

Impact of AIRS data over the Antarctic region

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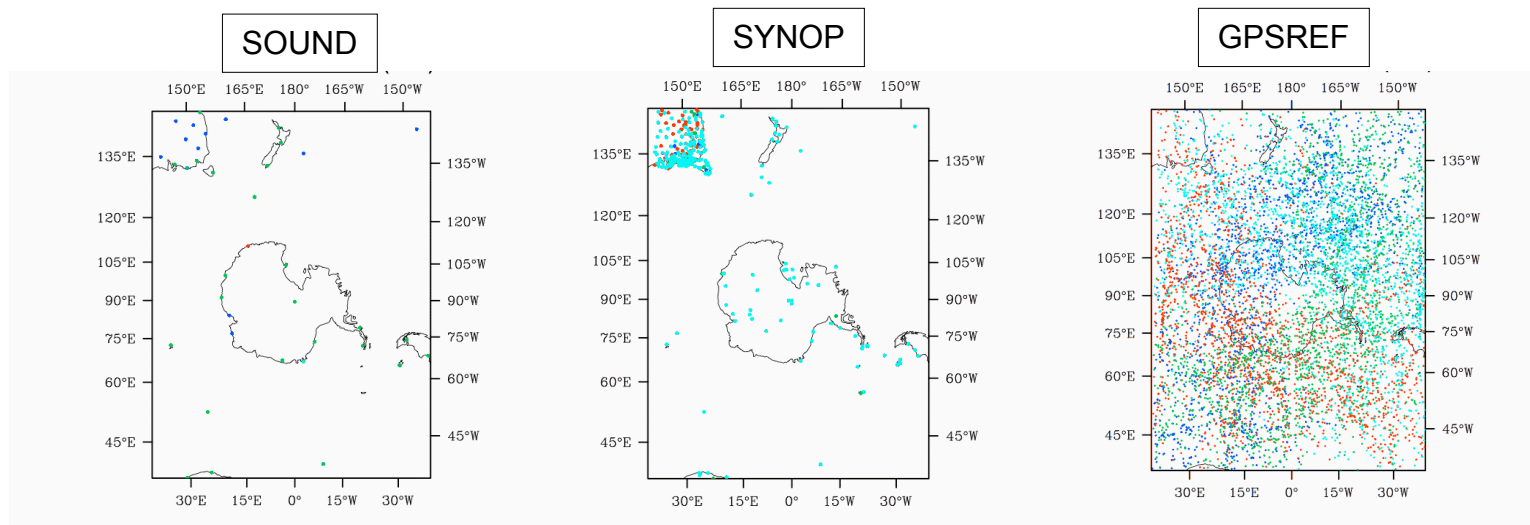
Introduction: AMPS

The Antarctic Mesoscale Prediction System (AMPS)

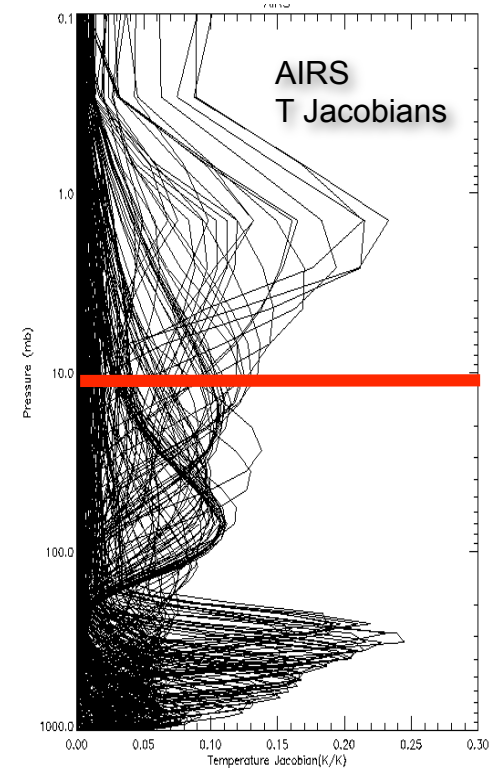
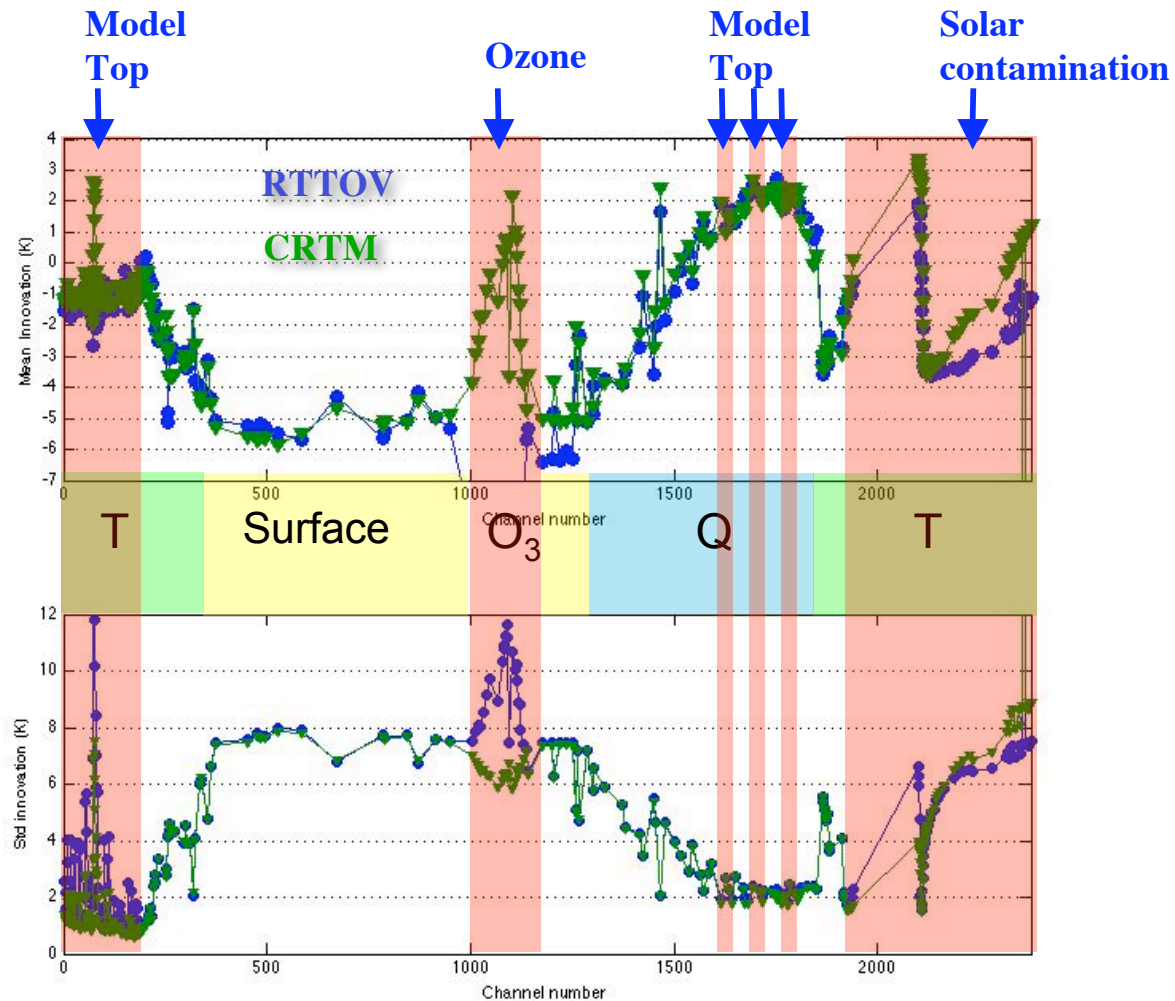
- Real-time, experimental NWP modeling capability for Antarctica
- Purposes: Support of weather forecasting and scientific activities

WRF-Var (3DVar)

- Specific Background Error Covariances
- Lateral Boundary Conditions from FNL



AIRS innovations: Channel Selection



AIRS innovations: QC & Thinning

- Pixel-level QC

- Reject **limb** observations
- Reject pixels over **land** and **sea-ice**

- NESDIS Cloud detection

- LW window channel > 271K
- Thresholds on model SST minus SST from 4 AIRS LW channels

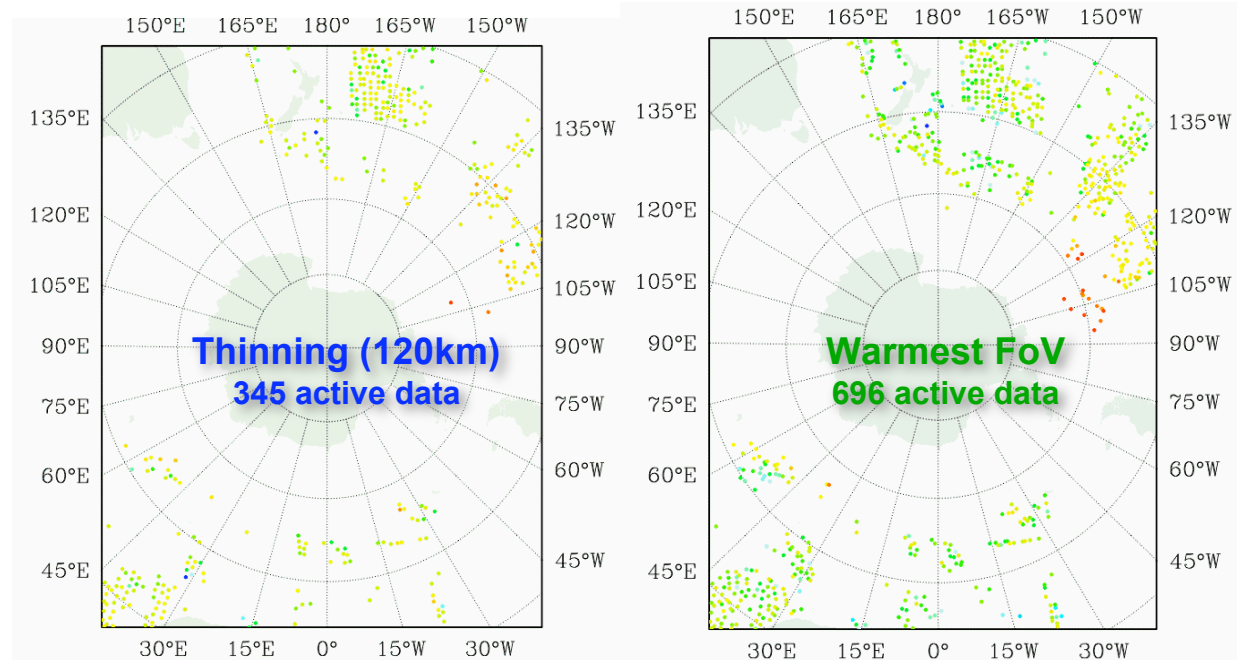
- Channel-level QC

- **Gross check** (innovations < 15 K)
- **First-guess check** (innovations < $3\sigma_0$). Error factor tuned from objective method (Desrozier and Ivanov, 2001)

- Imager AIRS/VIS-NIR

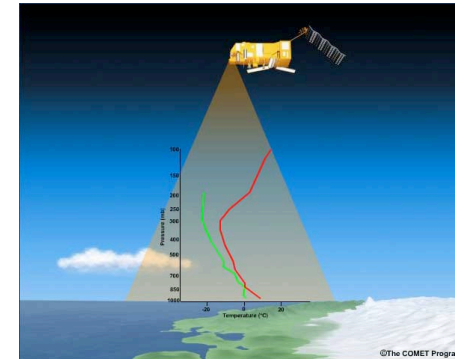
Day only (cloud coverage within AIRS pixel < 5%)

- Thinning

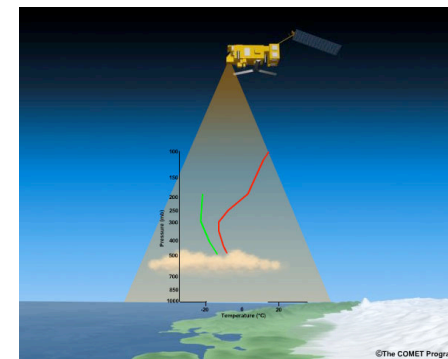


AIRS innovations: Cloud detection strategy

From « **hole hunting** »
(identifying clear pixels)...



... to **identifying clear channels**
(insensitive to the cloud).



Cloud Detection: MMR scheme

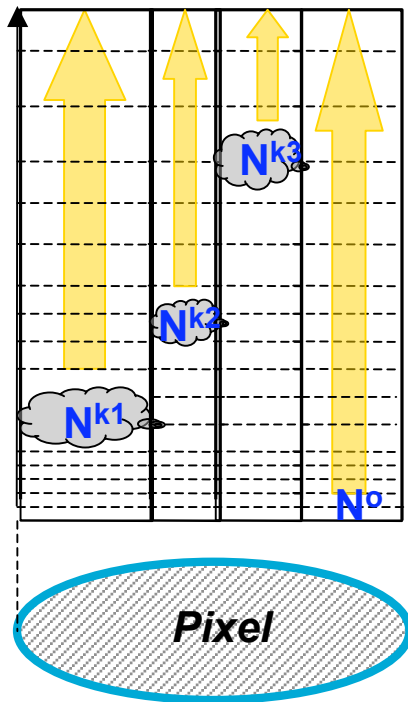
RTM { R_v° = Radiance calculated in **clear sky**
 $R_v^{\bullet k}$ = Radiance calculated for **overcast black cloud** at level k

Minimum Residual:

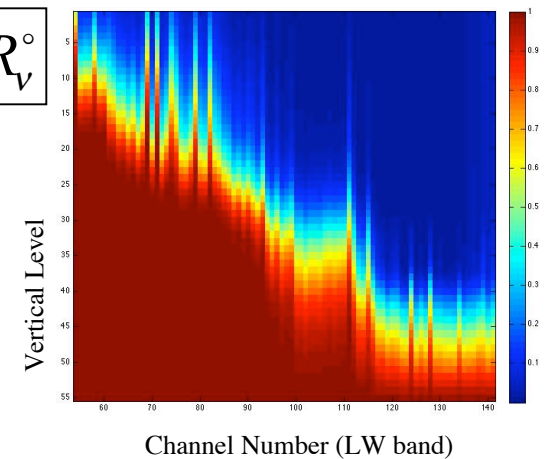
$$R_v^{Cld}(N, k) = (1 - N)R_v^\circ + NR_v^{\bullet k}$$

Multivariate Minimum Residual (MMR):

$$R_v^{Cld}(N^\circ, N^1, \dots, N^n) = N^\circ R_v^\circ + \sum_{k=1}^n N^k R_v^{\bullet k}$$



$$R_v^{\bullet k} / R_v^\circ$$

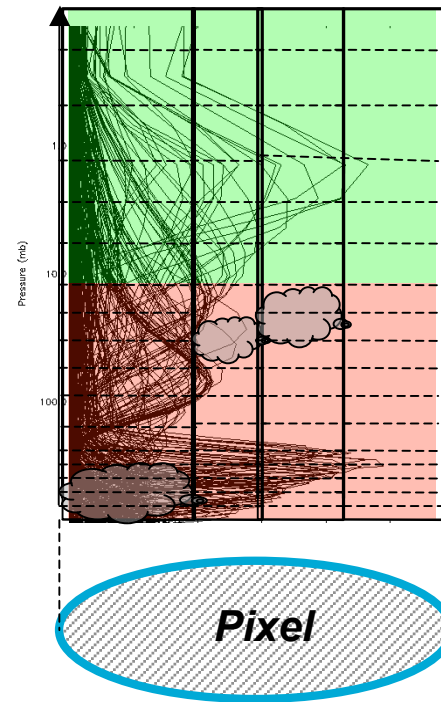
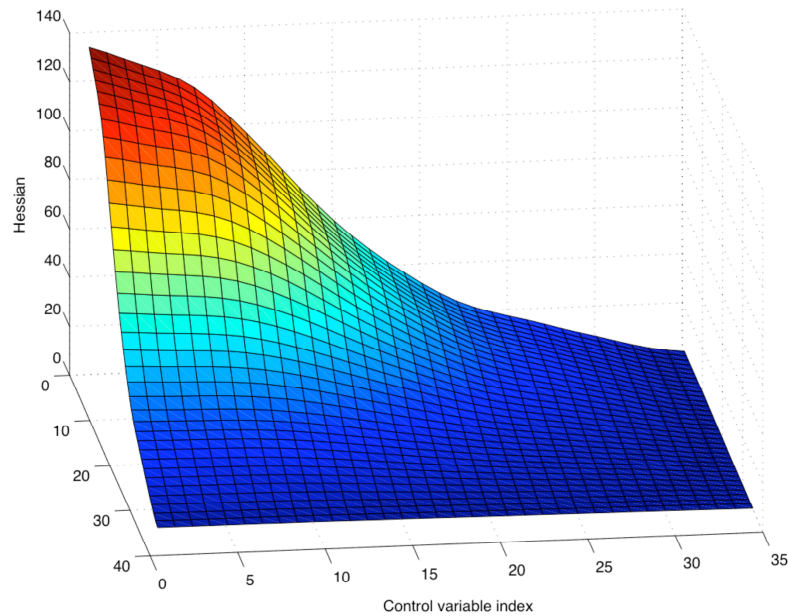


Cloud Detection: MMR scheme

$$R_v^{Cld} = N^{\circ} R_v^{\circ} + \sum_{k=1}^n N^k R_v^{\bullet k}$$

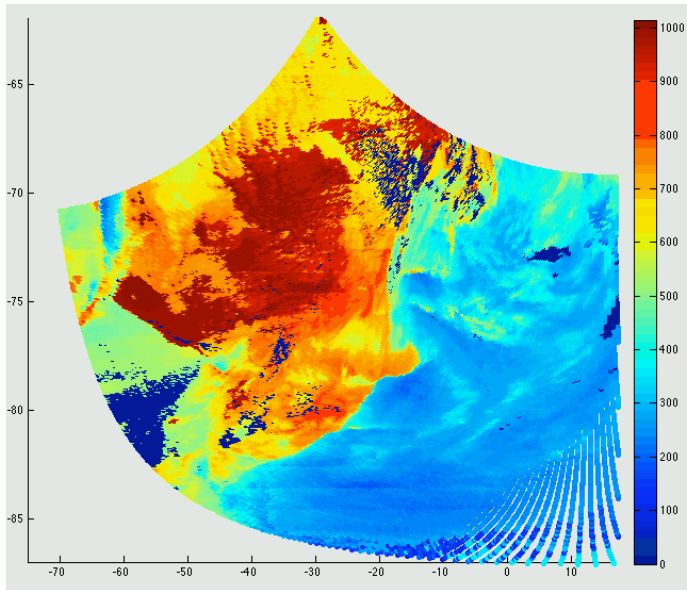
Cloud fractions N^k are adjusted **variationally** to fit observations:

$$J(N) = \frac{1}{2} \sum_v \left(\frac{R_v^{Cld} - R_v^{Obs}}{R_v^{\circ}} \right)^2 \quad \text{with} \quad \begin{cases} 0 \leq N^k \leq 1 \\ N^{\circ} + \sum_{k=1}^n N^k = 1 \end{cases}$$

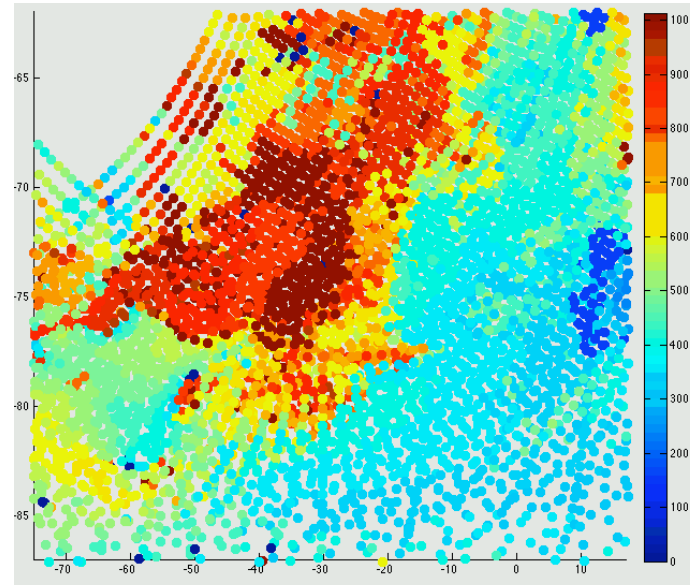


Cloud Detection: Initial Validation

Cloud Top Pressure (hPa)



MODIS Level 2 Product

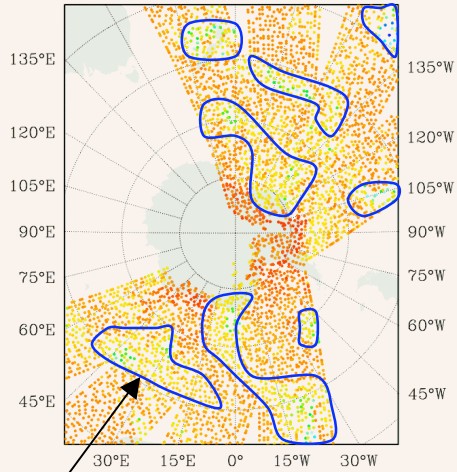


AIRS MMR

Perspective: Cloudy Radiances

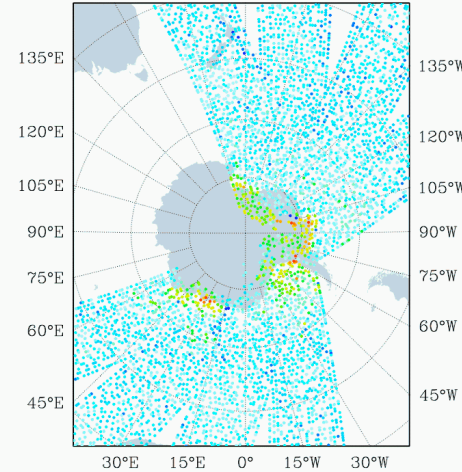
Innovations: $R_v^{Obs} - R_v^o$

meanDN 4.78 2006100100
150°E 165°E 180° 165°W 150°W



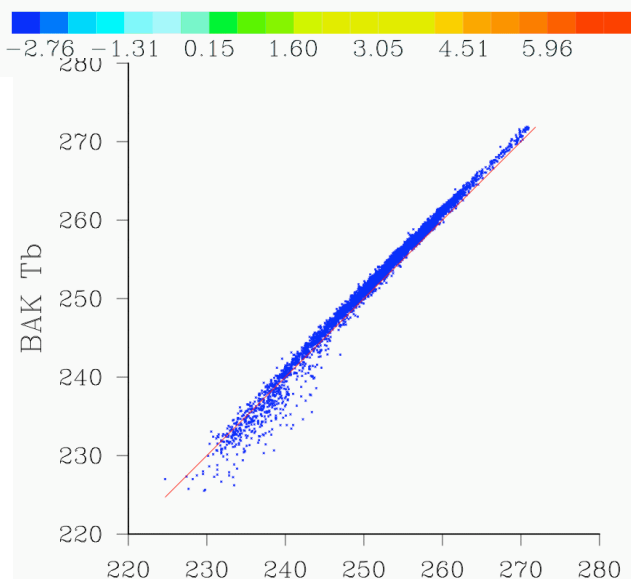
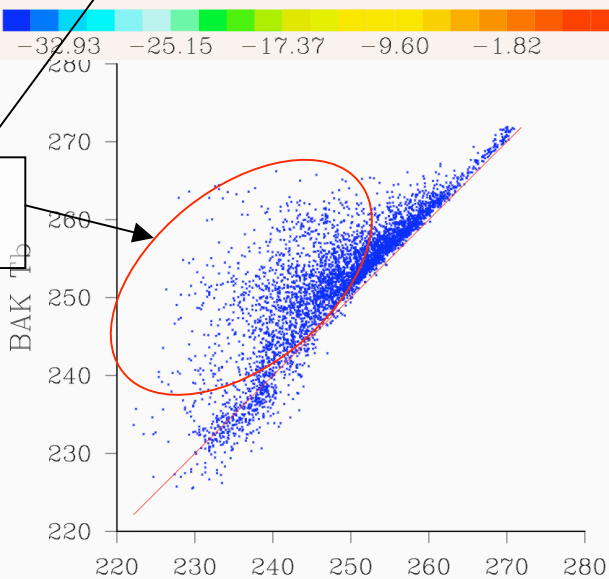
« Retrieved » Innovations: $R_v^{Obs} - R_v^{Cld}$

mean*F 1.04 2006100100
150°E 165°E 180° 165°W 150°W



Innovations
for AIRS
Channel #787
(surface)

Cloud
Contamination



Bias Correction: Variational Bias Correction

Modeling of errors in satellite radiances:

$$y = H(x_t) + B(\beta) + \varepsilon$$

{

$\langle \varepsilon \rangle = 0$

$B(\beta) = \sum_{i=1}^N \beta_i p_i$

Parameters

Predictors:

- Offset
- scan, scan², scan³

Bias parameters can be estimated within the **variational assimilation**, jointly with the atmospheric model state (Derber and Wu 1998) (Dee 2005) (Auligné et al. 2007)

Inclusion of the bias parameters in the control vector : $x^T \rightarrow [x, \beta]^T$

J_b: background term for x

J_o: corrected observation term

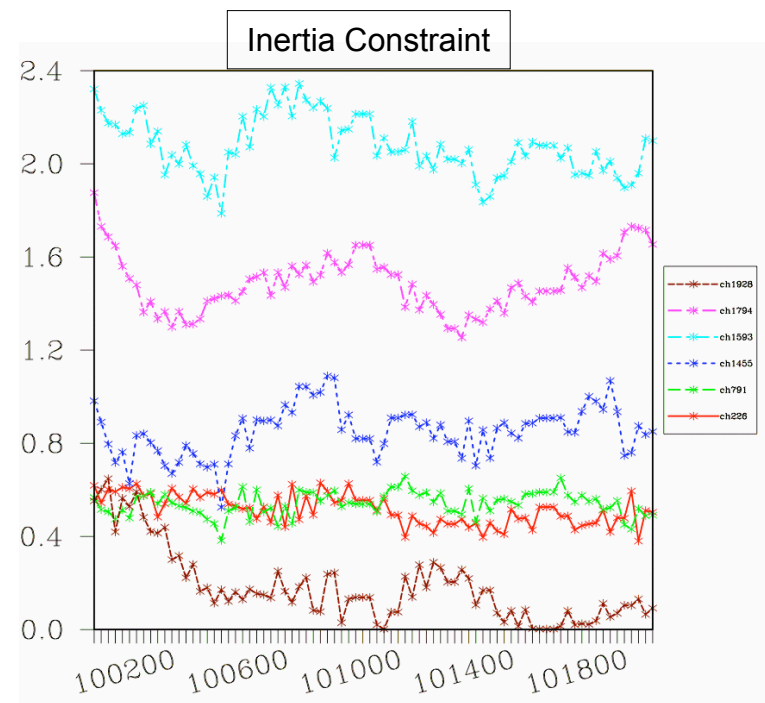
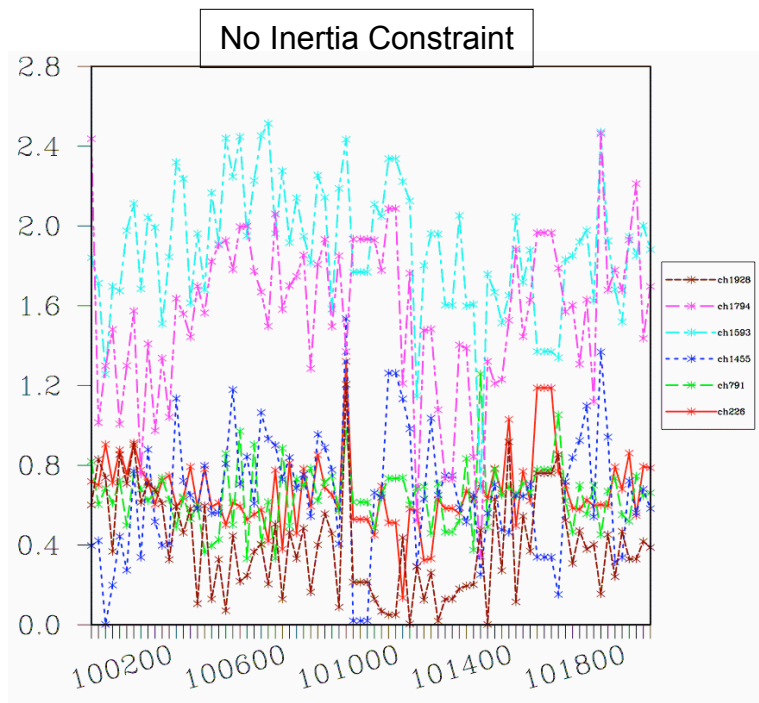
$$\begin{aligned}
 \mathbf{J}(x, \beta) = & \underbrace{(\mathbf{x}_b - \mathbf{x})^T \mathbf{B}_x^{-1} (\mathbf{x}_b - \mathbf{x})}_{\text{background term for } x} + \underbrace{[\mathbf{y} - H(\mathbf{x}) - B(\beta)]^T \mathbf{R}^{-1} [\mathbf{y} - H(\mathbf{x}) - B(\beta)]}_{\text{corrected observation term}} \\
 & + \underbrace{(\beta_b - \beta)^T \mathbf{B}_\beta^{-1} (\beta_b - \beta)}_{\text{background term for } \beta}
 \end{aligned}$$

J_β: background term for β

«Optimal » bias correction
considering all available information

Bias Correction: VarBC Timeseries

Time evolution of Offset bias parameter for various AIRS channels



Inverse Modeling: Adjoint Parameter Estim.

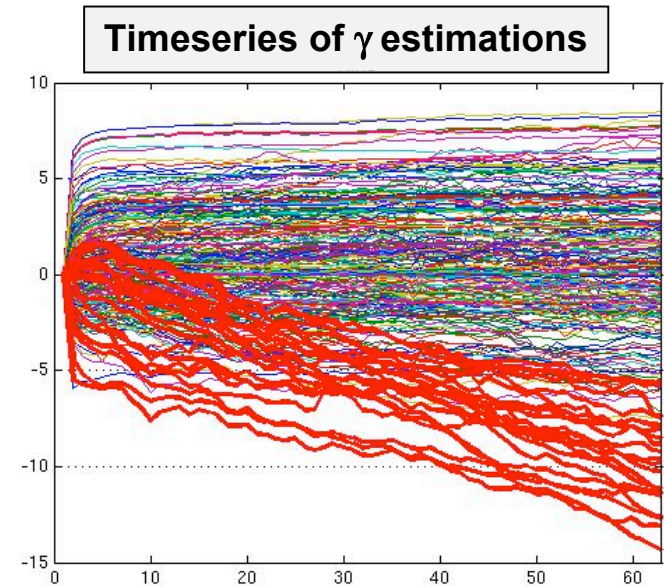
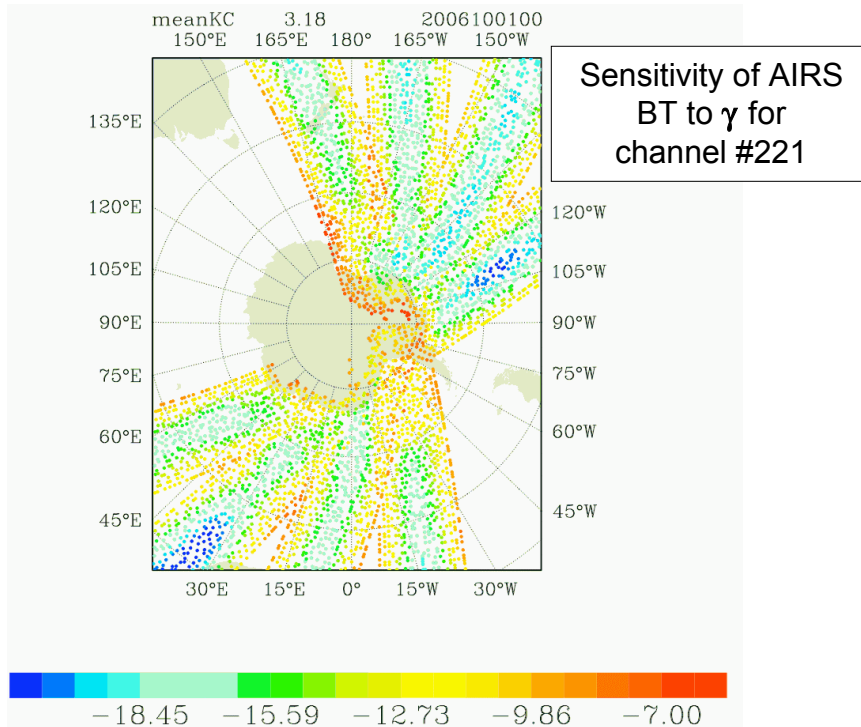
$$R_v^{atm} = \int_{z_0}^{\infty} B_v(T(z)) \left[\frac{d\tau_v(z, \theta)}{dz} \right] dz$$

$$\tau_v(z_1, \theta) = \exp\{-\gamma_v \sec \theta \int_{z_1}^{\infty} k_v(z) c(z) \rho(z) dz\}$$

B = Planck function
τ = transmittance
T = temperature
θ = incident angle
z = altitude coordinate
k_v = absorption coefficient
c = mixing ratio
P = atmospheric density

γ modulates atmospheric absorption to compensate for:

- poor knowledge of gas concentrations (CO₂, ...)
- errors in definition of ISRF
- errors in mean absorption coefficient

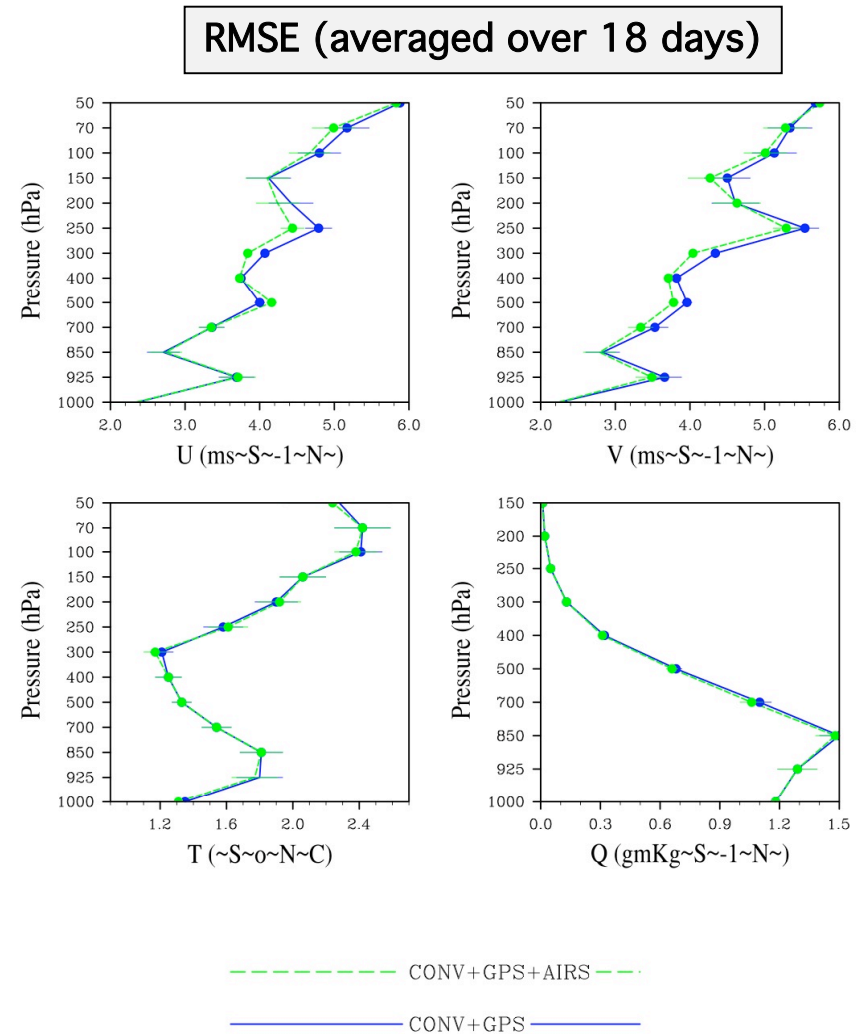


Auligné (2007)

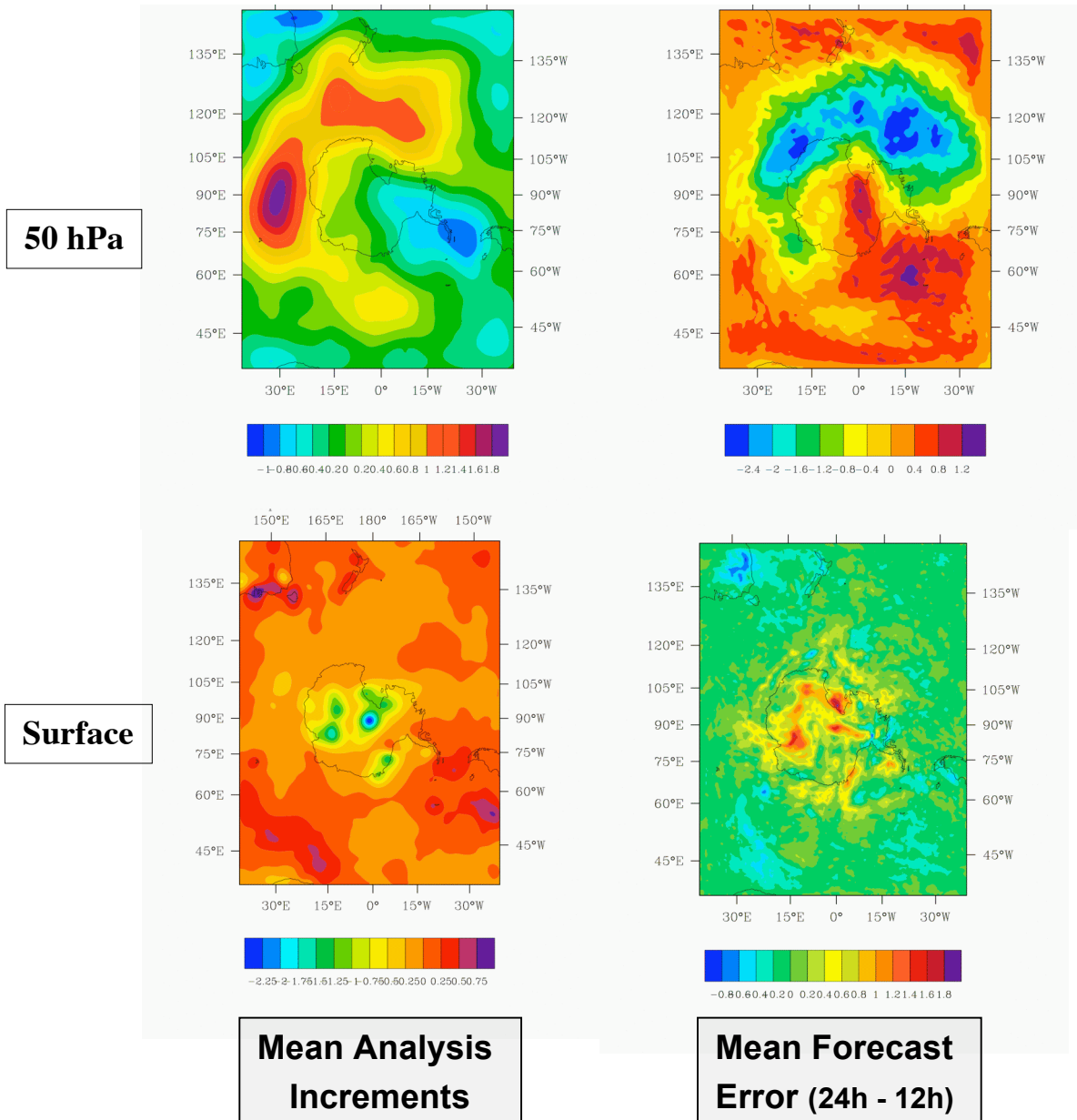
AIRS Impact: 36h Forecast vs. Radiosondes

Initial assessment of AIRS impact:

- 60km horizontal resolution
- 50hPa model top
- 6-hourly cycling with WRF 3DVar
- Period = 01-19 Oct 2006
- CTRL Expt = Conventional Data + COSMIC GPS refractivity
- AIRS Expt = CTRL + AIRS radiances
- Radiance thinning = 120km
- No radiance over land / snow / sea-ice



Major limitation: Systematic model error



Conclusions and future work

- **Encouraging results**
 - Initial test with conservative implementation
 - Neutral impact, slightly positive on wind forecast
- **Short-term improvements**
 - Raise model top
 - Use more AIRS channels
 - Improved estimation of surface emissivity over land
- **Longer-term developments**
 - Compare with impact of retrievals
 - Address systematic model errors
 - Assimilate cloud-contaminated radiances