Hybrid Variational/Ensemble Data Assimilation

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Outline

- Background
- Hybrid formulation in a variational framework
- Some results
- Introduction to hybrid practice

Motivation of Hybrid DA

- 3D-Var uses static ("climate") BE

$$J(\delta x) = \frac{1}{2}\delta x^{\mathrm{T}}\mathrm{B}^{-1}\delta x + \frac{1}{2}[\mathrm{H}\delta x - d]^{\mathrm{T}}\mathrm{R}^{-1}[\mathrm{H}\delta x - d]$$

- 4D-Var implicitly uses flow-dependent information, but still starts from static BE

$$J(\delta x) = \frac{1}{2}\delta x^{\mathrm{T}}\mathrm{B}^{-1}\delta x + \frac{1}{2}\sum_{i=1}^{I}[\mathrm{HM}_i\delta x - d_i]^{\mathrm{T}}\mathrm{R}^{-1}[\mathrm{HM}_i\delta x - d_i]$$

- Hybrid uses flow-dependent background error covariance from forecast ensemble perturbation in a variational DA system

What is the Hybrid DA?

- Ensemble mean is analyzed by a variational algorithm (i.e., minimize a cost function).
  - It combines (so "hybrid") the 3DVAR "climate" background error covariance and "error of the day" from ensemble perturbation.

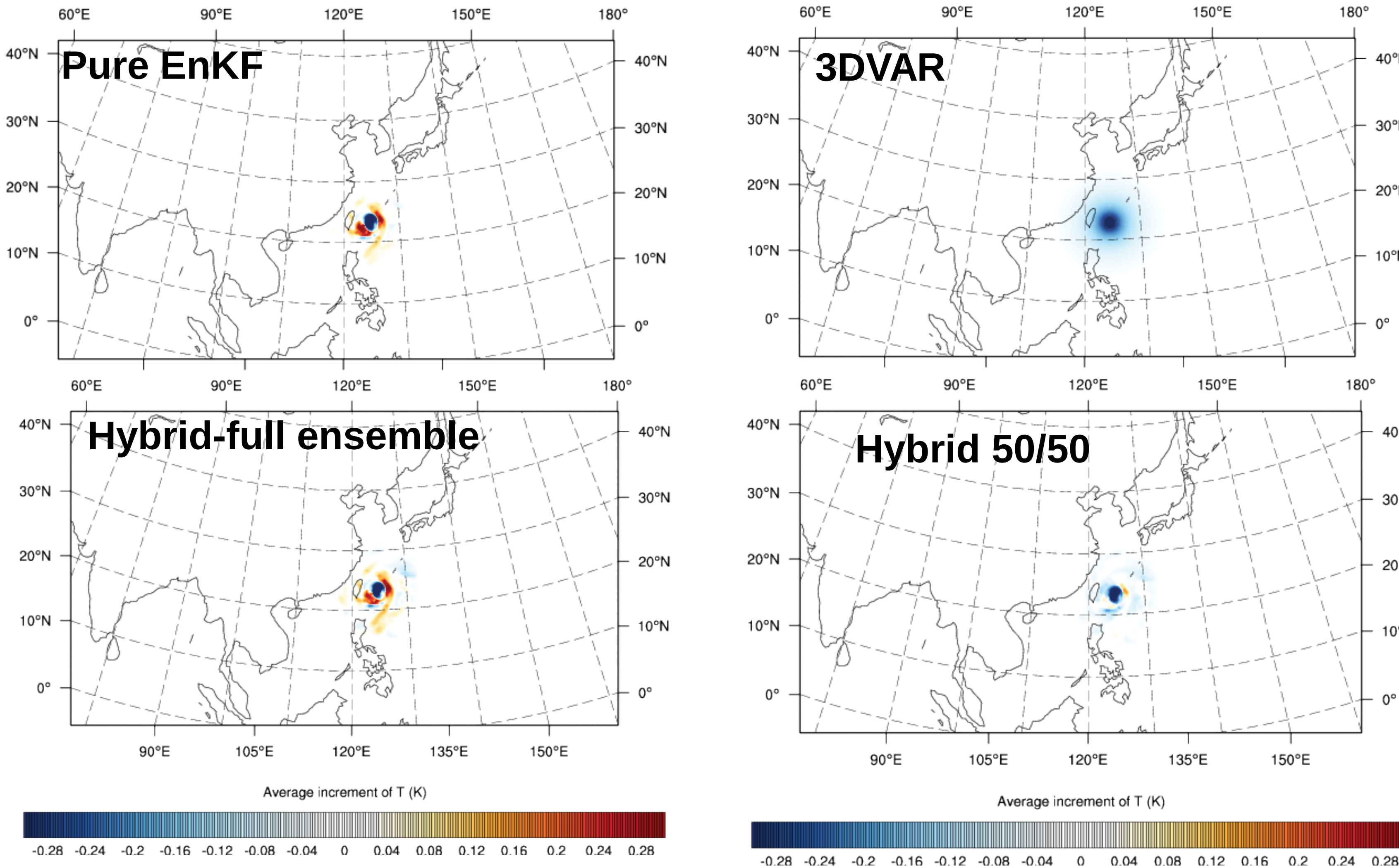
- Hybrid algorithm (again in a variational framework) itself usually does not generate ensemble analyses.

- Need a separate system to update ensemble
  - Could be ensemble forecasts already available from NWP centers
  - Could be an Ensemble Kalman Filter-based DA system
  - Or multiple model/physics ensemble

- Ensemble needs to be good to well represent "error of the day"

single observation tests

Potential temperature increment, 21st model level



Hybrid formulation (1)
(Hamill and Snyder, 2000)

- 3DVAR cost function

$$J(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}_b)^{\mathrm{T}} \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \frac{1}{2}[H(\mathbf{x}) - \mathbf{y}]^{\mathrm{T}} \mathbf{R}^{-1} [H(\mathbf{x}) - \mathbf{y}]$$

- Idea: replace **B** by a weighted sum of static $\mathbf{B}_s$ and the ensemble $\mathbf{B}_e$

$$\mathbf{B} = a_s \mathbf{B}_s + a_e \mathbf{B}_e, \ a_s = 1 - a_e$$

  - Has been demonstrated on a simple model.
  - Difficult to implement for large NWP model.

Hybrid formulation (2): used in WRFDA
(Lorenc, 2003)

• Ensemble covariance is included in the 3DVAR cost function through augmentation of control variables

$$J(\mathbf{x},\alpha) = \beta_s \frac{1}{2}(\mathbf{x}-\mathbf{x}_b)^{\mathrm{T}}\mathbf{B}^{-1}(\mathbf{x}-\mathbf{x}_b) + \overbrace{\beta_e \frac{1}{2}\sum_{i=1}^{\mathrm{N}} \alpha_i^{\mathrm{T}}\mathbf{C}^{-1}\alpha_i}^{\text{ensemble control variable } \alpha_i \ (M \times 1)}$$

$$+\frac{1}{2}[\mathbf{y}-H(\mathbf{x}+\mathbf{x}_e^{'})]^{\mathrm{T}}\mathbf{R}^{-1}[\mathbf{y}-H(\mathbf{x}+\mathbf{x}_e^{'})]$$

$\mathbf{x}_e^{'} = \sum_{\mathrm{i}=1}^{\mathrm{N}} \alpha_i \circ \mathbf{x}_i^{'}$, where $\mathbf{x}_i^{'}$ is the ensemble perturbation for the ensemble member i.

$\circ$ denote element - wise product. α_{i} is in effect the ensemble weight.

$\mathbf{C}$: correlation matrix (effectively loclization of ensemble perturbations)

• In practical implementation, α_i can be reduced to horizontal 2D fields (i.e., use same weight in different vertical levels) to save computing cost.

• β_s and β_e ($1/\beta_s + 1/\beta_e = 1$) can be tuned to have different weight between static and ensemble part.

Hybrid formulation (3)

- Equivalently can write in another form (Wang et al., 2008)

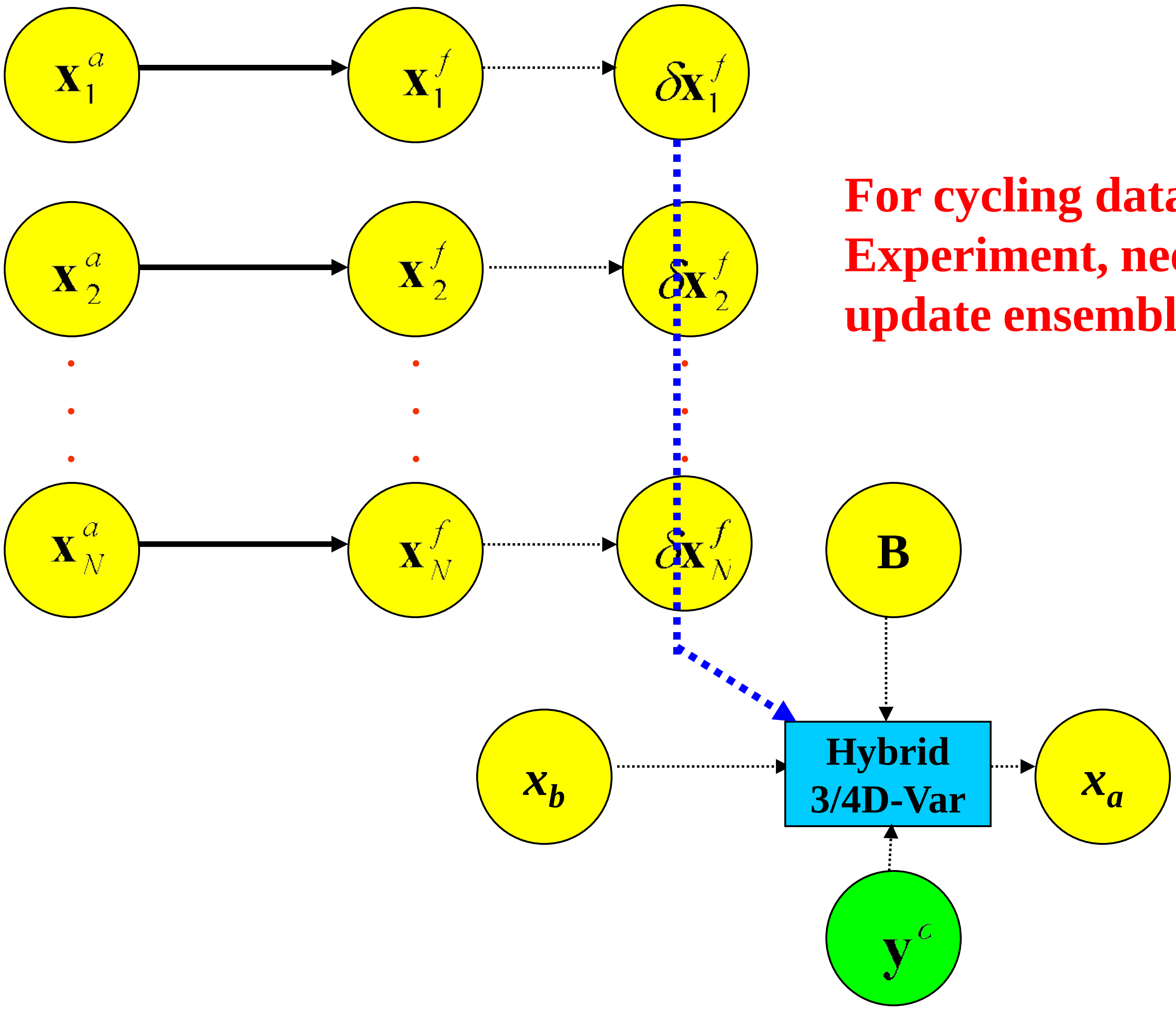
$$J(\mathbf{x},\alpha) = \frac{1}{2}(\mathbf{x} + \mathbf{x}_e - \mathbf{x}_b)^{\mathrm{T}} \left(\frac{1}{\beta_s}\mathbf{B} + \frac{1}{\beta_e}\mathbf{B}_e \circ \mathbf{C}\right)^{-1}(\mathbf{x} + \mathbf{x}_e - \mathbf{x}_b)$$

$$+ \frac{1}{2}[\mathbf{y} - H(\mathbf{x} + \mathbf{x}_e)]^{\mathrm{T}} \mathbf{R}^{-1}[\mathbf{y} - H(\mathbf{x} + \mathbf{x}_e)]$$

- **C** is “localization” matrix

Hybrid DA data flow

Ensemble Perturbations (extra input for hybrid)



For cycling data assimilation/forecast Experiment, need a mechanism to update ensemble.

EnKF-based Ensemble Generation

- EnKF with perturbed observations

- EnKF without perturbed observations
  - All based on square-root filter
  - Ensemble Transformed Kalman Filter (ETKF)
  - Ensemble Adjustment Kalman Filter (EAKF)
  - Ensemble Square-Root Filter (EnSRF)

- Most implementation assimilates obs sequentially (i.e., one by one, or box by box)
  - can be parallelized

More information was given in 2012 slides.

Advantages of the Hybrid DA

- Hybrid localization is in model space while EnKF localization is usually in observation space.

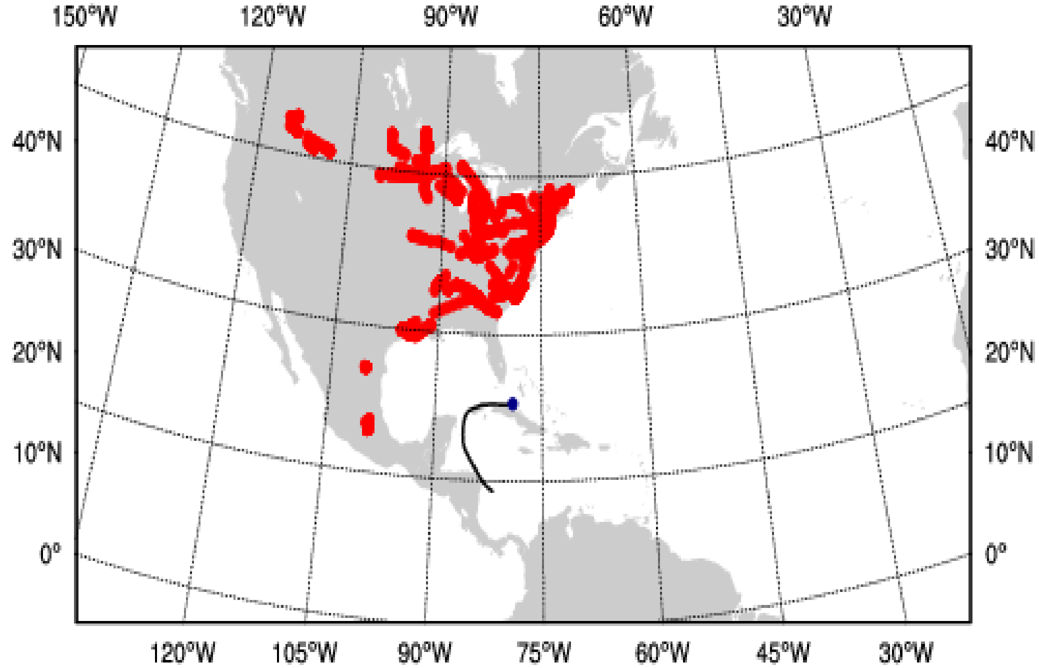
- For some observation types, e.g., radiances, localization is not well defined in observation space

- Easier to make use of existing radiance VarBC in hybrid

- For small-size ensemble, use of static B could be beneficial to have a higher-rank covariance.

a Hurricane Case Study (Dongmei Xu)

- Paula case: 0600 UTC 10 October 2010 to 1200 UTC 15 October 2010;
- Background: 15km interpolated from GFS data;
- Resolution: 718x 373 (15km) and 43 levels;
- Observations: GTS and TAMDAR;
- Cycle frequency: 6 hours;
- Background error:CV5;
- Time widows: 2 hours;



- TAMDAR: a new Tropospheric Airborne Meteorological Data Reporting (TAMDAR) observing system that has been developed by AirDat company.

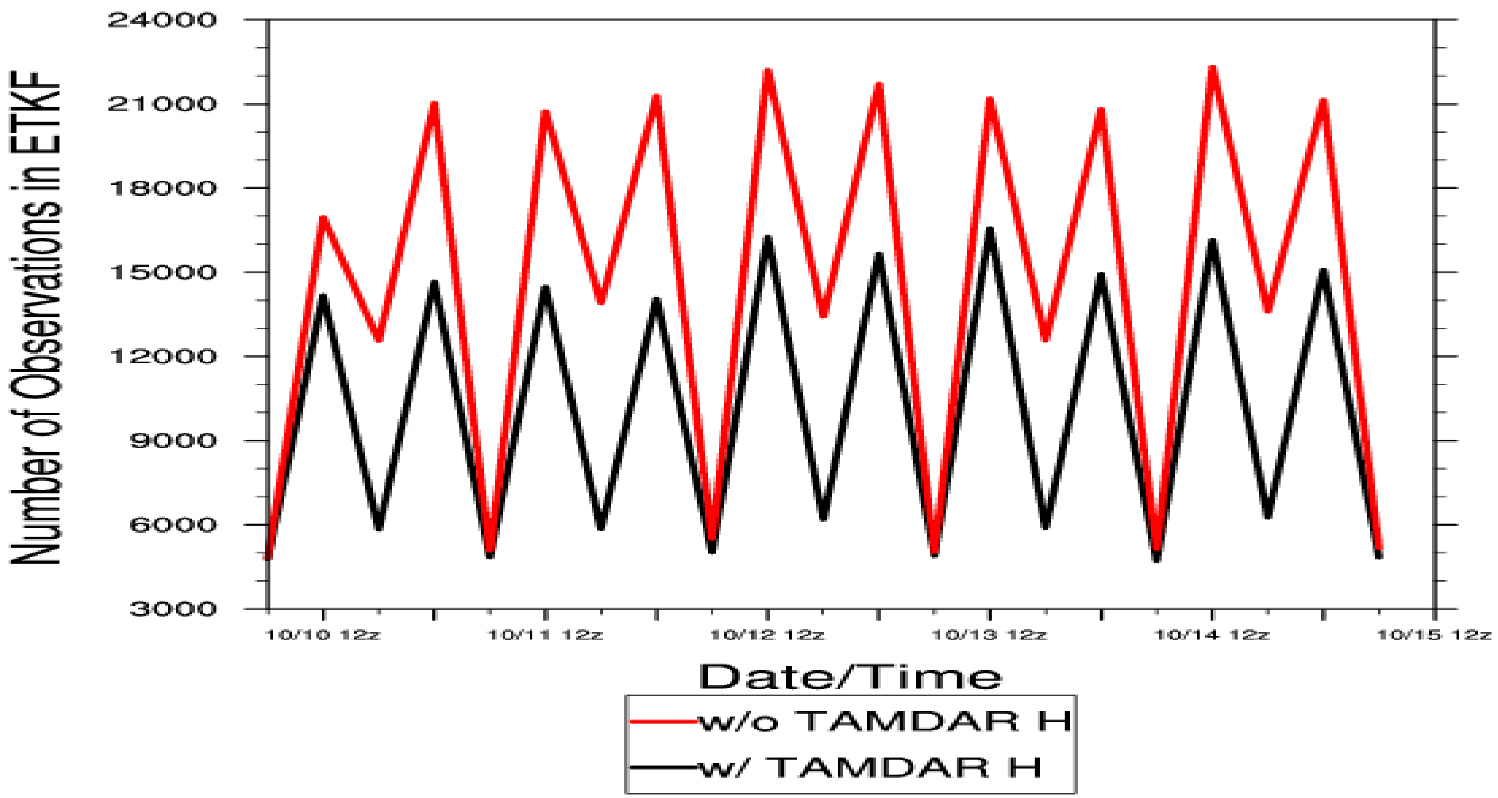
Experimental design

Experiments:

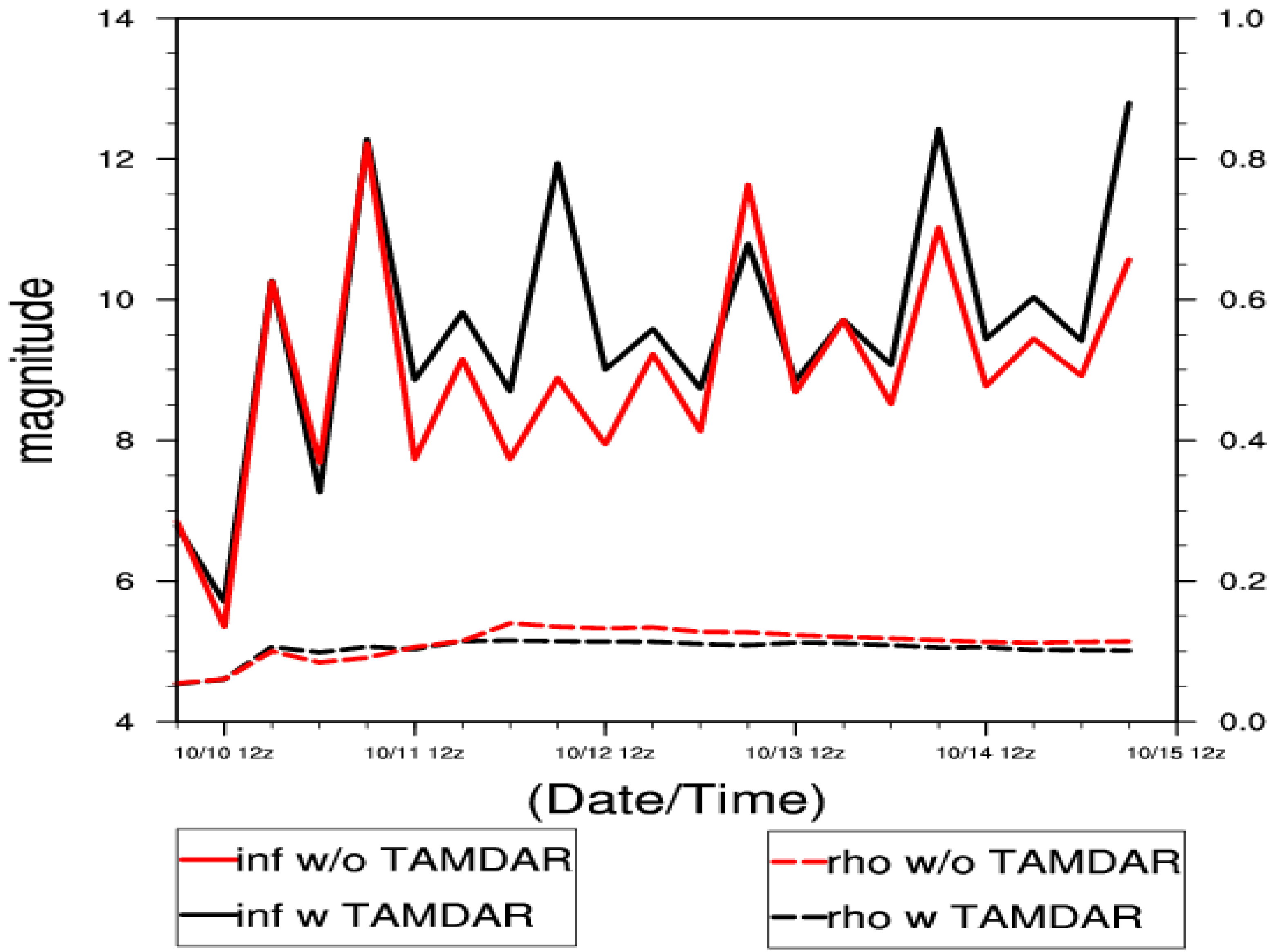
CYC1:assimilate GTS and TAMDAR with Hybrid (w/ TAMDAR H);

CYC2:same to CYC1,but no TAMDAR (w/o TAMDAR H)

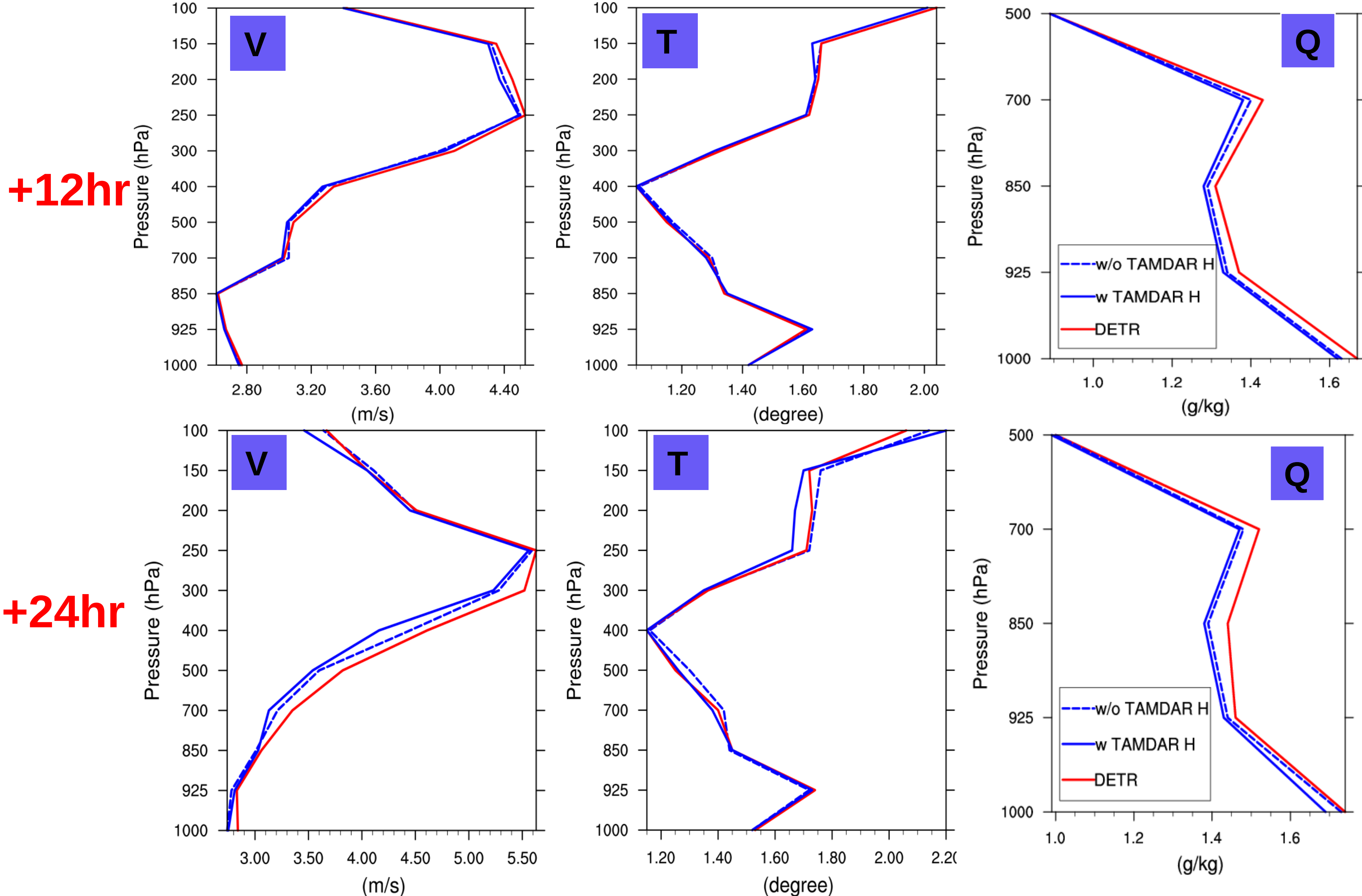
CYC3:assimilate GTS and TAMDAR with standard 3DVAR (Deterministic WRFDA)



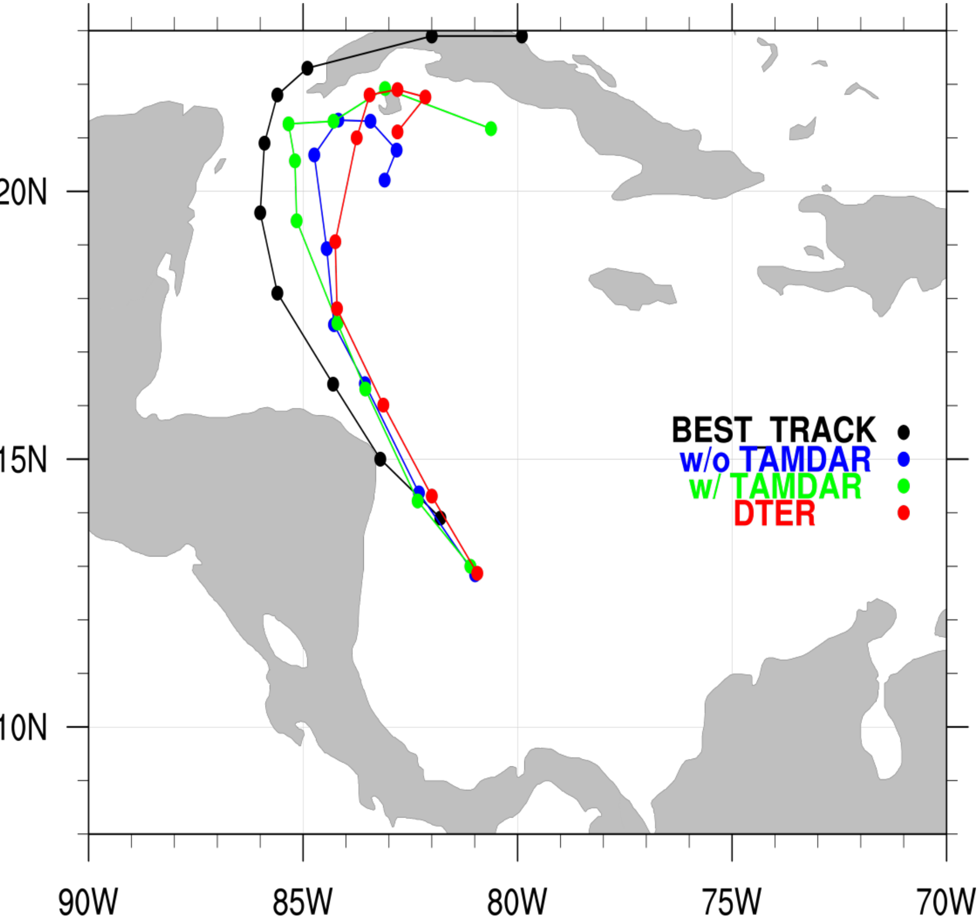
inflation and fraction factor

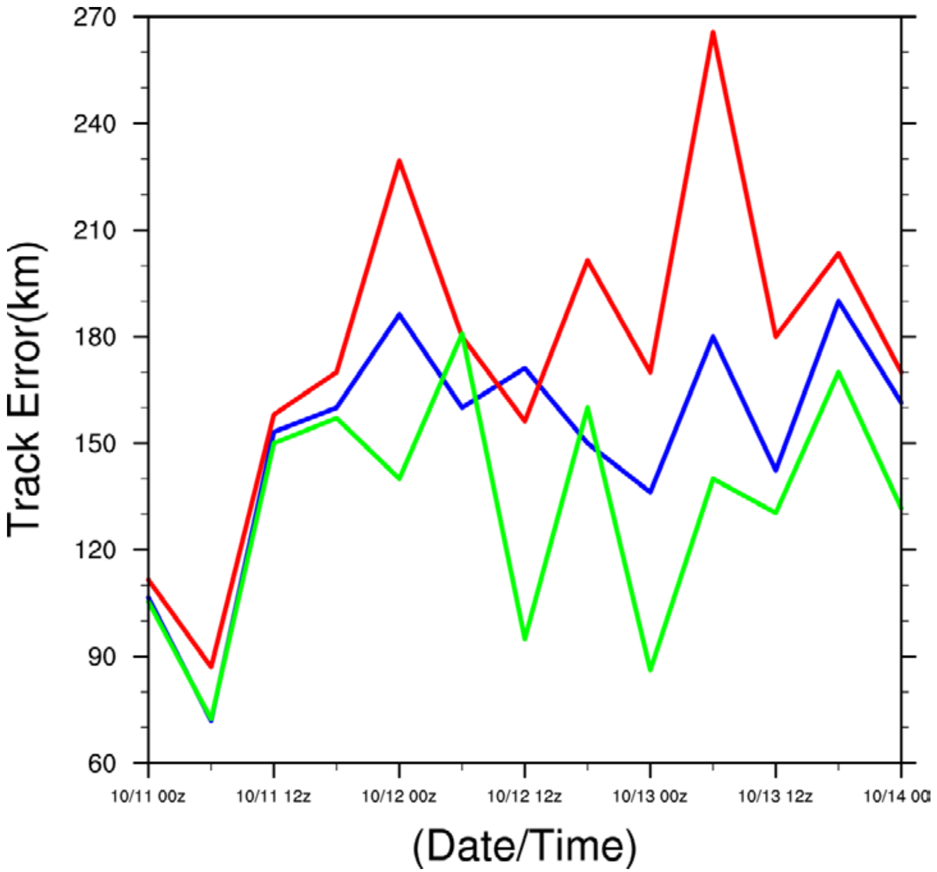


Forecast Verification: RMSE



Track Forecast Verification (+24hr)





Hybrid practice

- **Computation steps:**
  - Computing ensemble mean (**gen_be_ensmean.exe**).
  - Extracting ensemble perturbations (**gen_be_ep2.exe**).
  - Running WRFDA in "hybrid" mode (**da_wrfvar.exe**).
  - Displaying results for: ens_mean, std_dev, ensemble perturbations, hybrid increments, cost function
  - If time permits, play with different namelist settings: "je_factor" and "alpha_corr_scale".
- **Scripts to use:**
  - Some NCL scripts to display results.

- **Ensemble generation part not included in current practice**

Namelist for WRFDA in hybrid mode

&wrfvar7
je_factor=2,   # half/half for Jb and Je term

&wrfvar16
alphacv_method=2,   # ensemble part is in model space (u,v,t,q,ps)

ensdim_alpha=10,

alpha_corr_type=3, # 1=Exponential; 2=SOAR; 3=Gaussian

alpha_corr_scale=750., # correlation scale in km

alpha_std_dev=1.,

alpha_vertloc=true, (use program "**gen_be_vertloc.exe 42**" **to generate file**)

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