



# Evaluation of United Arab Emirates WRF two-way nested model on a series of thick coastal fog situations

## Ghantoot pile-up caused by thick fog on March 11th, 2008



Recently, on 11 March, early morning, a very thick fog occurred along the highway linking Dubai and Abu-Dhabi. At 06:00 local time (02:00 GMT), almost all the traffic stopped along the entire U.A.E. coasts reported less than 100 meters visibility. Such a situation is usually happening at this period of the year, but this time, it caused a horrific traffic accident killing and injuring many people and burning more than 200 vehicles.

This event, among multiple others, is denoting the great influence of weather phenomena in general and visibility drop as a particular most aggressive constraint for the economic and social activities in Emirates. The predictability of such phenomena is becoming among the first priorities.

The forecasts of fog occurrence, its extent, duration, and intensity are difficult practical because fog is a boundary layer phenomenon which generally shows large variability in time and space. As the boundary layer is driven and initially set up by the synoptic scale behavior, the forecast of fog is, to a first approximation, determined by the general circulation. However, fog occurrence is often governed by mesoscale features as determined by regional characteristics, and contributions from the boundary layer can diagnosis and predict. All of these interactions are taken into account inside the current WRF version through a set of planetary boundary layer physics schemes. But, the interactions may be complicated by microphysical processes within and outside fog patterns.

Every where in the world, fog prediction is a real challenge for any weather forecasting centre. The techniques used are generally depending on the local type of weather, climatology of the region, type of fog and geographical specificities. The experience of the local forecaster is generally central and beneficial when dealing with local and specific phenomena. But nowadays, scientific improvements in numerical weather prediction models made them very helpful in depicting even very small and delicate weather activities. These improvements are made especially at the levels of physics parameterizations, initialization methods and grid resolution.

United Arab Emirates Weather Centre is relying on WRF model for almost all its forecasting needs. The operational characteristics of such system are detailed in Ajaiji and Al-Katheri, 2007. UAE/WRF is making its own data assimilation based on the three dimensional variational analysis using the technique of First Guess at Appropriate Time (FGAT) and taking benefit of a large number of local observations not transrating through the GTS. FGAT is very helpful in dealing with fog prediction because it takes benefit of the information coming from frequently reported observations like METAR and RADAR. Observation nudging could also be turned on in conjunction with 3D-VAR.

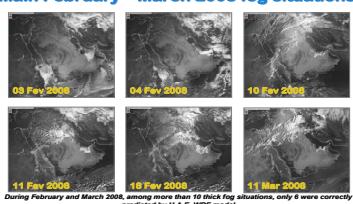
A series of sensitivity experiments based on this system are conducted in this study to assess the quality of UAE/WRF when dealing with fog and visibility drop predictions. This includes visibility drop due to dust load which is another common feature of U.A.E. weather and whose prediction performed actually using a dust model based on stochasticic evol.

The experiments are designed to test the impact of each ingredient among the existing options in the WRF version 3 package related to physics parameterizations (Nine microphysics schemes, four shortwave and long wave radiation schemes, three planetary boundary layer schemes and four land-surface models), horizontal resolution (nested 40 km, 13.3 km, 4.4 km and 1.4 km), vertical resolution (38, 45 and 60 Eta hybrid levels), assimilation techniques (cold start using GFS analysis, warm start using FGAT, cold start with nudging). Some new WRF options, which were released with the recent version 3, are also tested like Pleim and Xiu physics options; dynamic time stepping and digital filter initialization.

The experiments are concerning only one fog situation having occurred on early 11 March 2008. But the best combination found for the above mentioned configurations is tested on six other fog cases.



## Main February – March 2008 fog situations



During February and March 2008, among more than 10 thick fog situations, only 6 were correctly predicted by UAE/WRF model

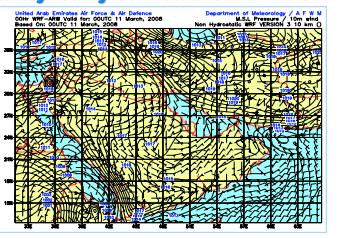
## U.A.E. WRF model characteristics

WRF 2.2	Domain 1	Domain 2	Domain 3	Resolution
Grid dimensions	40 km	13.33 km	4.4 km	1.4 km
Latitudes	25°N	25°N	25°N	25°N
Longitudes	55°E	55°E	55°E	55°E
Time step	22 s	70 s	28 s	FGAT
Micro-physics	Fitter	Fitter	Fitter	Bouarfa physics Initial and Boundary Conditions
Cumulus scheme	Kalman-Fritsch	Kalman-Fritsch	Explicit	Noah LSM RRTM Duffield RRTM Duffield
Turbulence	Two-way	Two-way	Two-way	RD-WRF RD-WRF RD-WRF
WRF-VAR	WRF-VAR version 2.2			Two-way Two-way Two-way
Notes				WRF-VAR is operated by UAE Air Force & Air Defense since August 2006

Model	Middle-East
Region	Arabian Peninsula
Country	United Arab Emirates
Version	WRF-VAR version 2.2
Notes	Confined on Ghantoot introduced only 91 x 91 x 28 with 1.4 km

WRF-VAR is operated by UAE Air Force & Air Defense since August 2006

## Fog situation of 11 March 2008 analyzed by UAE/WRF 3DVAR-FGAT



## Experimental Design



Description of the WRF 3 hours forecasts examining the impact of planetary boundary layer physical (PBL), RRTM/Dudhia and Radiation (RAD), CAM, GFS, etc.

Description of the WRF 3 hours forecasts examining the impact of surface radiative transfer (RAD) and the extinction coefficients ( $\beta_{ext}$  km<sup>-1</sup>)

NOAH / FSL Visibility

$VIS (miles) = 6000 \cdot \frac{T - T_f}{\beta_f}$

Visibility is an empirical function of temperature, dew point temperature and relative humidity

Adopted 3D-VAR FGAT Cycling type

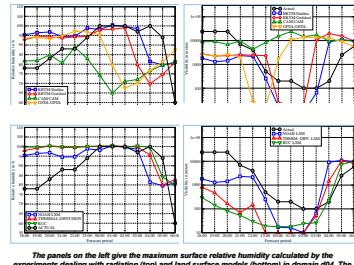
6 hourly 3D-Var Forecast

6 hourly 3D-Var Forecast

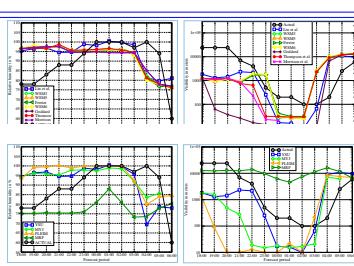
6 hourly 3D-Var Forecast

6 hourly 3D-Var Forecast

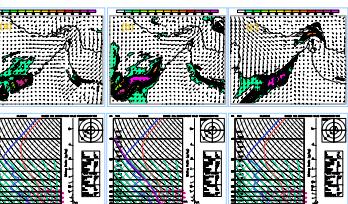
## Results



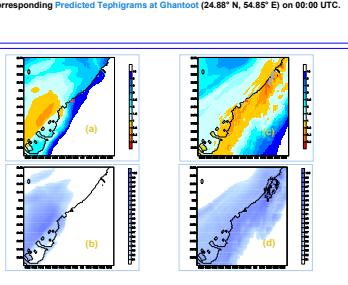
The panels on the left give the maximum surface relative humidity calculated by the experiments dealing with radiation (top) and land surface models (bottom) in domain d04. The panels on the right give the minimum visibility.



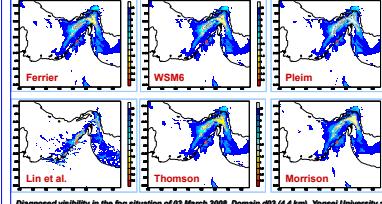
The panels on the left give the maximum surface relative humidity calculated by the experiments dealing with micro-physics (top) and planetary boundary layer (bottom) in domain d04. The panels on the right give the minimum visibility.



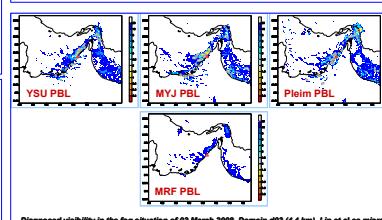
Surface relative humidity predicted by WRF model at 01:00 UTC, when using a) GFS analysis, b) GFS analysis with 3 hours nudging, 3DVAR-FGAT at warm start, with the corresponding Predicted Tephigrams at Ghantoot (24.88°N, 54.85°E) on 00:00 UTC.



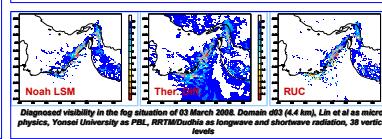
Cloud fraction (contoured) and visibility (shaded) calculated by FSL model: a) the operational and c) by the modified run. Surface relative humidity (shaded) and cloud water mixing ratio (contoured) predicted by b) the operational run, and d) the modified run. The red triangle shows Ghantoot location.



Diagnosed visibility in the fog situation of 03 March 2008, Domain d03 (4.4 km), Yonsei University as PBL, Noah as LSM, RRTM/Dudhia as longwave and shortwave radiation, 38 vertical levels



Diagnosed visibility in the fog situation of 03 March 2008, Domain d03 (4.4 km), Lin et al as micro-physics, Yonsei University as PBL, RRTM/Dudhia as longwave and shortwave radiation, 38 vertical levels



Diagnosed visibility in the fog situation of 03 March 2008, Domain d03 (4.4 km), Lin et al as micro-physics, Yonsei University as PBL, RRTM/Dudhia as longwave and shortwave radiation, 38 vertical levels

## Summary

This study tested a series of scientific options offered by WRF version 3 having an influence on fog predictability. These options comprise the entire physics alternatives especially at the levels of microphysics, planetary boundary layer, shortwave and longwave radiation, surface layer model. The impact of different vertical and horizontal resolutions was also fetched. Different initialization methods using cold start, cold start with nudging and warm start with first guess at appropriate time, were examined. The series of experiments conducted are dealing with a thick fog case study which took place on late night of 10 March 2008 and covered the major south western coastal parts of U.A.E.

The main results obtained are summarized as it follows:

1. Planetary boundary layer physics and land surface models play a key role in fog depiction. The most reliable options in the context of U.A.E. region are Yonsei University for PBL and Noah for LSM.
2. Shortwave and longwave radiation affect also the fog occurrence. Rapid Radiative Transfer Model as longwave and Dudhia as shortwave are the best. Goddard shortwave lead also to good results.
3. Almost all the microphysics schemes are valid, but Lin et al. scheme presents more satisfactory fog predictability potential.
4. Horizontal resolution does not affect the fog occurrence, but it is important to have a fine resolution for fog depiction.
5. Using GFS analyses as initial states for the model give bad results if the spinup period is short. When using a GFS initial state, the local phenomena like fog occurrence are well reproduced on a GFS initial state, but its efficiency depends on the frequency and relevance of the observations used in the nudging, as well as on cut-off nudging period. 3DVAR-FGAT with a warm start model is the best, it features the advantages of nudging, but it incorporates the different sources of information in a more complicated and coherent way permitting the creation of small scales features inside the analysis. These small scales are crucial in positioning subsequently the fog patterns accurately and orienting the forecast model for well predicting their intensity.

ACKNOWLEDGMENT  
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