

Initializing a Hurricane Vortex with an EnKF

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Hurricane Prediction

- Yearly-average 24-h track forecast error ~ 150 km
- Initialization --- Challenge
 - Vortex bogusing and relocation
 - 3DVar, 4DVar
 - Ensemble Kalman filter (EnKF)
- Ensemble hurricane forecast
 - Probabilistic forecast is desirable
 - Implementing EnKF in an ensemble forecast system is simple
 - EnKF also provides initial conditions for ensemble forecast

Hurricane Observation

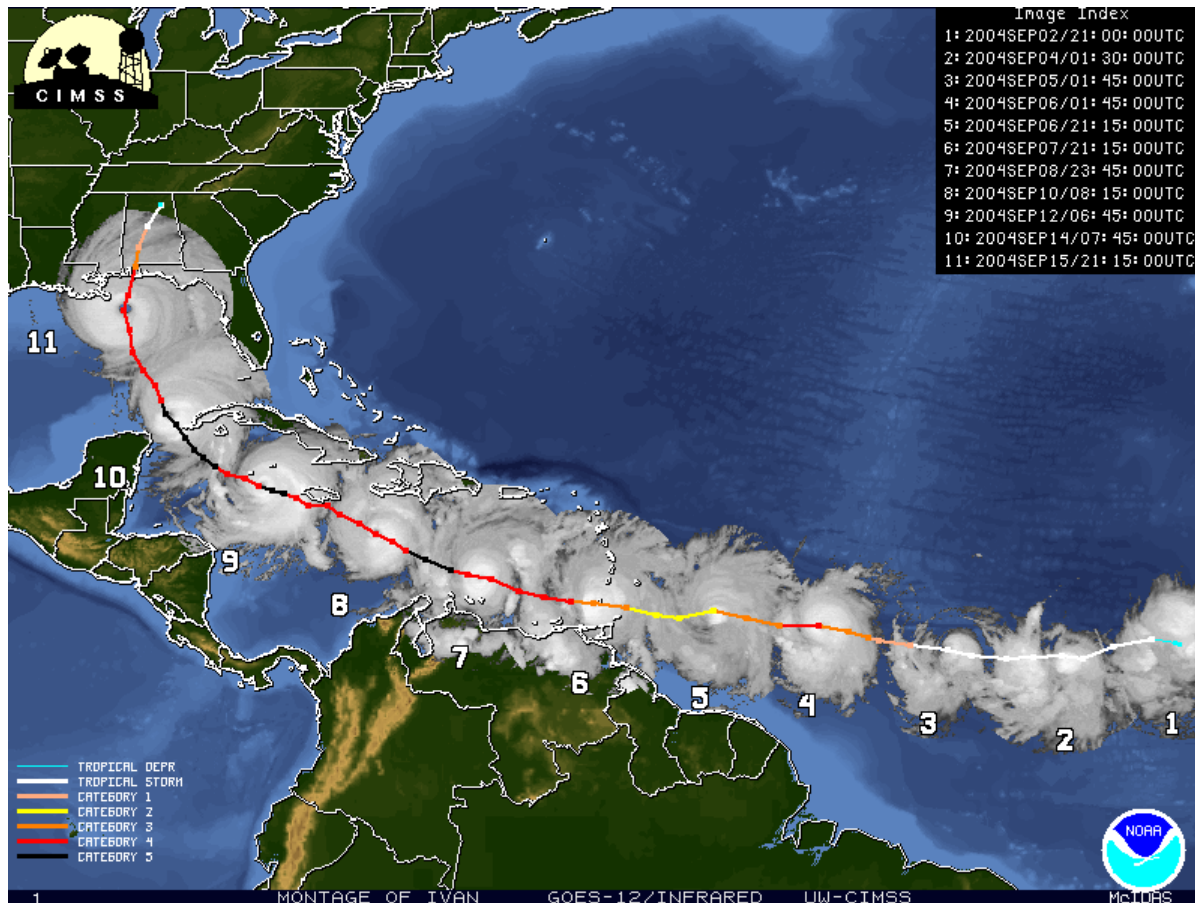


Image courtesy of CIMSS/SSEC/WISC

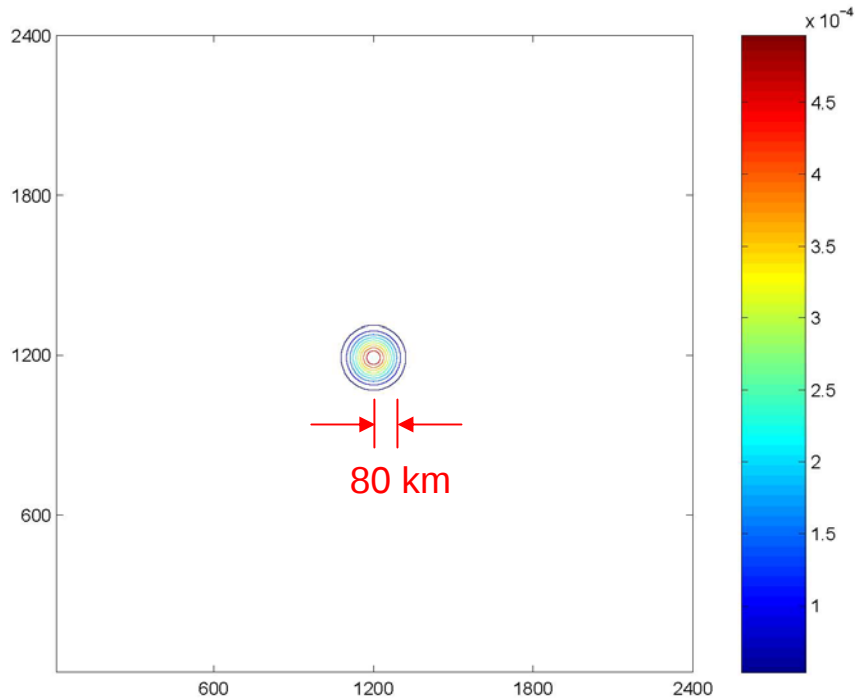
Ensemble Kalman Filter

$$\overline{\mathbf{X}}^a = \overline{\mathbf{X}}^f + \mathbf{K}(\mathbf{y} - \mathbf{H}\overline{\mathbf{X}}^f)$$

Analysis Forecast Correction

- Observation operator **H**: find vortex position from model state **X**
- Kalman Gain **K** ~ Cov (X,HX)
can be computed directly from the ensemble
- Performance
 - Optimal when position errors are small and Gaussian
 - Degrades as position errors increase
 - Other observations such as intensity and shape can extend its effectiveness

A Simple Example



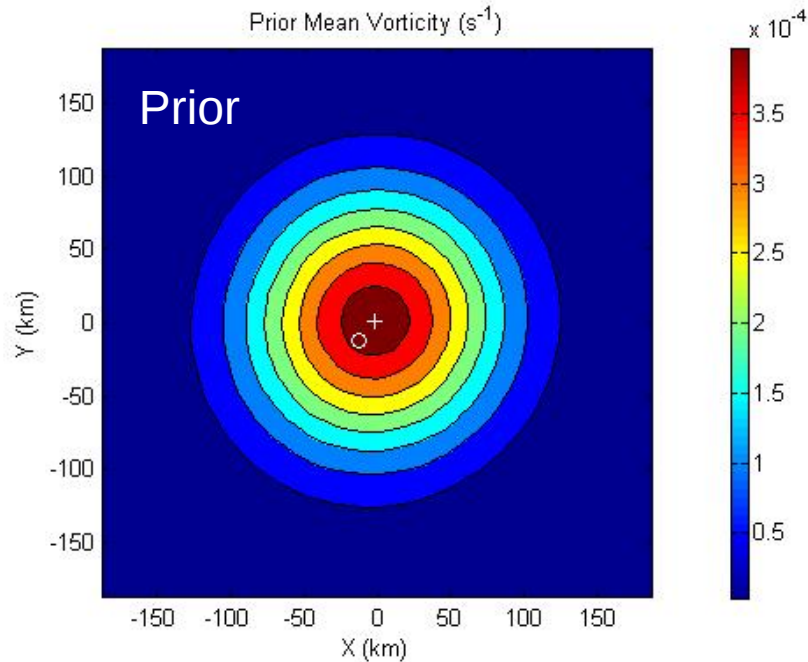
$$\zeta(\mathbf{x}) = \zeta_0(\mathbf{x} + \mathbf{d})$$

$$= \zeta_0(\mathbf{x}) + \mathbf{d} \cdot \frac{\partial \zeta_0}{\partial \mathbf{x}} + O(|\mathbf{d}|^2)$$

For small $\mathbf{d} \sim N(\mathbf{0}, \sigma_f^2 \mathbf{I})$,

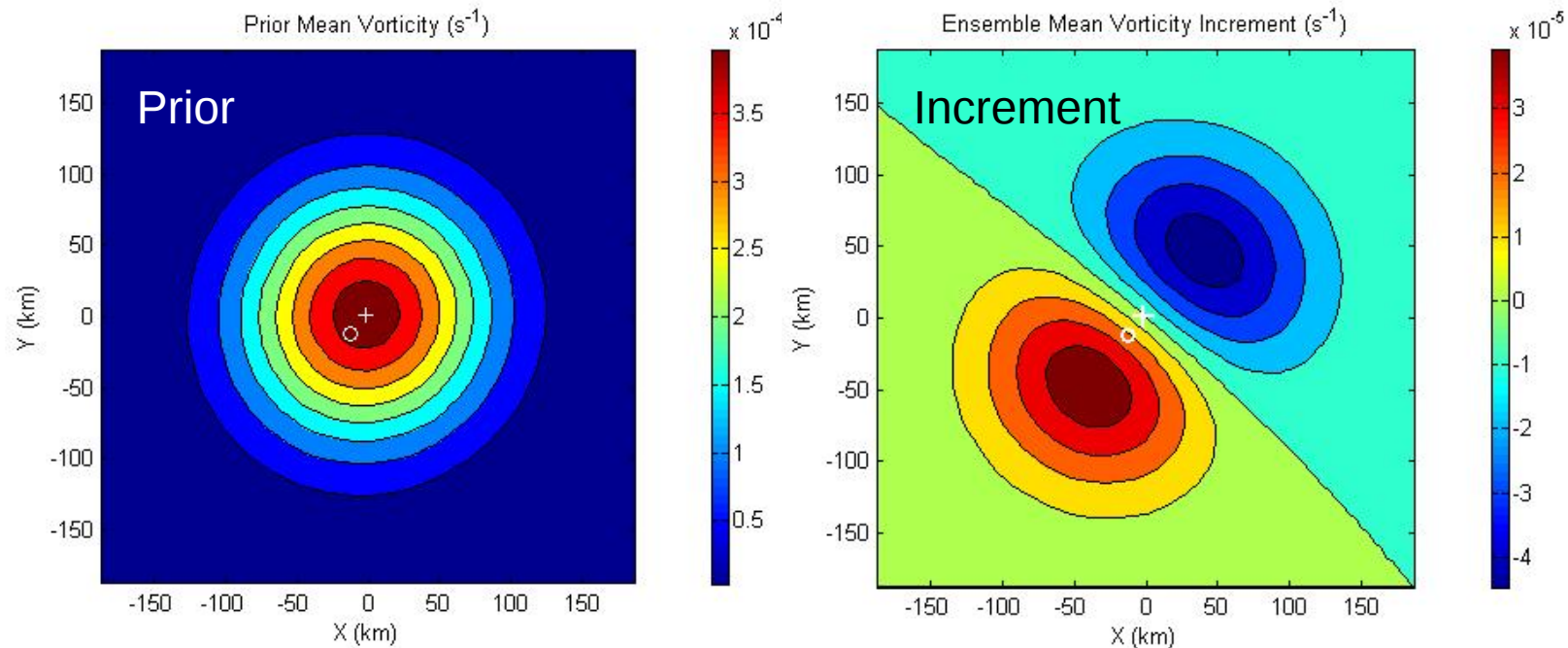
$$\zeta \sim N(\zeta_0, \sigma_f^2 \left(\frac{\partial \zeta_0}{\partial \mathbf{x}} \right) \left(\frac{\partial \zeta_0}{\partial \mathbf{x}} \right)^T)$$

Assimilating center position



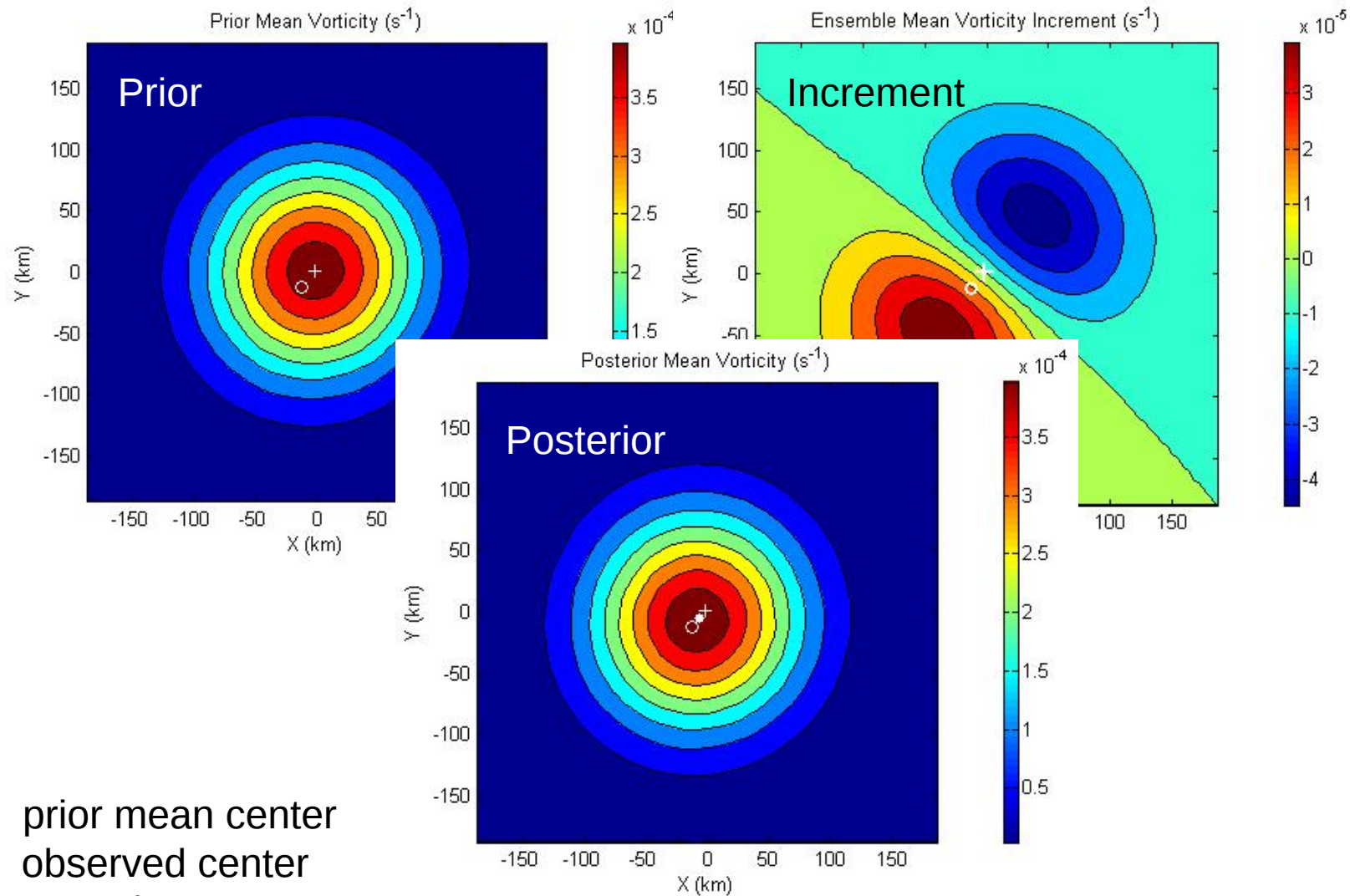
- + prior mean center
- o observed center
- dot posterior mean center

Assimilating center position

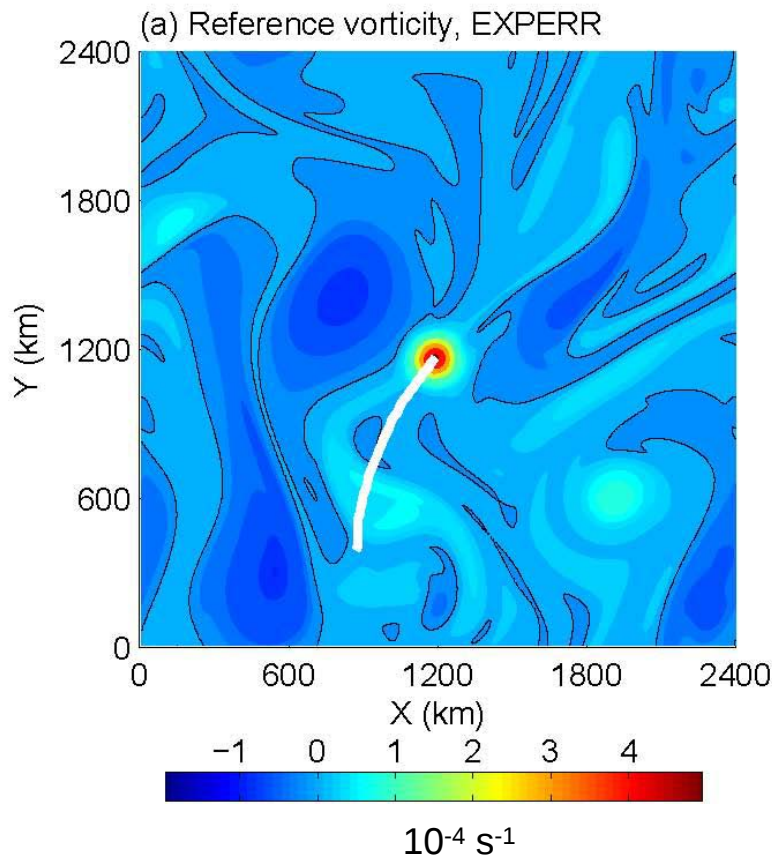


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Assimilating center position



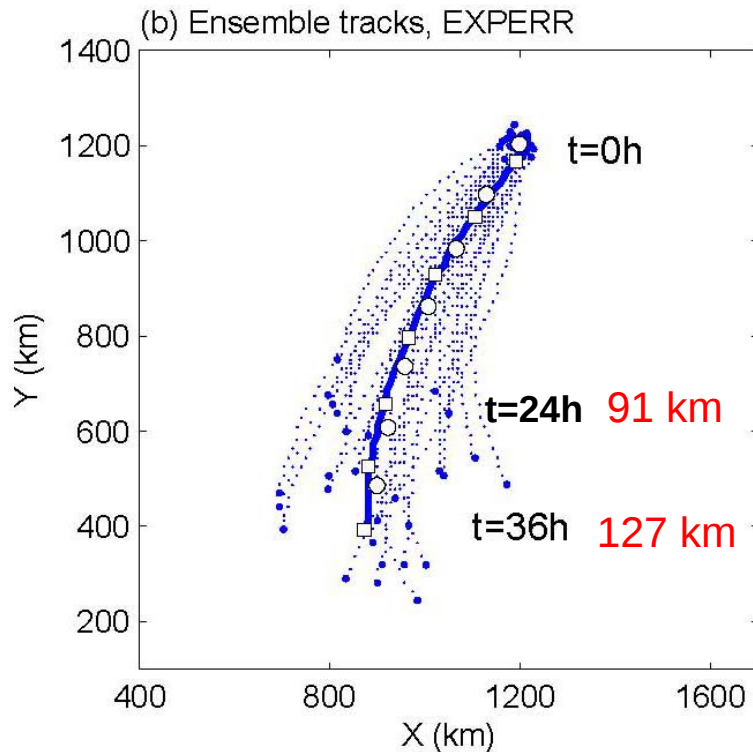
A simple experiment with a barotropic model



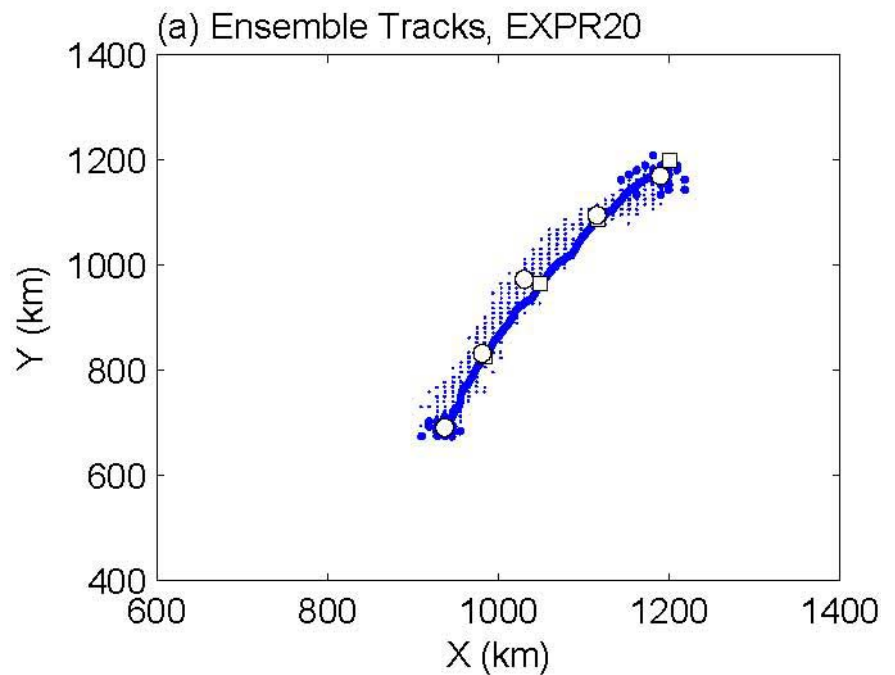
- Barotropic vorticity equation
- 2400 km x 2400 km, doubly periodic domain
- True state is strong 80-km vortex embedded in large-scale turbulent flow
- Simulate obs of vortex position with random error
- Assimilate obs into forecast with initial errors in vortex position and large-scale flow
- 30 ensemble members + 1 true/reference

Ensemble tracks

Without assimilation



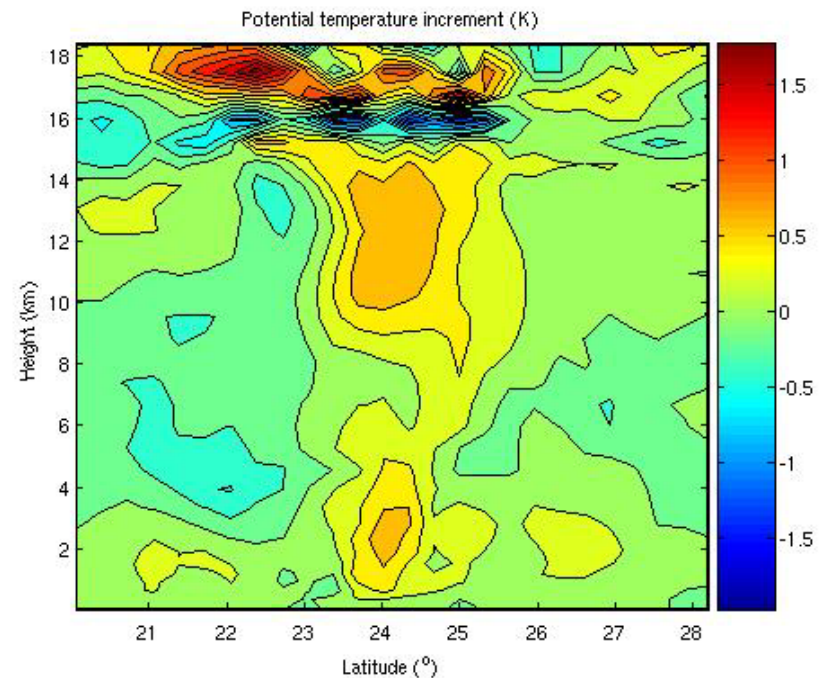
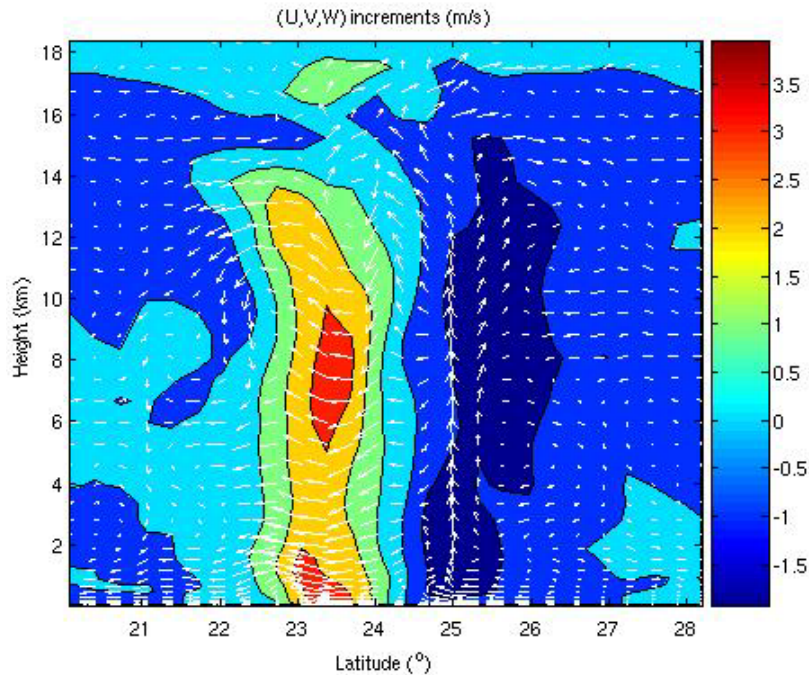
With assimilation



Experiments with WRF/DART

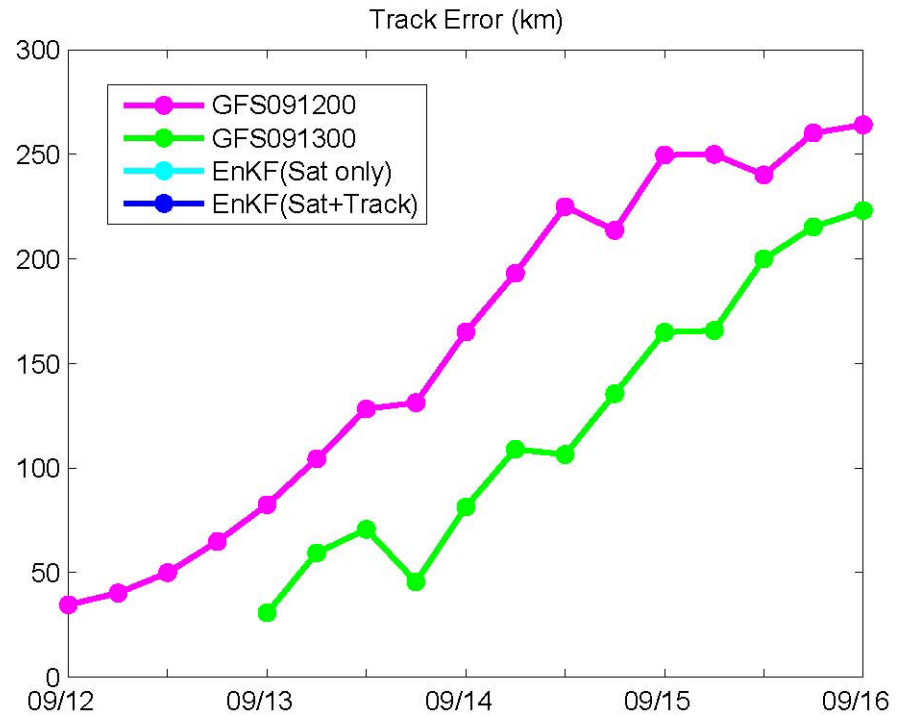
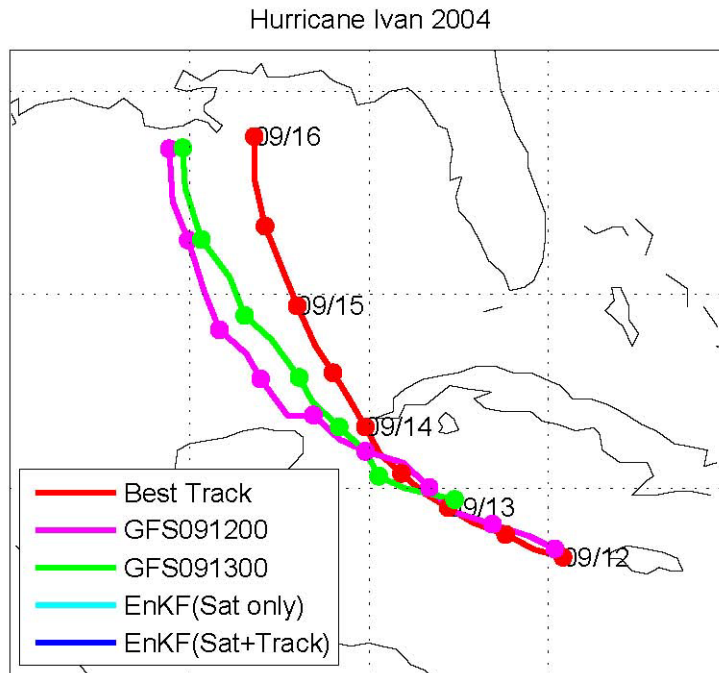
- **WRF** -- Weather Research and Forecasting model
- **DART** -- Data Assimilation Research Testbed
- 36 km horizontal resolution, 35 vertical levels
- 26/28 ensemble members
- Ensemble initial and boundary conditions are generated by perturbing GFS(AVN) analysis/forecast with WRF-VAR error statistics
- Assimilated observations:
 - hurricane track (center position and minimum sea level pressure from NHC advisories)
 - Satellite winds (3% available observations)
- Compare forecasts initialized from the EnKF mean analysis and from the GFS analysis

Position and intensity Correction



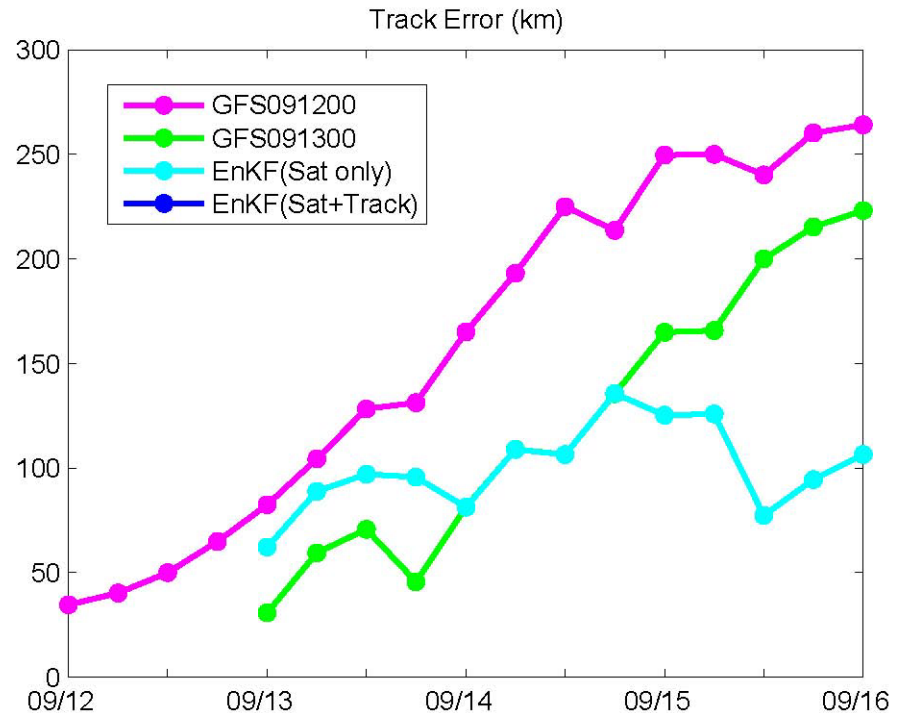
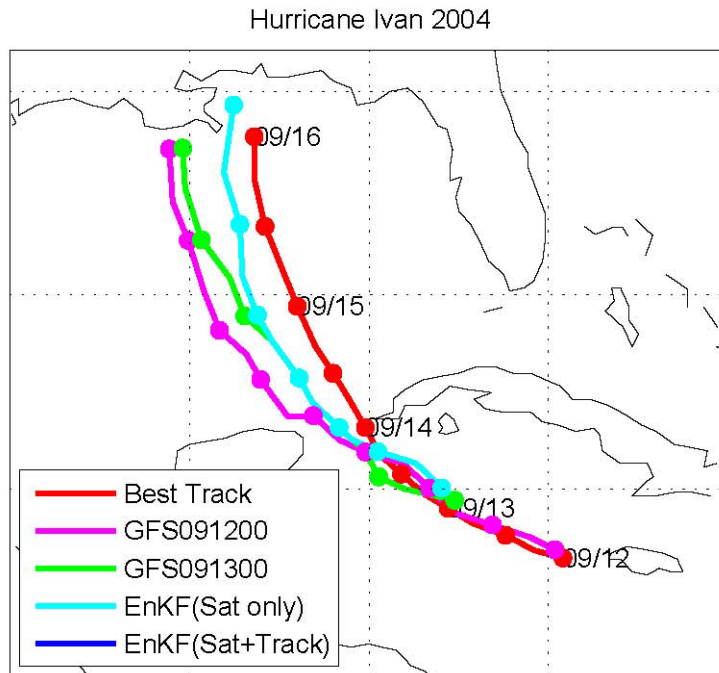
RITA 2005-09-20-23Z		Center Lat. (°N)	Center Lon. (°W)	Mini. SLP(mb)
Observation	(error)	24.00 (0.3)	-82.20 (0.3)	973.0 (5.0)
Prior mean	(spread)	23.85 (0.24)	-82.33 (0.23)	988.6 (2.0)
Posterior mean	(spread)	23.89 (0.15)	-82.29 (0.18)	986.5 (2.0)

Hurricane Ivan 2004



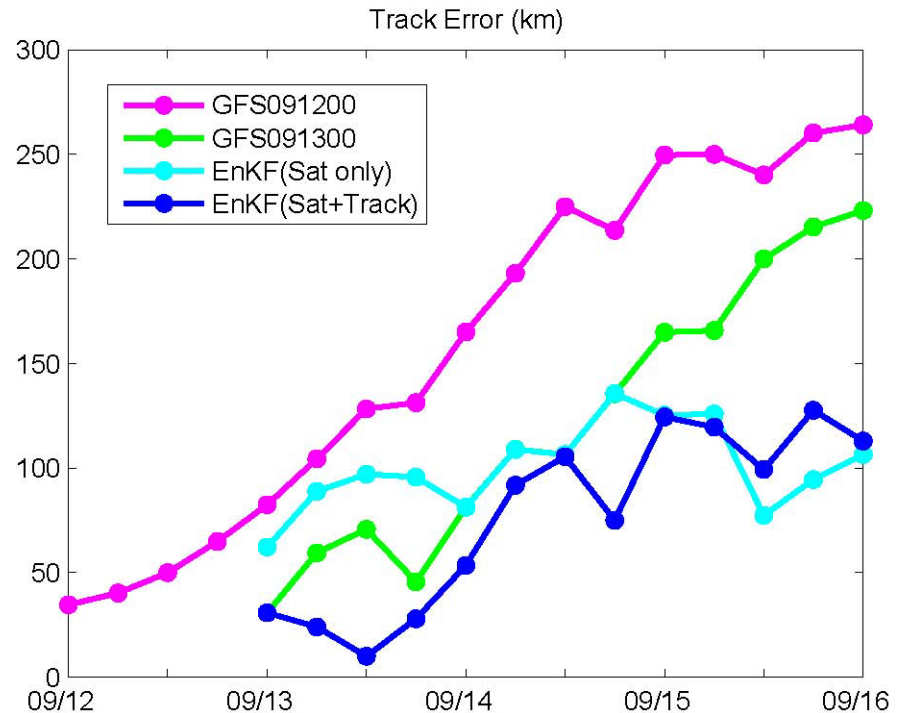
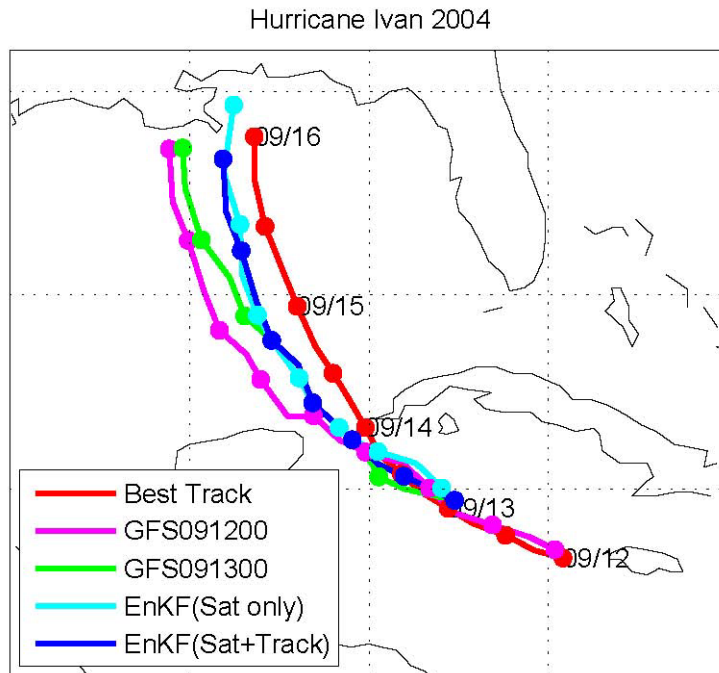
- 36-km horizontal resolution, 28 ensemble members
- Assimilate position, intensity and satellite winds every 3h for a total of 24h
- Compare forecasts initialized from the EnKF analysis and from the GFS analysis

Hurricane Ivan 2004



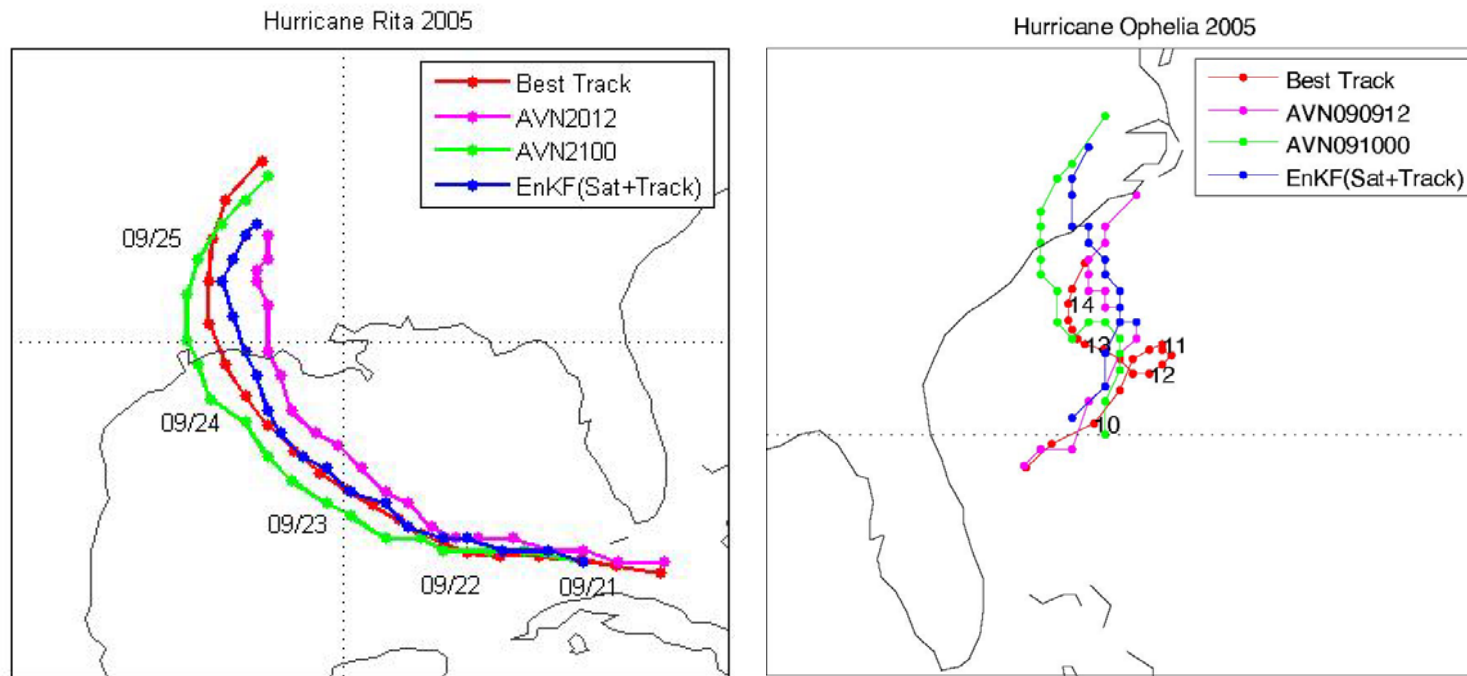
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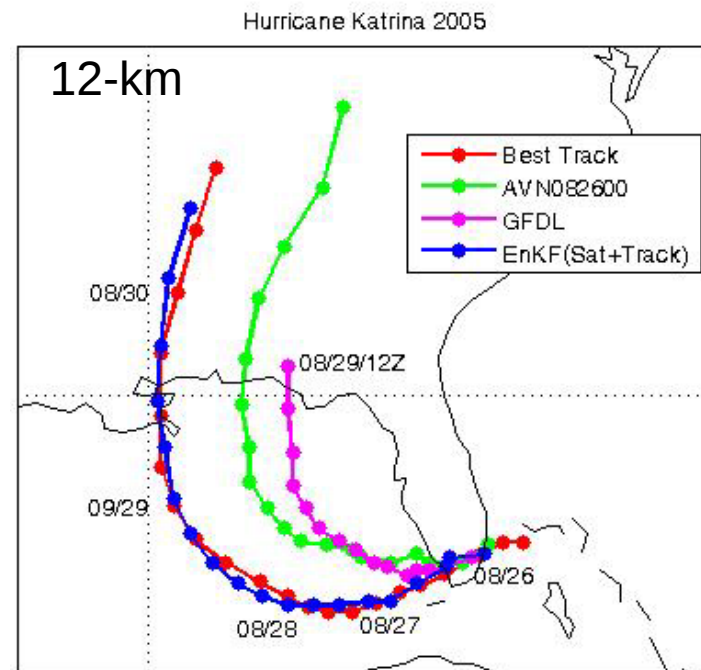
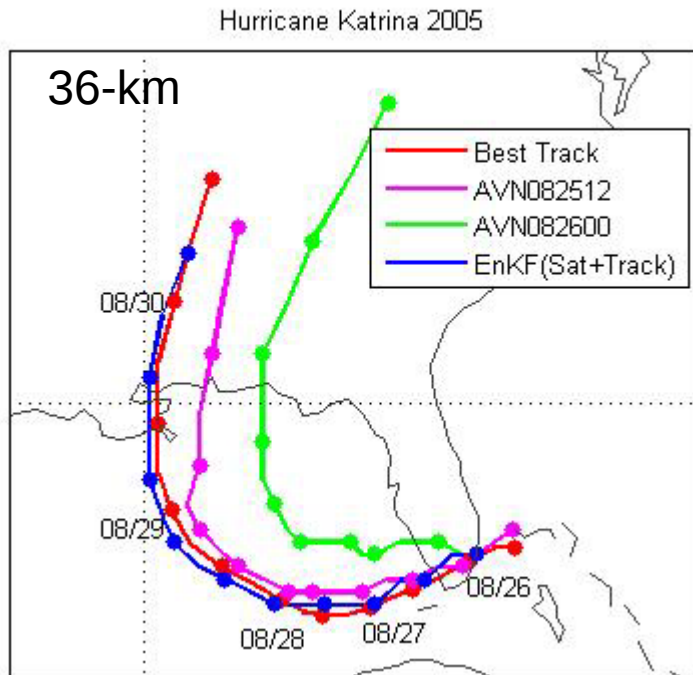
- 36-km horizontal resolution, 28 ensemble members
- Assimilate position, intensity and satellite winds every 3h for a total of 24h
- Compare forecasts initialized from the EnKF analysis and from the GFS analysis

Hurricane Rita and Ophelia 2005



- 36-km horizontal resolution, 26 ensemble members
- Assimilate position, intensity, and satellite winds every hour for a total of 12 hours
- Compare forecasts initialized from the EnKF analysis and from the GFS/AVN forecasts.

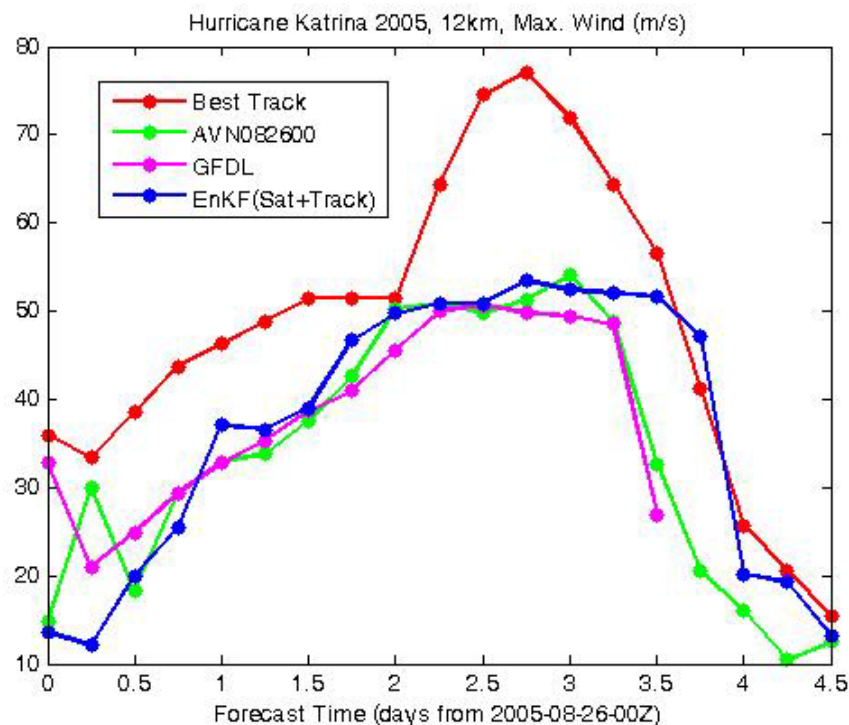
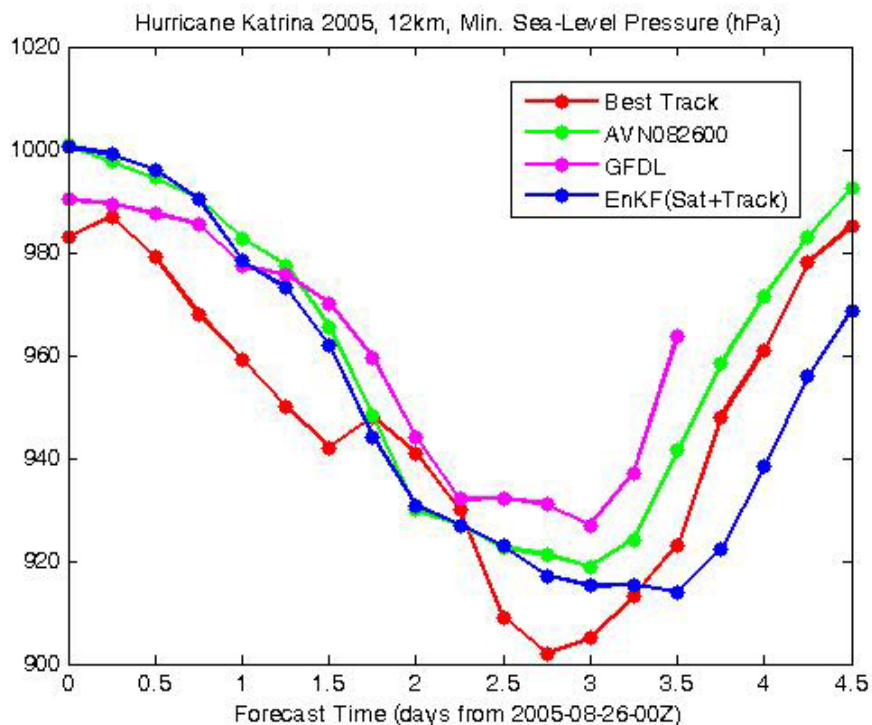
Hurricane Katrina 2005



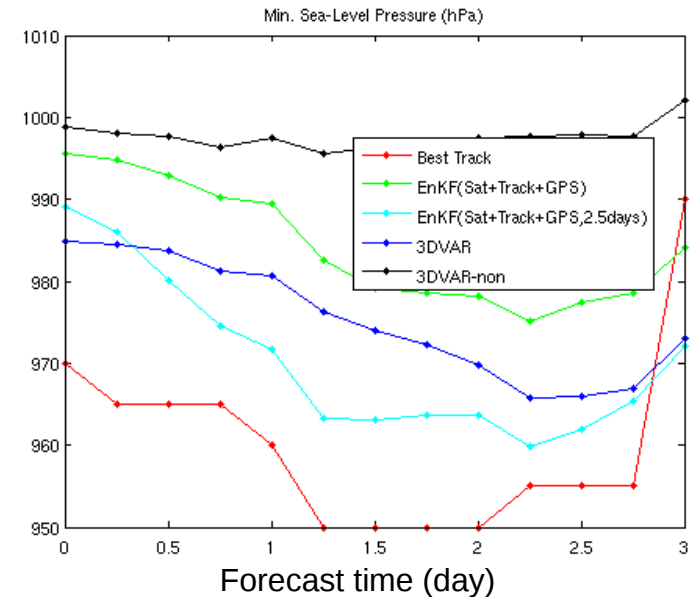
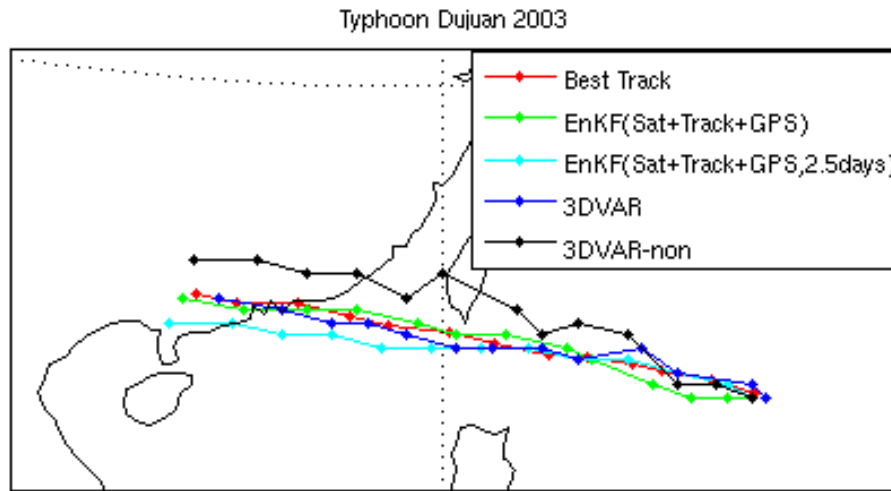
- Analysis:
 - 36-km horizontal resolution, 26 ensemble members
 - Assimilate position, intensity, and satellite winds every hour for a total of 12 hours
- Forecasts:
 - Compare forecasts initialized from the EnKF analysis, from the GFS/AVN forecasts and from GFDL analysis at 36-km and 12-km resolutions

Hurricane Katrina 2005

12-km forecast



Typhoon Dujuan 2003



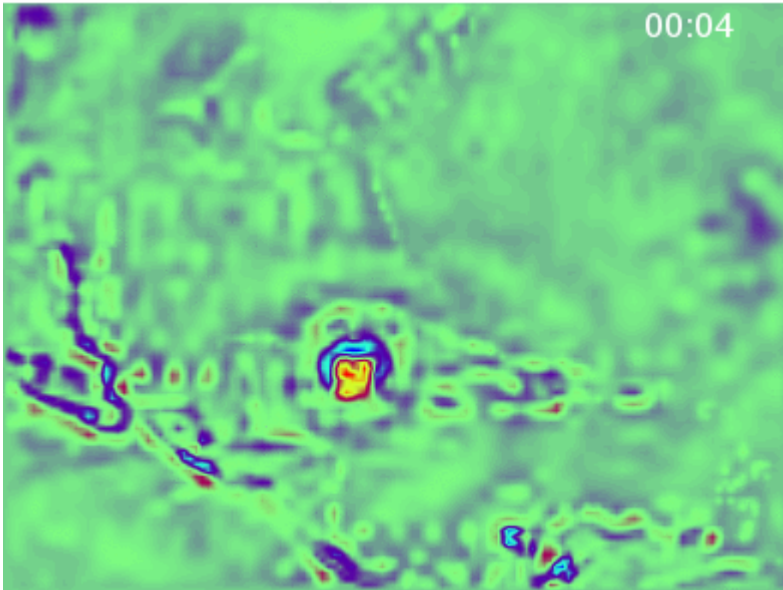
- 45-km horizontal resolution, 28 ensemble members
- Assimilate position, intensity, satellite winds, and GPS refractivity for 1 day or 2.5 days
- Compare forecasts initialized from
 - EnKF analysis
 - WRF 3DVAR analysis (3DVAR, cycling for 2.5 days)
 - GFS analysis (3DVAR-non)



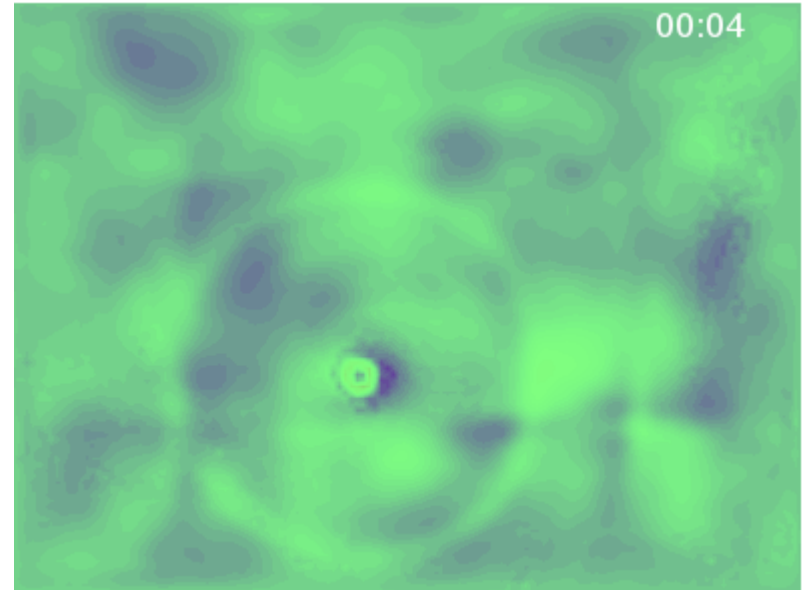
Vortex Spin-up

Hurricane Ivan 2004
Surface Pressure Tendency

GFS0913



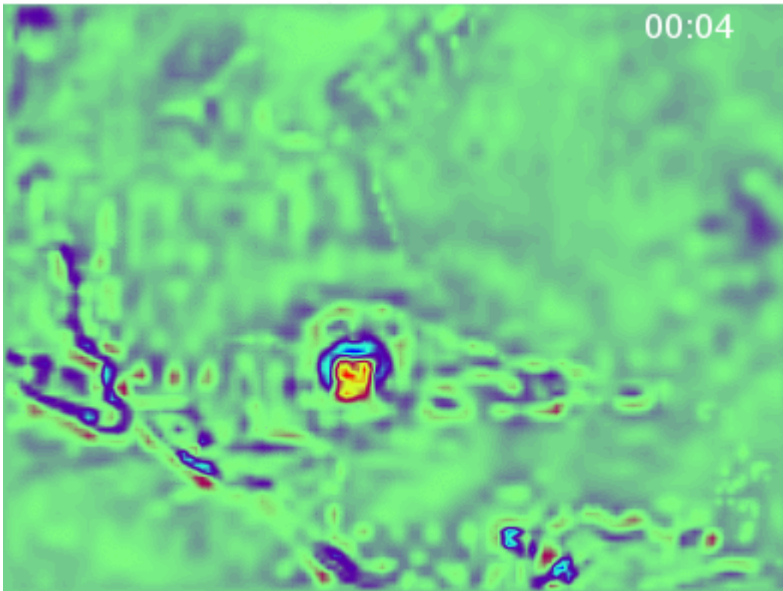
EnKF



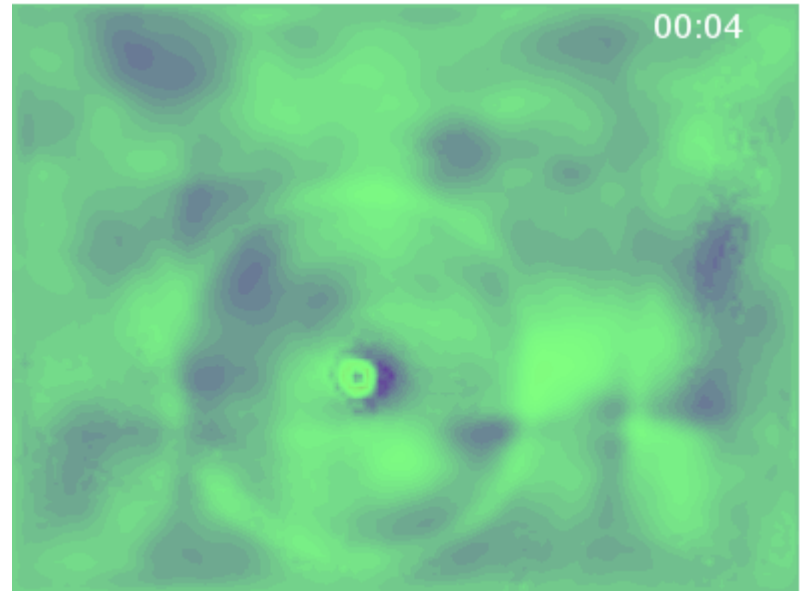
Vortex Spin-up

Hurricane Ivan 2004
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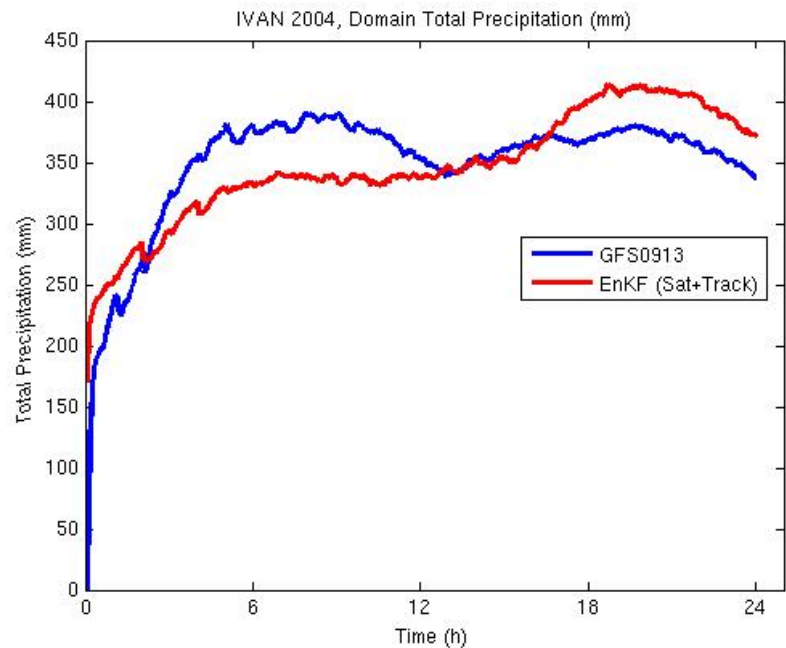
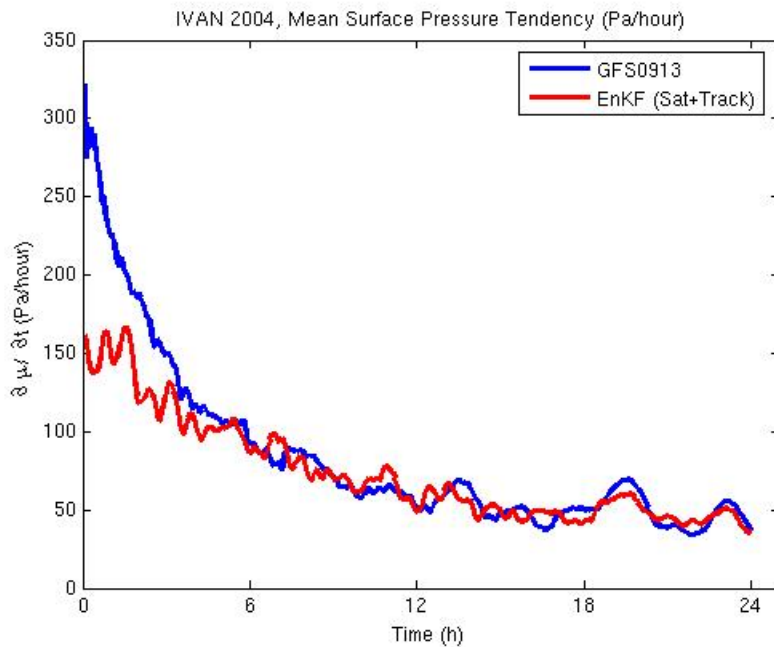


EnKF



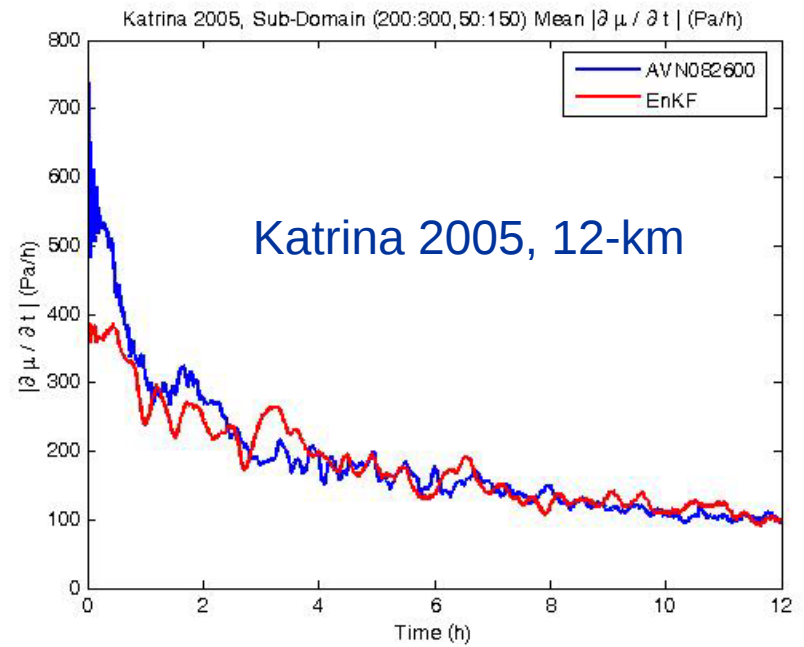
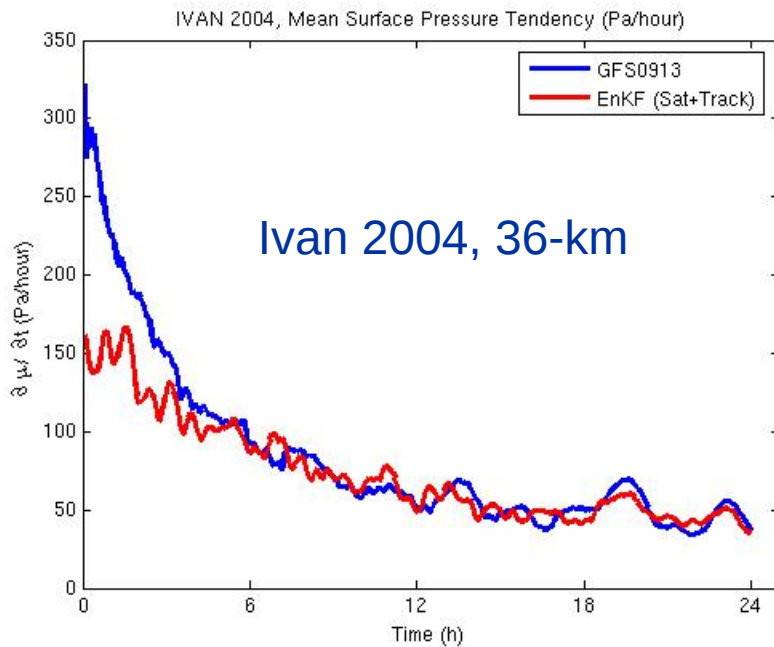
Vortex Spin-up

Hurricane Ivan 2004



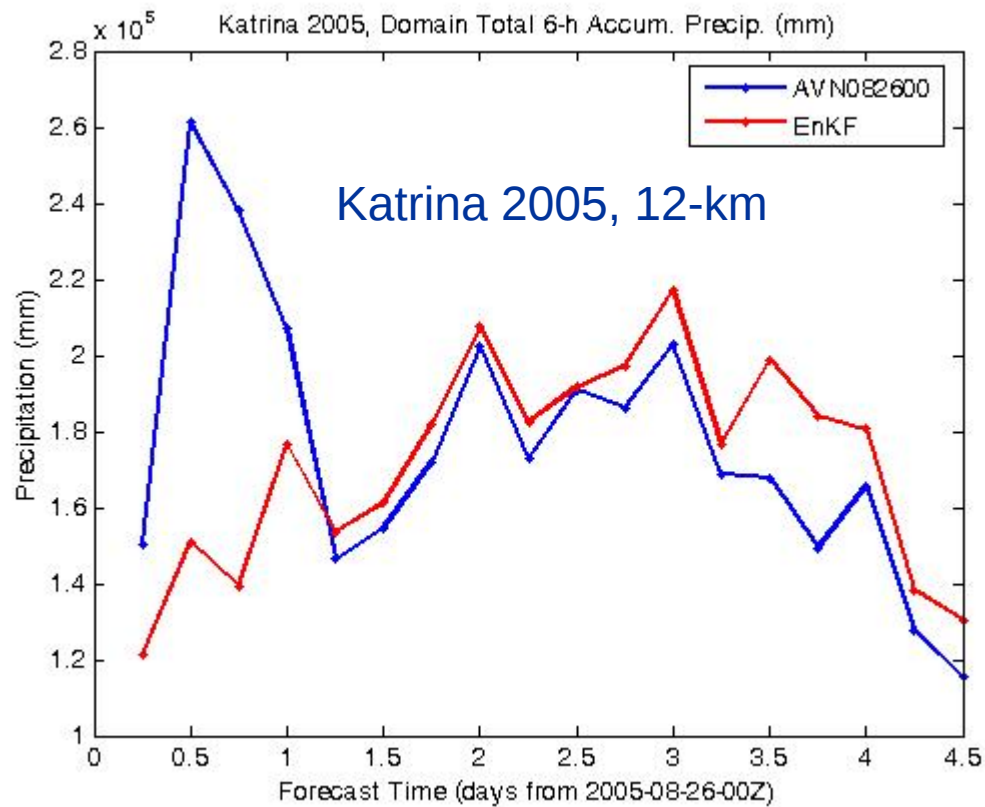
Vortex Spin-up

Mean Surface Pressure Tendency



Vortex Spin-up

6-h Accumulated Precipitation



Summary

- Hurricane track observations can be easily assimilated with an EnKF
- Track forecasts initialized from the EnKF analysis are significantly improved
- EnKF analysis produces dynamically consistent increments, and reduces spurious transient evolution of initial vortex