WRF Guangzhou Tutorial

Recent Enhancements in the Numerics of the WRF Dynamical Core

Hybrid Vertical Coordinate Modifications for Moist LES Simulations

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WRF Terrain-Following Sigma (mass) Coordinate

Hydrostatic dry pressure: p_d Vertical coordinate: $\eta = \frac{p_d - p_t}{p_s - p_t}$

g (column mass per unit area): $\mu = p_s - p_t$

_ayer mass per unit area:
$$\rho_d \Delta z = -\frac{1}{g} \Delta p_d = -\frac{\mu}{g} \Delta \eta$$

Conserved prognostic variables: μ , $U = \mu u$, $V = \mu v$, $W = \mu w$, $\Theta = \mu \theta$







Basic sigma coordinate

Hybrid sigma coordinate

$$p_{d} = \eta(p_{s} - p_{t}) + p_{t}$$

$$p_{d} = B(\eta)(p_{s} - p_{t}) + [\eta - B(\eta)](p_{0} - p_{t}) + p_{t}$$

$$B(\eta): \text{ Relative weighting between terrain-following and pure dry hydrostatic pressure coordinate:}$$

$$\eta = \frac{p_{p} - p_{t}}{p_{s} - p_{t}} \quad \text{for } B(\eta) = \eta \quad (\text{basic sigma})$$

$$\eta = \frac{p_{d} - p_{t}}{p_{0} - p_{t}} \quad \text{for } B(\eta) = 0 \quad (\text{pure pressure})$$
Coordinate metric:
$$\mu_{d}(x, y, t) = \frac{\partial p_{d}}{\partial \eta} = \Delta p_{c} \qquad \mu_{d}(x, y, \eta, t) = \frac{\partial p_{d}}{\partial \eta} = B_{\eta} \Delta p_{c} + (1 - B_{\eta})(p_{0} - p_{t})$$

$$\Delta p_{c} = p_{s} - p_{t} \quad \sim \text{mass in each vertical column}$$



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Continuity equation for dry hydrostatic pressure:

$$\begin{aligned} \frac{\partial \mu_d}{\partial t} + (\boldsymbol{\nabla} \cdot \boldsymbol{V})_{\eta} &= 0\\ \text{Basic sigma coordinate} & \text{Hybrid sigma coordinate}\\ -\int_{1}^{0} \frac{\partial \mu_d}{\partial t} d\eta &= \\ \frac{\partial \Delta p_c}{\partial t} &= \int_{1}^{0} \boldsymbol{\nabla} \cdot \boldsymbol{V}_H d\eta\\ \Omega &= -\int_{1}^{\eta} \left(\frac{\partial \Delta p_c}{\partial t} + \boldsymbol{\nabla} \cdot \boldsymbol{V}_H\right) d\eta \end{aligned} \qquad \begin{aligned} \frac{\partial \Delta p_c}{\partial t} d\eta &= -\int_{1}^{0} B_{\eta} \frac{\partial \Delta p_c}{\partial t} d\eta\\ \frac{\partial \Delta p_c}{\partial t} &= \int_{1}^{0} \boldsymbol{\nabla} \cdot \boldsymbol{V}_H d\eta\\ \Omega &= -\int_{1}^{\eta} \left(\frac{\partial \Delta p_c}{\partial t} + \boldsymbol{\nabla} \cdot \boldsymbol{V}_H\right) d\eta \end{aligned}$$
Recover μ_d from: $\mu_d = \Delta p_c(x, y)$

$$\mu_d = C_1(\eta) \Delta p_c(x, y) + C_2(\eta)\\ C_1(\eta) &= B_{\eta}\\ C_2(\eta) &= (1 - B_{\eta})(p_0 - p_0)\\ (C_1, C_2 \text{ depend only on } \eta) \end{aligned}$$



 $-\int_{1}^{0}\frac{\partial\mu_{d}}{\partial t}d\eta =$







Improvement of WRF Dynamics for LES Applications

Strong Sensitivity to the Acoustic Time Step in WRF LES Simulations of Low Clouds



DYCOMS II RF02 nighttime marine stratocumulus case

DOE ARM Southern Great Plains Statocumulus Case

- Small time step sensitivity and numerical noise also occurs in WRF LES simulations for this case.
- Noise is present during first 2 hours of the simulation before cloud forms.

Stripped-down dycore test shows noise

- 2-D domain, 4 km (X) by 5 km (Z)
- dx = 100 m, dz = 20 m
- dt = 0.5 s, N_{ns} = 12
- No microphysics; No radiation; No surface forcing (only initial perturbation); No SGS mixing scheme; No Coriolis force





Acoustic Step Time Integration Using $\Theta = \mu_d \theta$ $\eta = \frac{p_d - p_t}{\mu_d} \qquad \mu_d = p_{ds} - p_t$ Vertical coordinate: $\frac{\partial U}{\partial t} + \left(\mu_d \alpha \frac{\partial p}{\partial x} + \frac{\alpha}{\alpha_d} \frac{\partial p}{\partial n} \frac{\partial \phi}{\partial x}\right)^{\tau} = R_U^t$ $U^{\tau + \Delta \tau}$ $\frac{\partial \mu_d}{\partial t} + \frac{\partial U}{\partial x}^{\tau + \Delta \tau} + \frac{\partial \Omega}{\partial n}^{\tau + \Delta \tau} = 0$ $\mu_d^{\tau+\Delta\tau}$, $\Omega^{\tau+\Delta\tau}$ $\frac{\partial \Theta}{\partial t} + \left(\frac{\partial U\theta^t}{\partial x} + \frac{\partial \Omega\theta^t}{\partial n}\right)^{\tau + \Delta \tau} = R_{\Theta}^t$ $\Theta^{\tau + \Delta \tau}$ $W^{\tau+\Delta\tau}, \ \phi^{\tau+\Delta\tau} \begin{cases} \frac{\partial W}{\partial t} + g \overline{\left(\mu_d - \frac{\alpha}{\alpha_d} \frac{\partial p}{\partial \eta}\right)}^{\tau} = R_W^t \\ \mu_d^t \frac{\partial \phi}{\partial t} + U^{\tau+\Delta\tau} \frac{\partial \phi}{\partial x}^t + \Omega^{\tau+\Delta\tau} \frac{\partial \phi}{\partial n}^t - g \overline{W}^{\tau} = R_\phi^t \end{cases}$ $\alpha_d^{\tau+\Delta\tau} \qquad \alpha_d^{\tau+\Delta\tau} = -\frac{1}{\mu_d^{\tau+\Delta\tau}} \frac{\partial \phi}{\partial \eta}^{\tau+\Delta\tau}$ $p^{\tau+\Delta\tau} \qquad p^{\tau+\Delta\tau} = p_0 \left(\frac{R_d \Theta^{\tau+\Delta\tau} [1 + (R_v/R_d)q_v^t]}{p_0 \mu_d^{\tau+\Delta\tau} \alpha_d^{\tau+\Delta\tau}} \right)^{\gamma}$





DOE ARM Southern Great Plains Stratocumulus Case



Idealized 2-D WRF Moist ABL Simulation, $\Delta x = 100$ m



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Idealized 2-D WRF Moist ABL Simulation, $\Delta x = 1$ km



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Idealized Test Case, 2-D WRF Prototype, $\Delta x = 1$ km



Idealized Supercell Simulation, dx = 2 km, t = 1 h

 $\delta t = 12 \text{ s}, \text{ N}_{\text{s}} = 6$ w, 8 km θ , 0.2 km q_r, 0.2 km **Initial Sounding** θ_{m} -80 -60 100 200 $max \sim 40 \text{ m/s}$ min ~ -7 K max ~ 5 gm/kg pressure (hPa) θ_d 400 600 800 1000 -20 0 20 Temperature, T_{eq}(z) (°C) $\theta_m - \theta_d$ max ~ 0.4 K $max \sim -0.1 \text{ gm/kg}$ $max \sim 1 m/s$ (Wei Wang, NCAR) 50 km → ←

Idealized Supercell Simulation, dx = 2 km, t = 1 h





Idealized Supercell Simulation, dx = 2 km, t = 1 h





Summary

- In WRF LESs of low clouds, significant sensitivity of simulated cloud properties to the acoustic time step and the growth of numerical noise is found to occur at low levels in the vicinity of strong vertical gradients of water vapor.
- The sensitivity appears to be caused by the neglect of temporal variations in water vapor in computing the pressure during the acoustic time steps in the WRF time-split numerical integration scheme.
- This artificial behavior has been removed from WRF by solving for a moist potential temperature θ_m as a prognostic variable on the acoustic time steps (instead of θ), which removes the explicit appearance of q_v on the small time steps.
- Moist θ_m as a prognostic was variable released in WRF version 3.7
 - Set option use_theta_m = 1 (default = 0)
 - Include patch from WRF Web page "WRF Model Version 3.7: Known Problems and Fixes"
- The potential impact of θ_m in other WRF applications needs to be examined.
- A hybrid sigma coordinate in WRF should provide more accurate numerics, particularly in computing horizontal pressure gradients. (Hopefully available in WRF next year).

