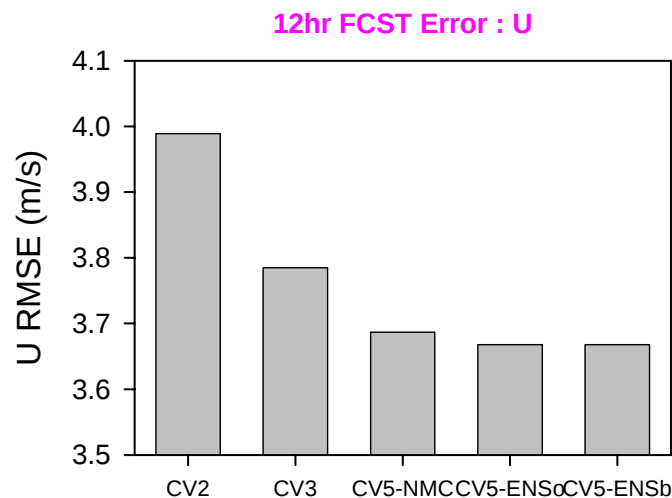


T increments : T Observation (1 Deg , 0.001 error around 850 hPa)



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Forecast Error (vs. sonde) Sensitivity to BE Stats



Courtesy Mi-Seon Lee

CV2 = Global statistics (MM5), CV3 = Global Statistics (GFS), CV5 = Local statistics (WRF)

NMC = NMC-method, ENS = Perturbed observation ensemble.



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2. WRF-Var Background Error Covariance Generation (gen_be)



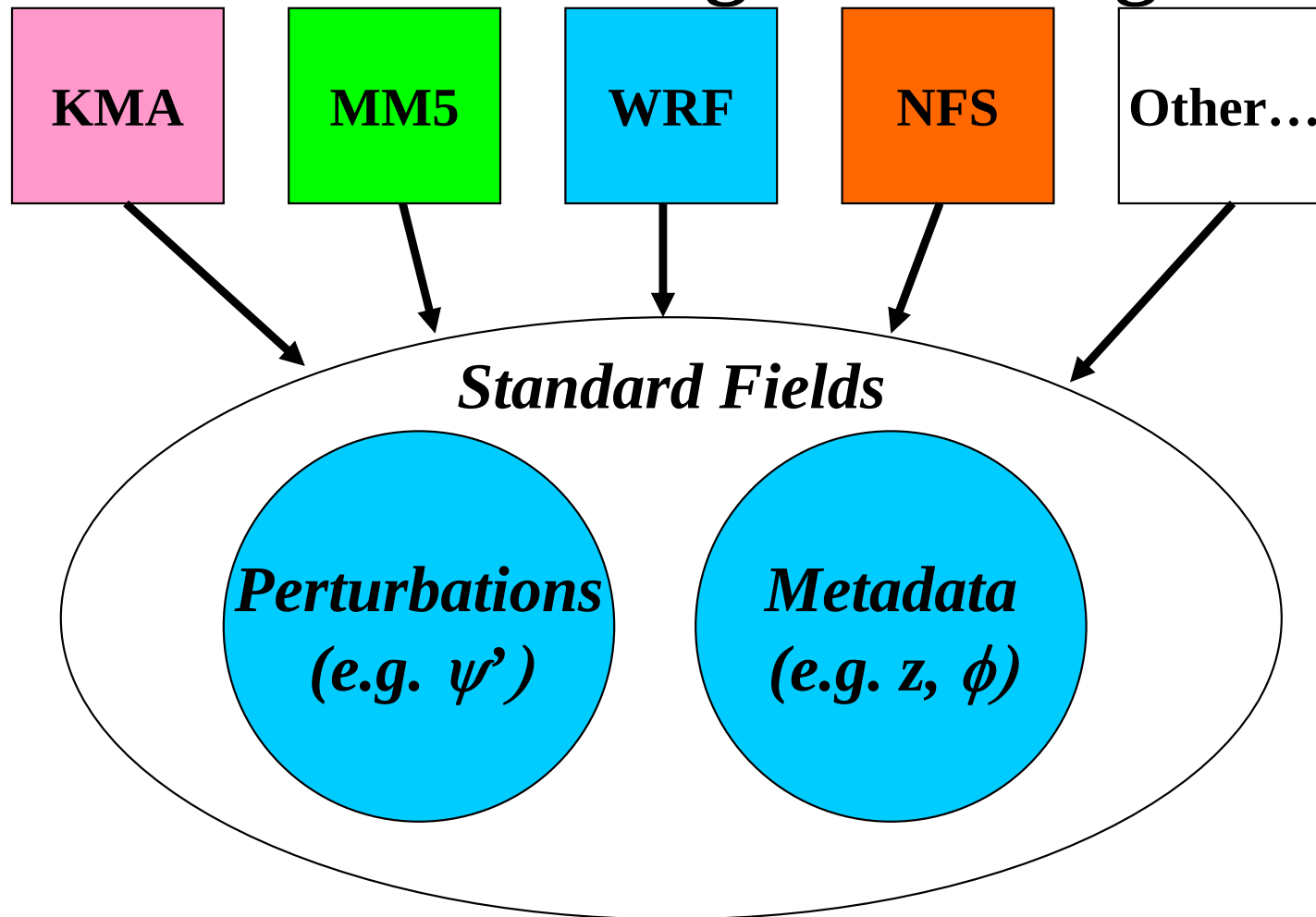
Background Error (BE) Estimation in WRF-Var

A new utility *gen_be* has been developed at NCAR to calculate BEs. The new *gen_be* code is split into a number of stages:

- **Stage0: Convert model-specific data to “standard fields”.**
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- Stage 4: Calculate horizontal error correlations: lengthscales (in regional domains), and “power spectra” in global domains.



BE Generation: gen_be_stage0



- Stage0 is the only stage that is model specific (e.g. gen_be_stage0_nfs).
- Perturbed fields are either forecast differences (NMC-Method) or ensemble perturbations (ensemble method).
- Standard fields are perturbations of streamfunction, velocity potential, temperature, relative humidity, and surface pressure.

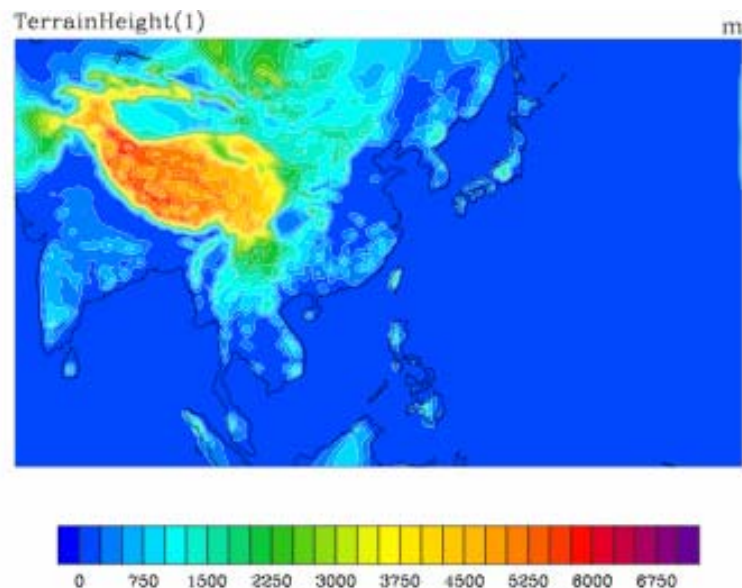


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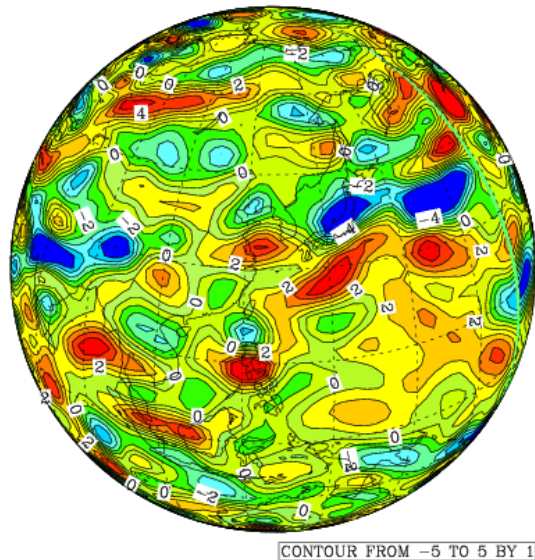
Background Error (BE) Estimation for different domains/models/times

In the following results, we apply gen_be stages 1-4 to a variety of models to see robustness of results:

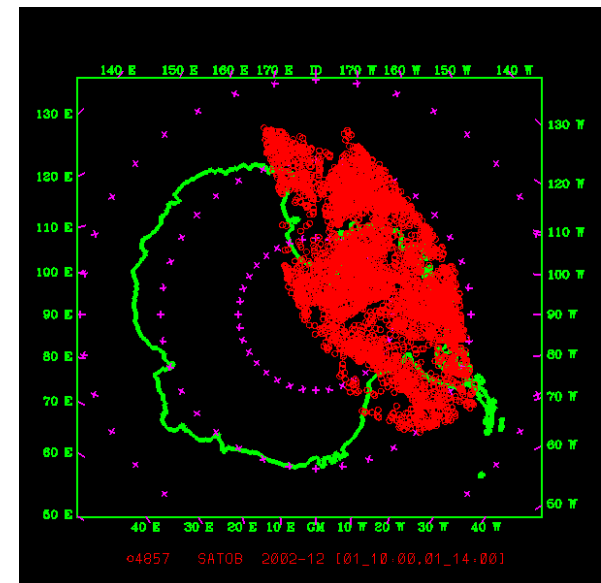
CWB 45km WRF



Korean T213 Global:



AMPS 30km WRF





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WRF-Var Control Variable Transform

cv_options		2 (original MM5)	3(GSI)	4 (Global)	5(regional)
Analysis increments	$\mathbf{x}'$	$u', v', T', q', p_s'(i, j, k)$			
Change of Variable	U_p	$\psi', \chi', p_{su}', q'(i, j, k)$	$\psi', \chi_u', T_u', \tilde{T}', p_{su}'(i, j, k)$		
Vertical Covariances	U_v	$\mathbf{B} = \mathbf{E} \mathbf{\Lambda} \mathbf{E}^T$	RF	$\mathbf{B} = \mathbf{E} \mathbf{\Lambda} \mathbf{E}^T$	
Horizontal Correlations	U_h	RF		Spectral	RF
Control Variables	$\mathbf{y}$	$\mathbf{v}(i, j, m)$		$\mathbf{v}(l, n, m)$	$\mathbf{v}(i, j, m)$

$$\mathbf{x}' = U \mathbf{v} = U_p U_v U_h \mathbf{v}$$

Define control variables:

$$\psi'$$

$$r' = q' / q_s(T_b, q_b, p_b)$$

$$\chi' = \chi_u' + \chi_b'(\psi')$$

$$T' = T_u' + T_b'(\psi')$$

$$p_s' = p_{su}' + p_{sb}'(\psi')$$



Balance Via Statistical Regression

Regression Coefficients after Wu et al (2002):

$$\chi'_b = c \psi' \quad T'_b(k) = \sum_{k1} G(k, k1) \psi'(k1) \quad p'_{sb} = \sum_k W(k) \psi'(k)$$



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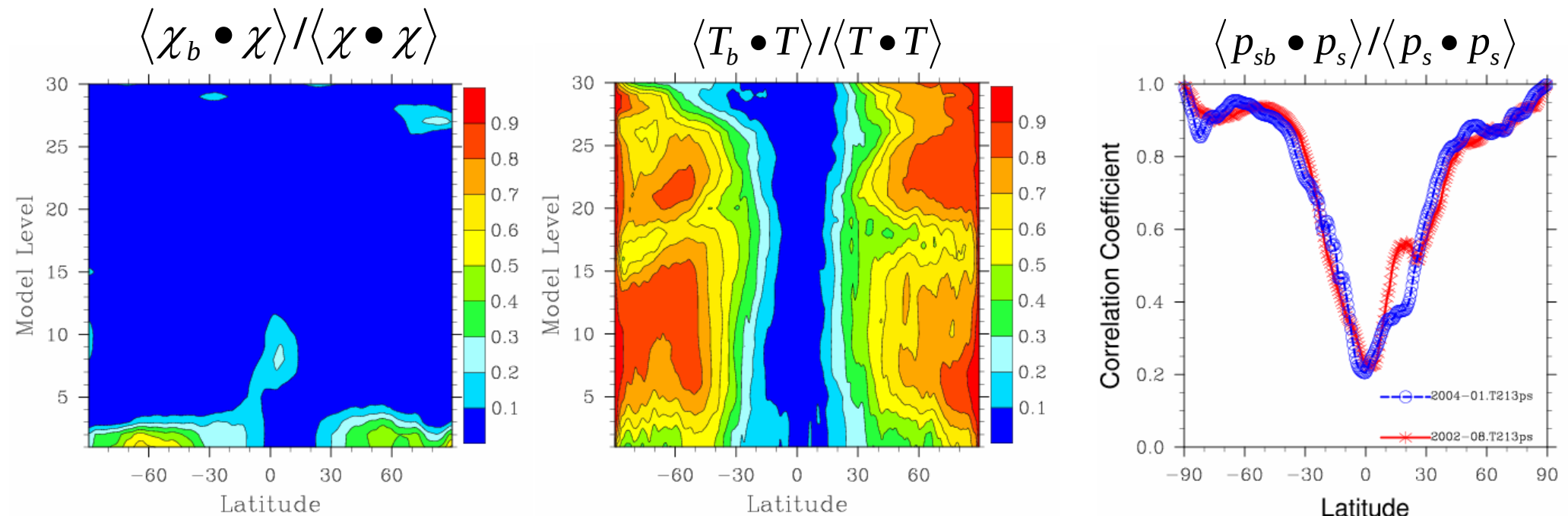


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**Explained covariance due to balance constraints (Jan 2004
global data - NMC-method applied):**





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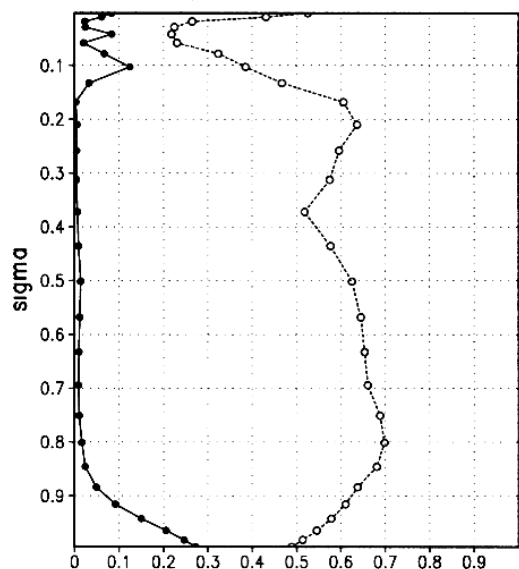
Stage2: CWB/KMA/AMPS Comparison

Calculate domain averaged correlations:

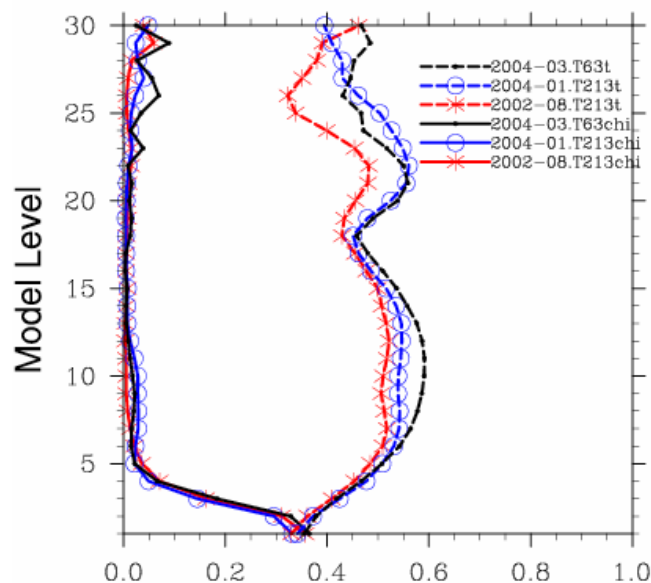
$$\langle T_b \bullet T \rangle / \langle T \bullet T \rangle \quad \langle \chi_b \bullet \chi \rangle / \langle \chi \bullet \chi \rangle$$

For a variety of models using NMC-method.

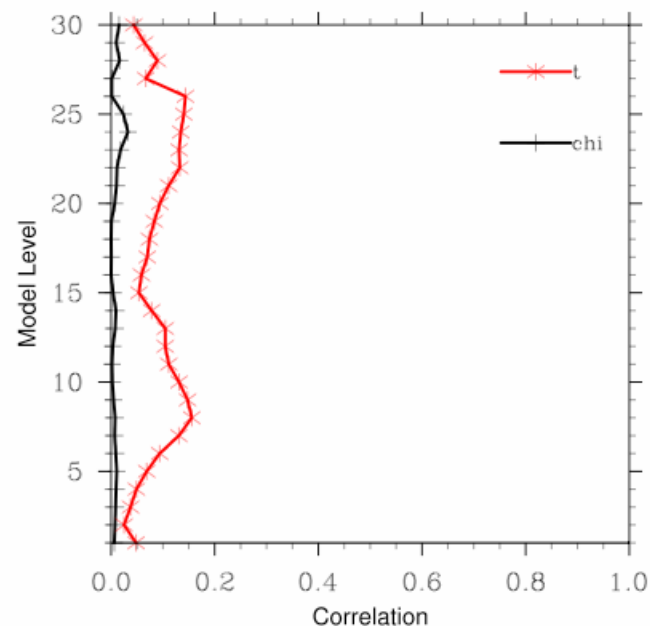
NCEP (Wu et al 2002):



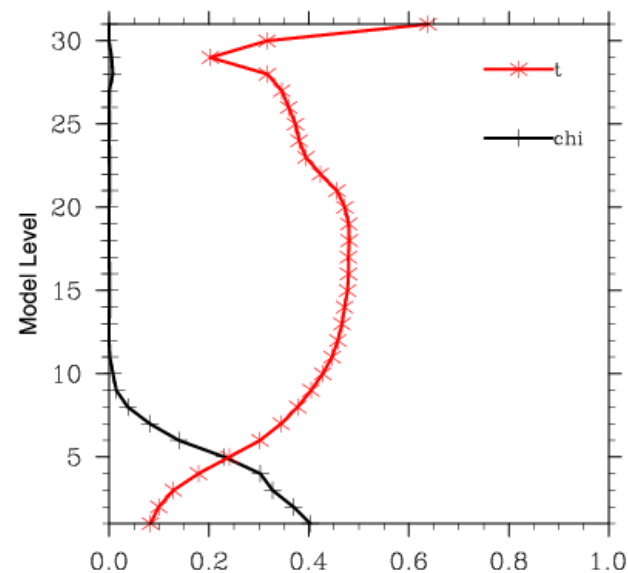
Korean T213 Global:



CWB 45km WRF:



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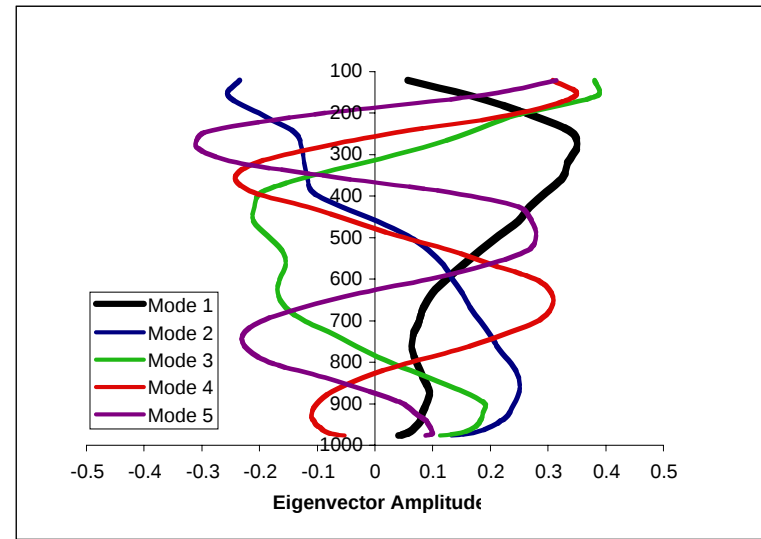
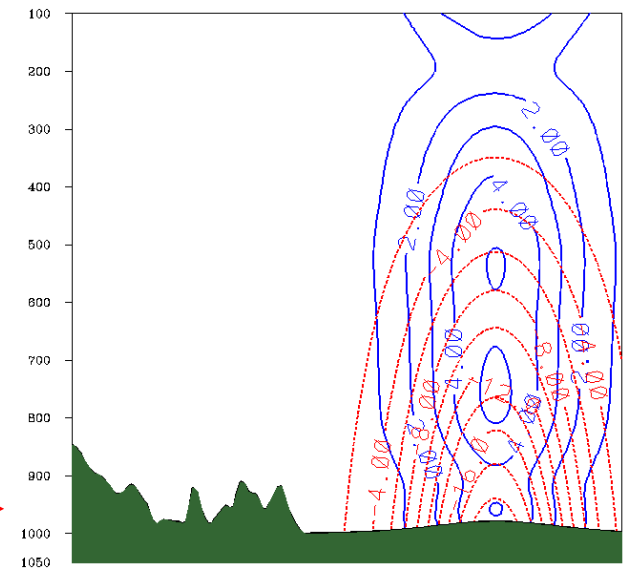


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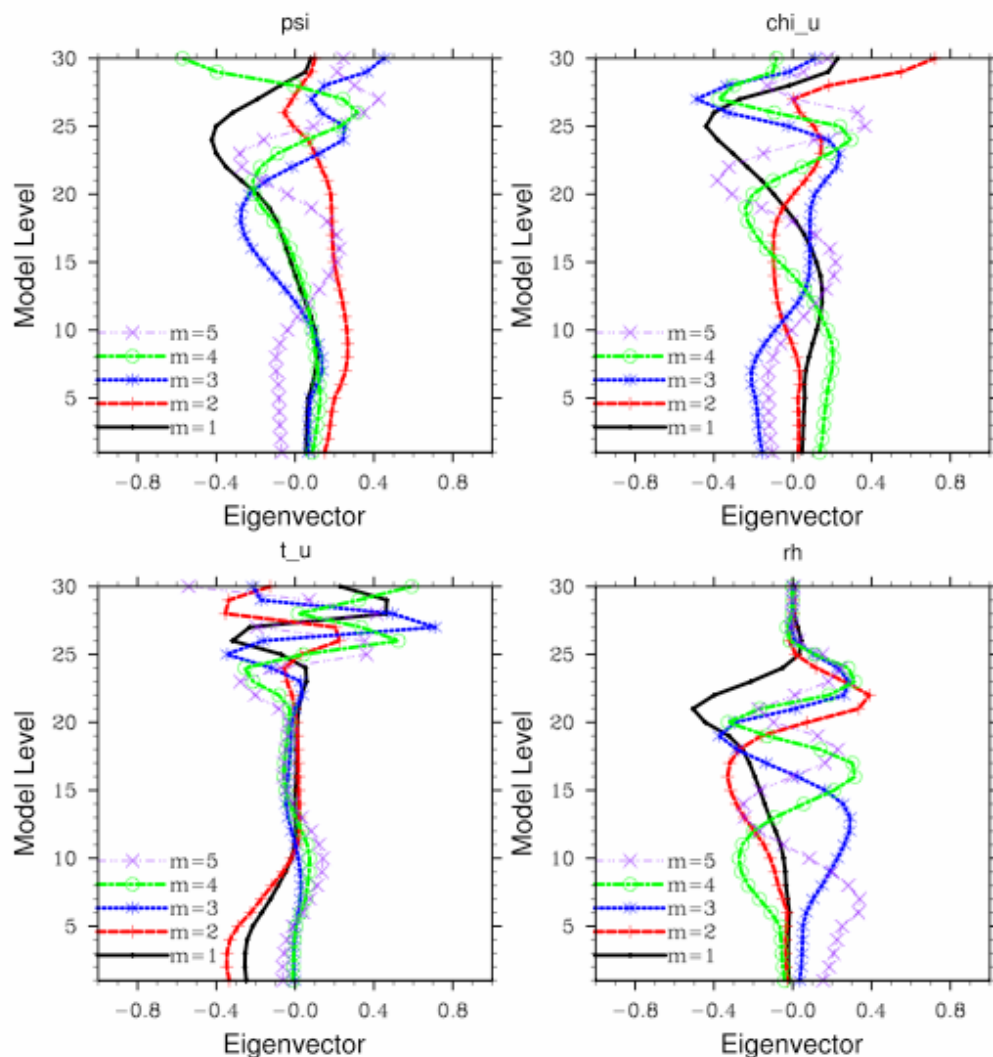




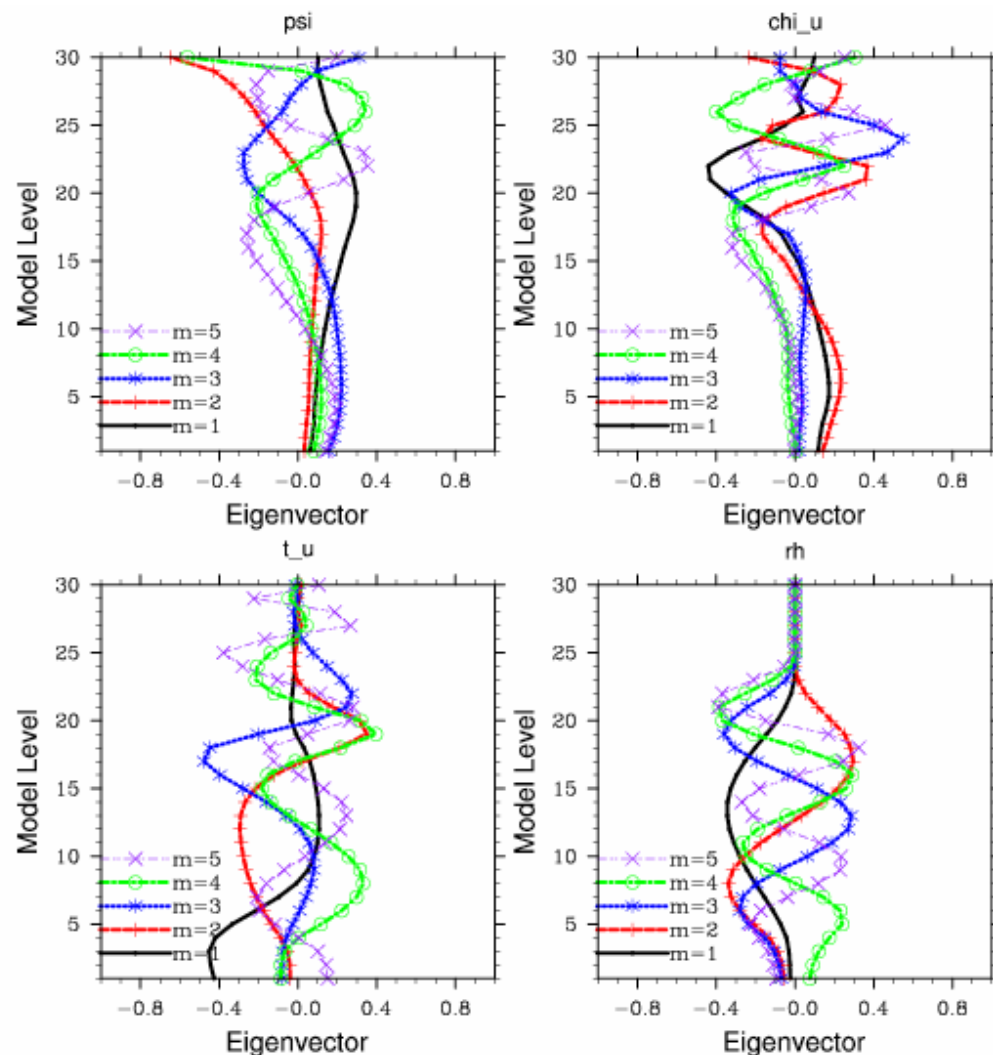
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Comparison of Domain-Averaged Eigenvectors E_v^g

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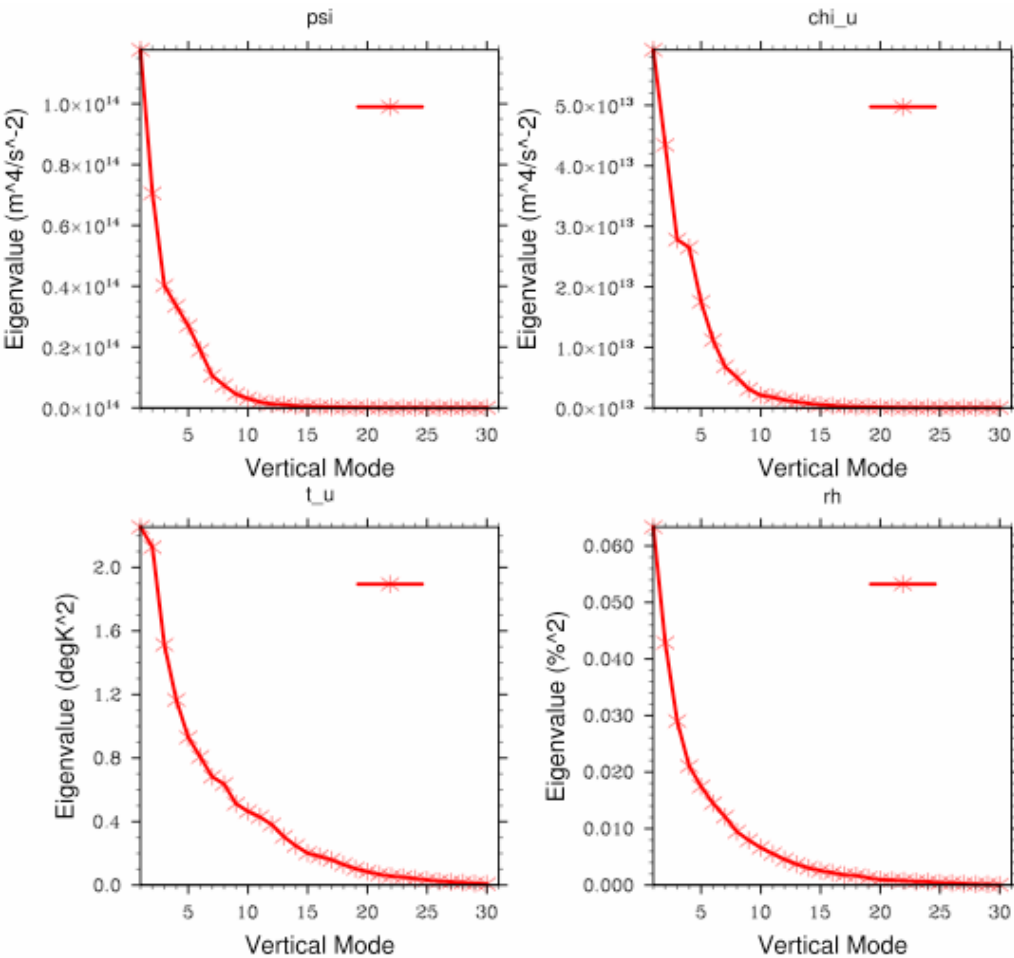


Conclusion: Significant differences in regional/global models (as one might expect), so it is important to calculate domain-specific background error correlations.

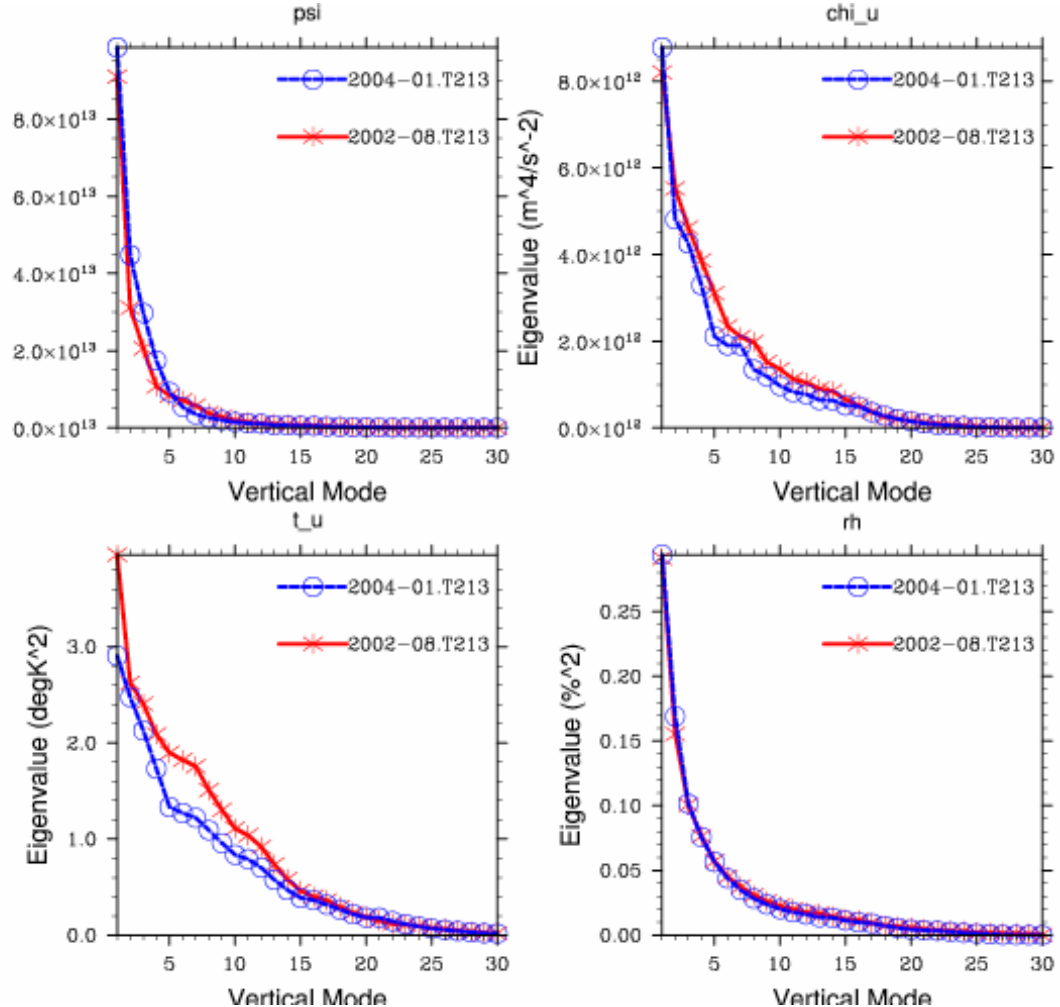


Comparison of Domain-Averaged Eigenvalues Λ_v^g

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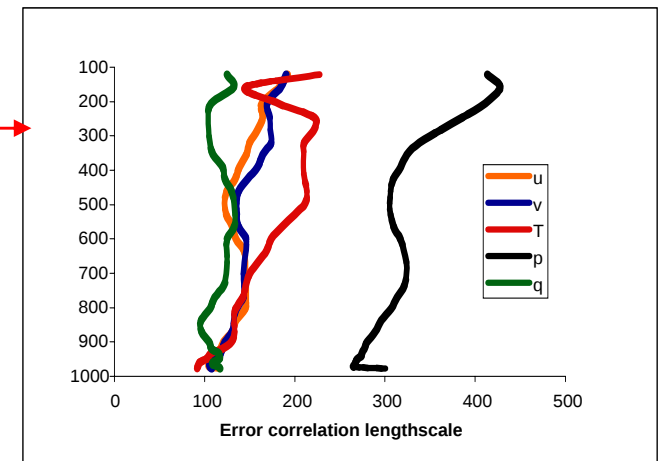
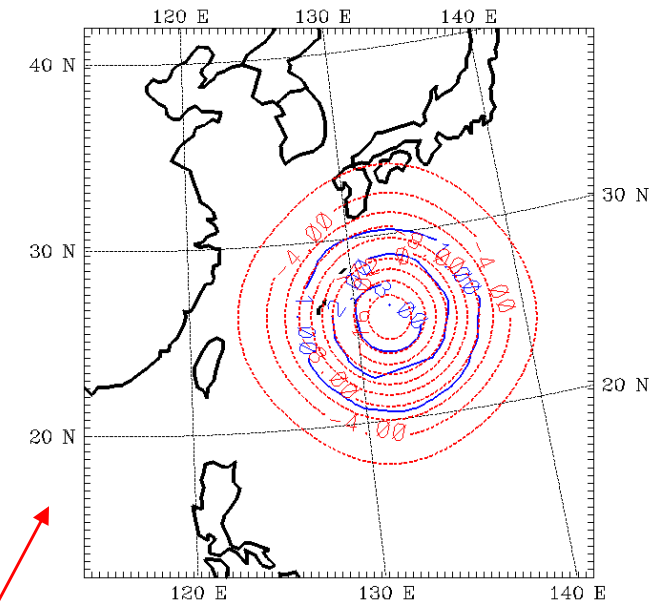
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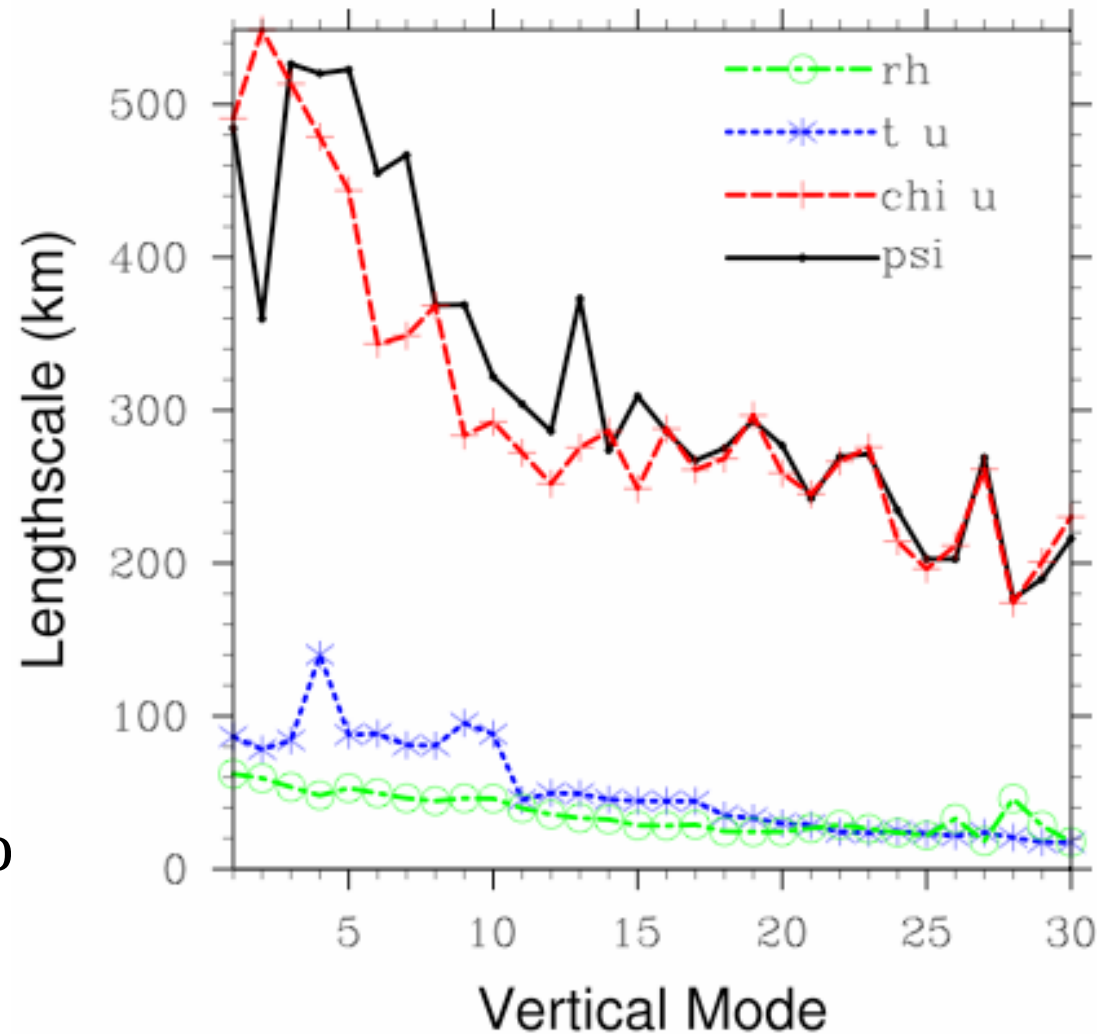




Stage4: Regional model (CWB Sept. 2003) data

Horizontal error correlation
lengthscales are produced as
follows:

- a. Bin each 2D perturbation field as a function of gridpoint separation.
- b. Calculate correlation matrix for all data.
- c. Fit Gaussian curve to data to estimate horizontal error correlation lengthscales.





Components of Global Background Error Statistics

- a) **Regression Coefficients** (used to derive “balanced” components of fields) after Wu et al (2002) (output from stage2):

$$\chi'_b = c \psi' \quad T'_b(k) = \sum_{k1} G(k, k1) \psi'(k1) \quad p'_{sb} = \sum_k W(k) \psi'(k)$$

- b) **Eigenvectors/eigenvalues** of vertical component of background error (output from stage3):

Domain/time averaged “global” values - $\mathbf{P}_{fv}^g = \mathbf{E}_v^g \Lambda_v^g \mathbf{E}_v^{gT}$

Longitude/time averaged “local” values - $\mathbf{P}_{fv}^l(\phi) = \mathbf{E}_{fv}^l(\phi) \Lambda_{fv}^l(\phi) \mathbf{E}_{fv}^{lT}(\phi)$

- a) **Power spectra** (model horizontal error correlations for each vertical mode - output from stage4_global):

$$F^m(\phi) = \frac{1}{I} \sum_{i=1}^I F(\lambda_i, \phi) e^{-im\lambda_i} \rightarrow F_n^m = \sum_{j=1}^J W_j F^m(\mu_j) P_n^m(\mu_j) \rightarrow D_n = \sum_{m=-n}^n (F_n^m)^2$$



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- a) **Lengthscales** (model horizontal error correlations s for each vertical mode - output from stage4_regional):

$$B(r) = B(0) \exp[-r^2 / 8s^2]$$



Conclusions

1. Background Error Statistics are a crucial input to 3/4D-Var systems.
2. BE estimation methods are somewhat ad-hoc, and require significant efforts to accumulate the necessary forecast input data (e.g. 1 month 24hr forecasts)
3. A new utility *gen_be* has been written to calculate BEs for WRF-Var applications (for a variety of models, and techniques).
4. The output of *gen_be* must be further tuned to optimize WRF-Var performance. A number of additional utilities are available to perform this work.