# Joint WRF/MPAS Users Workshop 2024

### NOAA/GSL Model Prediction Development with MPAS

### Curtis Alexander and many collaborators across GSL, NOAA, UCAR, NSF-NCAR

CLOBAL SYSTEMS LABORATORY

25 June 2024

Forecast systems that deliver solutions

# **Current GSL MPAS Experiments**

### Global

- GSL grand challenge working towards global convection allowing model (CAM) configuration MPAS 7.5 km global mesh, 48 hr forecast from GFS in 2.5 hrs using 20 AWS cloud instances
- Physics testing for atmospheric rivers, precipitation, snow, clouds, radiation, aerosols MPAS 12+ km global mesh, 24 hr forecast from GFS

### **Regional CAM**

- Deterministic baselines to inform future Rapid Refresh Forecast System (RRFS) designs NSSL led MPAS 3km CONUS mesh, 48-60 hr forecasts from HRRR and RRFS
- Resolution sensitivity experiments to inform future Rapid Refresh Forecast System (RRFS) designs MPAS 2-4km CONUS meshes, 36 hr forecasts from HRRR
- Members to inform future Rapid Refresh Forecast System (RRFS) ensemble designs MPAS 3 km CONUS mesh, 48 hr forecasts from HRRR and RDAS/GEFS perturbations
- Physics testing including tropical/hurricane prediction MPAS 3 km CONUS + Atlantic basin mesh, 42 hrs from RAP (HRRRv5), 5 day from GFS

### **Regional Convection Resolving Model (CRM)**

 Extreme precipitation estimation for infrastructure resiliency and fire weather prediction for urban-scale MPAS 1 km sub-CONUS meshes, 24-48 hrs, from HRRR



### GSL Physics development and code management

- Physics updated in GSL fork
  - Thompson mp updated to aerosol-aware
  - GF convection
  - MYNN PBL and sfc
  - RUC LSM
- Thompson mp now updated and in its own repo (<u>TEMPO</u>)
  - Other parameterizations to follow
- Experimental 3-km MPAS-HRRRv5 over CONUS
  - Initialized from RAP
  - Runs 4 times per day: 00, 06, 12 and 18 UTC up to 42-h forecast
  - MPAS 8.1 + NSSL + Updated GSL physics (no GF)

See more details on presentations from

Joe Olson on "Development Strategy for GSL-led to Physical Parameterization for all Model Hosts/Apps" Georg Grell on "Development and applications of the latest GF parameterization in MPAS"



### Recent Challenges in real-time 3-km MPAS-HRRRv5

- 1. Intermittent crashes due to computational instabilities
  - The crash was in mpas\_convective\_diagnostics.F due to high wind speeds
  - *Fixed on 5 June 2024*: config\_number\_of\_sub\_steps = 4 (originally, it was a default =2)
- 2. A problem with albedo information in the static file
  - Fixed on 5 June 2024: re-created static file with config\_supersample\_factor = 3 (=1 before)
- 3. A lag in the SW radiation
  - Swint\_opt available in WRF is not available in MPAS (swint\_opt =1 computes radiation in the middle on the radiation time step).
  - Not fixed, but radiation time step is changed from 30 min to 15 min
- 4. Too opaque clouds
  - Default configuration used poorly specified effective radii.
  - Fixed on 31 May 2024 using effective radii from microphysics scheme (Anders Jensen)
- 5. Daytime moist bias in 2-m dewpoint
  - Improvement from RUC LSM tuning starting 00 UTC, 7 June 2024
  - Tuning in other physics parameterization may be needed



### 2. Albedo





after fix

before fix



NOAA

### 3. A lag in SW radiation





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Incoming Solar Radiation (W/m<sup>2</sup>, shaded)

### 4. Opaque Clouds

### **Original Configuration**

 was not configured to use the effective radii from the microphysics; defaulted to very poorly set values, making clouds too opaque.





# Update to use effective radii from microphysics

- Changed the default value of config\_microp\_re to true
- Currently working on a revision of the macrophysics tailored for MPAS.





### 5. Daytime moist bias in 2-m dewpoint

- Tuning of RUC LSM parameters in MPAS
  - Soil resistance to evaporation from HRRR too small for MPAS, overestimated direct soil evaporation;
  - Irrigation depends on cropland greenness in the updated version of RUC LSM. The climatological greenness fraction in MPAS is higher than real-time VIIRS greenness in RRFS over Western US, as a result *irrigation is triggered too early, adds soil moisture*
- Fixes:

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- Increased soil resistance to evaporation (as in RRFS)
- Irrigation is turned off for now.

Red - MPAS Blue - HRRR Gold - RRFS





0.3 Soil moisture

Plots: courtesy Anders Jensen Powered By **GSL** 

05 June 2024





300

Ih [W m<sup>-2</sup>]

Plots: courtesy Anders Jensen
Powered By GSL

### **GSL** Participation in Experiments and ICs

### • Spring Forecast Experiment (NOAA HWT)

- GSL participated with members running "old physics" (without recent updates)
- A configuration with "new physics" was run for internal scrutiny at GSL (not shared)

### • Flash Flood and Intense Rainfall Experiment (NOAA HMT)

If results look good, we may start piping forecasts to them in late June

### Hurricane Forecast Improvement Experiment (NOAA HFIP)

- If results look good, we will start realtime runs over the Atlantic basin in mid-July
- Two configurations: with and without GF convection
- HWT and HMT configurations initialized from RAP
- HFIP initialized from GFS but soil fields over NA from RAP
  - Uses a procedure called "soil surgery" to initialize RUC LSM





### NOAA NSSL/NWS SPC Spring Forecast Experiment 2024



MPAS resolution sensitivity at 3 and 4 km meshes

# Forecasting composite reflectivity against MRMS observations



### NOAA NSSL/NWS SPC Spring Forecast Experiment 2024



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# GSL Data assimilation development and code management RDASApp https://github.com/NOAA-EMC/RDASApp

- RDASApp is to replace GSI. It contains all required JEDI components to build, test and run RRFSv2 data assimilation experiments.
- It greatly facilitates the collaboration and discussions between GSL and EMC with issue tracking, PR reviewing and Wiki Documentation
- GSL has participated over 45 issues, 42 PRs so far; contributed to the developing, testing, evaluation, documentation, portability of RDASApp and establishing/maintaining FV3-JEDI, MPAS-JEDI test cases
- We meet bi-weekly and established a preliminary code management and regression test policy





### GSL MPAS-JEDI development sandbox



MPAS CONUS 12KM domain + 30 ensembles for preliminary tests Comparable RAP/HRRR-like domain, to be used by GSI baseline tests







#### Single sonde obs MPAS-JEDI 3DEnVAR experiment with 401km horizontal JEDI radius and 11 vertical levels radius



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### GSL MPAS-JEDI development for surface observations



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METAR OBS MPAS-JEDI DA

O-B sanity check

Larger O-B near the coastlines

GSI has special treatment for observation near coastlines

Work is underway to bring this function to MPAS-JEDI



### **GSL MPAS-JEDI observation processing**



### GSL MPAS-JEDI model background error

# $\mathbf{B} = \mathbf{K}_1 \mathbf{K}_2 \mathbf{\Sigma} \mathbf{C} \mathbf{\Sigma}^\mathsf{T} \mathbf{K}_2^\mathsf{T} \mathbf{K}_1^\mathsf{T}$

Tests completed using pure 3DEnVAR

Work to generate a reasonable regional static BE

Meetings with the NCAR MPAS-JEDI team including BJ

Global test case provided to adapt procedure to generate a suitable static BE for regional MPAS-JEDI cases



Static BE





- Approach is similar to CAM-SIMA, i.e., add a new dycore to UFS
  - As opposed to running MPAS-A as part of NCEP production suite
- Reason: Having a single modeling system (UFS) simplified the work by NOAA and the community to use, maintain, and develop the system
- Please see poster by Bernardet et al. on "Expanding the UFS to Include the MPAS Dynamical Core"



### Generalizing UFS Atmospheric Component (FV3ATM)

- This is a prerequisite for connections to CCPP and external components
- The atmospheric component of the UFS WM is **FV3ATM**
- FV3ATM is a coupling interface between dynamics, physics, atmospheric I/O, and external components
- Parts of FV3ATM tie directly to FV3 dycore
- Needs abstraction and generalization (FV3ATM -> UFSATM)
- Opportunity to clean up and restructure
  - Enhance maintainability of FV3
  - Facilitate introduction of a new dycore, such as MPAS



### Code Management

- MPAS will be a submodule under UFS Weather Model (UWM)
- Code will point directly to the <u>MPAS official repository</u> (NCAR MMM)
- MPAS UWM interface will stay under UWM atmosphere repository
- This is similar to how the MPAS dycore is used in CESM/CAM
- Needs new tests (e.g., regression tests)



### **Pre-Processing**

- There are existing tools to ingest GRIB2 and drive MPAS
- Similarly, there are existing tools to interpolate static datasets to MPAS grid
- These may need to be connected to ufs\_utils
- Not much development needed on this front (at first)

### **Data Assimilation**

- JEDI DA algorithms and obs operators are model-agnostic
  - Allow for swapping the model interface
- JEDI uses grids provided by model interfaces
  - Native grid DA for both FV3 and MPAS can be used
- Ongoing MPAS-JEDI experiments by MMM and JCSDA
- Can leverage JEDI-UFS work and MPAS-JEDI work at JCSDA (w/ in-kinds)





### **Stochastic Physics**

### • SKEB, SHUM, SPP, SPPT

- Should work since they are model agnostic
- Some code changes (due to being hardcoded to GFS DDTs)
- DTC is working on implementing stochastic physics (via the UFS repository) into MPAS stand-alone (specifically the ad-hoc schemes, SHUM, SKEB, and SPPT)
- DTC has funds to start interfacing CCPP with MPAS, which will allow us to run SPP in the future

### Cellular Automata

- Will need to be reworked for use in an unstructured grid
- Not critical for Short-Range applications





# MPAS in UFS Inter-Component Coupling: UFSATM NUOPC Cap

- Drive MPAS dycore through the existing UFSATM NUOPC Cap
  - A NUOPC Cap is a model wrapper with well-defined entry points and model state that is used to create standardized interoperability of models and mediators
- Connections between MPAS and the UFSATM NUOPC Cap
  - MPAS dycore initialization, run (a.k.a. advance), and finalize phases
  - MPAS dycore geometries and domain decomposition (parallelization)
  - MPAS dycore field/data memory for inter-component coupling of import and export states

Some of this functionality already exists in CESM/CAM and can be leveraged





### Input/Output - Two Possible Approaches

Note: MPAS outputs files on its native unstructured mesh

- Approach 1: Use MPAS I/O
  - Sufficient for initial testing
  - MPAS outputs in native grid
  - Use *convert\_mpas* utility to interpolate from native mesh to lat-lon

### • Approach 2: Develop asynchronous IO (write grid component) capability

- Needed to increase performance for operations
- Set up output field bundles in the MPAS dycore driver code
- Set up the write grid component in UFSATM cap
- Output history (diagnostic) files on native mesh and other grids





### Post Processing - Three Steps

- Run offline UPP from MPAS history files
  - MPAS outputs history files in native mesh
  - convert\_mpas converts history files to lat-lon grid
  - UPP generates products from history files
  - MPASSIT + UPP set up by NSSL used older locally customized version of UPP (called "UPP\_NSSL")
  - GSL tests indicate that the authoritative UPP code can ingest MPASSIT-generated files
- MPAS directly outputs all the Post Processing products
  - Integrate UPP code into MPAS to output in native mesh
  - Use *convert\_mpas* to convert to lat-lon grid
- Run inline UPP in write grid component
  - Develop write grid component to encompass all grids needed for output
  - Call UPP on the write grid component





### Workflow

- Need to add new tasks to the workflow
  - Similar to WRF's geogrid, ungrib, metgrid
- This will be more efficient if done in one place
  - Doing it in Unified, SRW App, RRFS, HAFS, etc. adds cost
- Creating generalized workflow is more complex than customizing workflow
- Proposed approach is to start from a regional workflow, create a branch for MPAS, and manage the deltas
- Upcoming GSL runs will use the MPAS App that invokes Unified Workflow Tools (uwtools)
- Please see Derrico et al. poster, "An MPAS App with Unified Workflow Tools"



### Resource Estimate - 13.1 FTE

Task	FTE years	Notes
Code Mgmt and Governance	0.5	Ongoing
Generalizing ATM FV3ATM $\rightarrow$ UFSATM	1.0	
Build system and software stack	0.6	
Pre-processing and data assimilation	Store L.	Dependent on generalized UFSATM
Post-processing/IO	4	Dependent on generalized UFSATM
NUOPC Cap (inter-component coupling)	1	Dependent on generalized UFSATM
Complete connection to CCPP (physics dynamics coupling)	2	Dependent on generalized UFSATM
Workflow	4	



# **GSL** Summary

Broad engagement in MPAS development Global and regional applications Hydrostatic through CAM to convection resolving scales Physics testing and development across forecast applications MPAS-JEDI data assimilation development including ensemble use Infrastructure work with UFS including physics-dynamics coupling, workflow, post, etc... Wide variety of MPAS mesh generation interests Global and limited area meshes Hydrostatic to sub-km scales Variable resolution and discontinuous grids

GSL is committed to development and testing of MPAS for use in future UFS-based Rapid Refresh Forecast System (RRFS). For information on the status, update and plans for the RRFS along with related discussions on MPAS, please consider attending the UFS/EPIC workshop on 22-26 July 2024:

https://epic.noaa.gov/eventsposts/uifcw-2024/



