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Introduction

The current operational configuration of the 3-km HRRR features an hourly update cycle based on a downscaled RAP initialization and a one-hour pre-forecast. Afterward, 3D hybrid EnVar data assimilation is conducted, followed by a free forecast. However, a wealth of observational data exists at sub-hour intervals, including aircraft and METAR observations, available every minute. To evaluate the advantage of assimilating these data, the HRRR was run for three days in a 15-minute DA update cycle during the one-hour pre-forecast, for 3D and 4D hybrid EnVar. Forecasts from these experiments were then compared to those produced with the hourly data assimilation configuration.

Employed Data Assimilation Methods

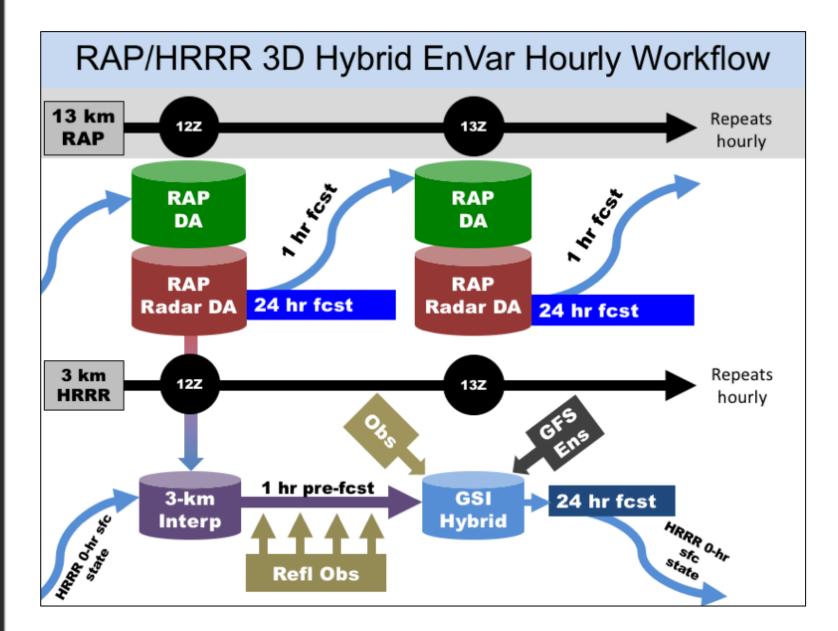
- > Hourly 3D Hybrid EnVar: Data assimilation is conducted using an observation window of 30 minutes on either side of the hourly analysis period, with all observations considered to occur at one time. The covariance matrix is constructed in a hybrid manner, with 75% coming from one forecast of the 80-member GFS ensemble and 25% coming from static, isotropic background covariance based on model statistics.
- Sub-Hourly 3D Hybrid EnVar: Data assimilation is conducted using an observation window of 12 minutes on either side of each 15-minute analysis period, with all observations considered to occur at one time. The covariance matrix calculation is identical to that used in the hourly 3D hybrid EnVar.
- Sub-Hourly 4D Hybrid EnVar: Data assimilation is conducted by incorporating three time levels (separated by 15 minutes) with observation windows of 7.5 minutes on either side of each time level. Observations are considered to occur at one of these three times. The covariance matrix calculation is identical to that used in the hourly 3D hybrid EnVar, except that three matrices are computed from different forecasts of the 80-member GFS ensemble.

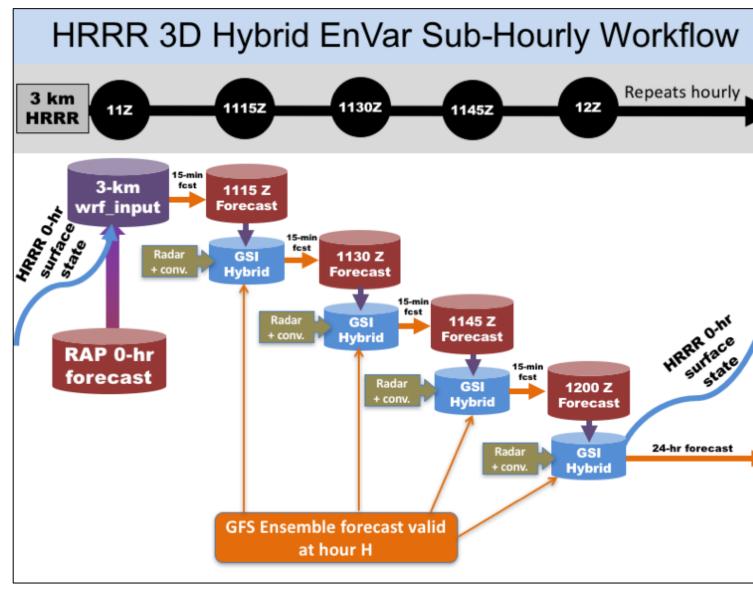
Experimental Design

The goal of this study was to compare analysis and free forecast performance within the 3-km HRRR when using both hourly and sub-hourly 3D and 4D hybrid EnVar data assimilation techniques.

• Configuration:

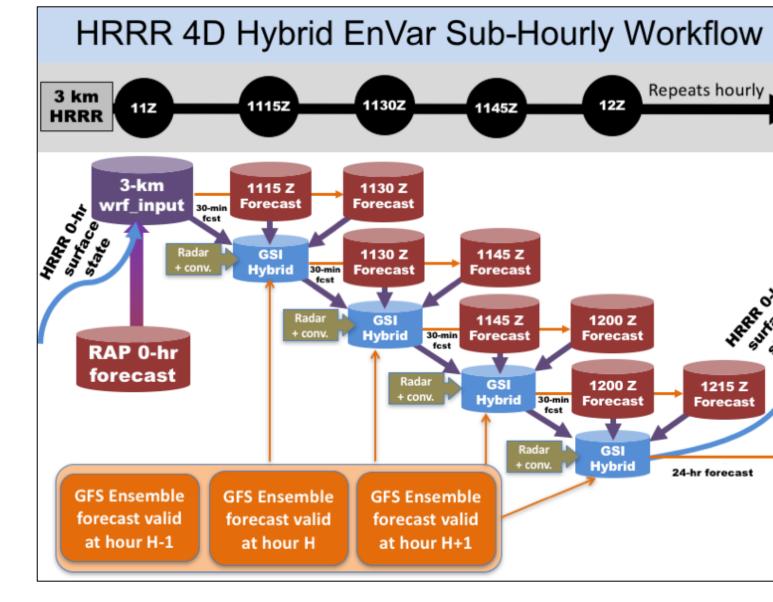
For this research, the operational HRRR set-up was used as an hourly data assimilation benchmark. The sub-hourly experiments were identical in design, except that they contained 15-minute cycling prior to the free forecast.





• Workflows:

Shown above and to the right are the three different workflows for the hourly and sub-hourly 3D and 4D hybrid EnVar experiments. Each simulation begins with a RAP forecast issued at the top of the hour which is downscaled to the 3-km HRRR grid. Afterward, a one-hour pre-forecast is started. For the sub-hourly runs, subsequent DA cycles and forecasts are issued every 15 minutes. The subhourly 3D hybrid EnVar simulations use the same single GFS ensemble forecast as the hourly workflow, while the 4D hybrid EnVar simulations use three GFS ensemble forecasts. After the pre-forecast, a final 24hr simulation is launched at the end of the hour.

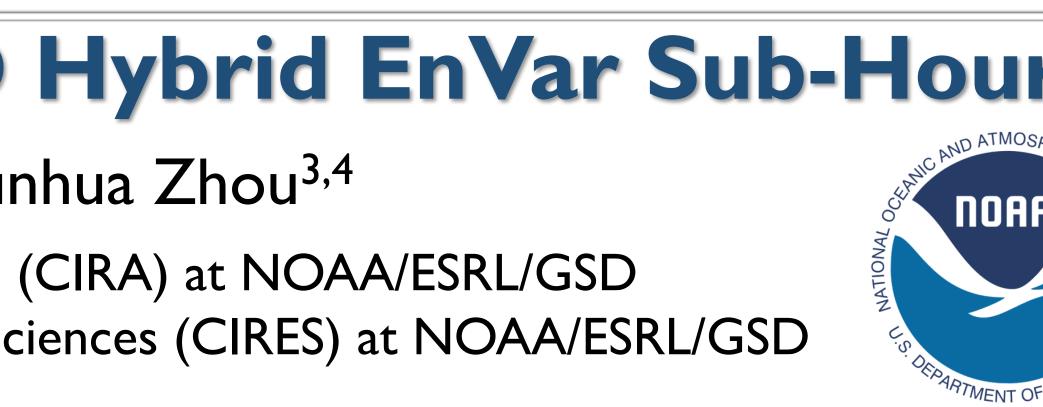


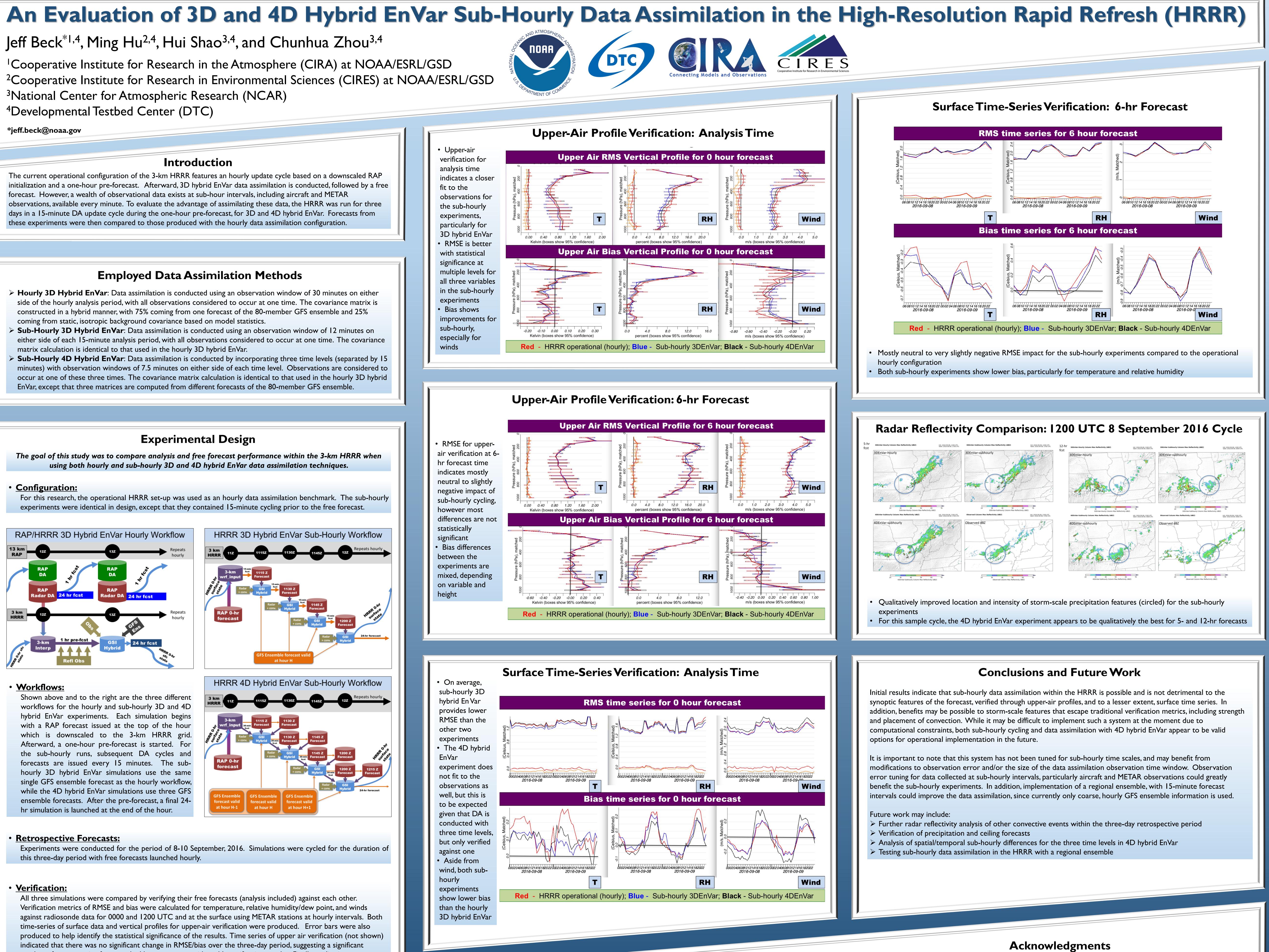
<u>Retrospective Forecasts:</u>

Experiments were conducted for the period of 8-10 September, 2016. Simulations were cycled for the duration of this three-day period with free forecasts launched hourly.

Verification:

All three simulations were compared by verifying their free forecasts (analysis included) against each other. Verification metrics of RMSE and bias were calculated for temperature, relative humidity/dew point, and winds against radiosonde data for 0000 and 1200 UTC and at the surface using METAR stations at hourly intervals. Both time-series of surface data and vertical profiles for upper-air verification were produced. Error bars were also produced to help identify the statistical significance of the results. Time series of upper air verification (not shown) indicated that there was no significant change in RMSE/bias over the three-day period, suggesting a significant number of retrospective forecasts had been run to provide stable verification results. Finally, qualitative comparisons of radar reflectivity were conducted to assess storm-scale feature location and intensity.





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